# X10 Language Specification <br> Version 2.2 

## DRAFT — January 31, 2012

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January 31, 2012


#### Abstract

This report provides a description of the programming language X10. X10 is a class-based object-oriented programming language designed for high-performance, high-productivity computing on high-end computers supporting $\approx 10^{5}$ hardware threads and $\approx 10^{15}$ operations per second.


X 10 is based on state-of-the-art object-oriented programming languages and deviates from them only as necessary to support its design goals. The language is intended to have a simple and clear semantics and be readily accessible to mainstream OO programmers. It is intended to support a wide variety of concurrent programming idioms.
The X10 design team consists of Bard Bloom, David Cunningham, Robert Fuhrer, David Grove, Sreedhar Kodali, Nathaniel Nystrom, Igor Peshansky, Vijay Saraswat, Mikio Takeuchi, Olivier Tardieu, Yoav Zibin.

This version of the language was implemented by a team that includes the designers and Bowen Alpern, Philippe Charles, Ben Herta, Yan Li, Yuki Makino, Toshio Suganuma, Hai Chuan Wang.
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For extended discussions and support we would like to thank: Gheorghe Almasi, Robert Blackmore, Rob O’Callahan, Calin Cascaval, Norman Cohen, Elmootaz Elnozahy, John Field, Kevin Gildea, Chulho Kim, Orren Krieger, Doug Lea, John McCalpin, Paul McKenney, Andrew Myers, Filip Pizlo, Ram Rajamony, R. K. Shyamasundar, V. T. Rajan, Frank Tip, Mandana Vaziri, and Hanhong Xue.
We thank Jonathan Rhees and William Clinger with help in obtaining the ETEX style file and macros used in producing the Scheme report, on which this document is based. We acknowledge the influence of the Java ${ }^{\mathrm{TM}}$ Language Specification [5], the Scala language specification [8], and ZPL [4].
This document specifies the language corresponding to Version 2.1 of the implementation. Version 1.7 of the report was co-authored by Nathaniel Nystrom. The design of structs in X10 was led by Olivier Tardieu and Nathaniel Nystrom.
Earlier implementations benefited from significant contributions by Raj Barik, Philippe Charles, David Cunningham, Christopher Donawa, Robert Fuhrer, Christian Grothoff, Nathaniel Nystrom, Igor Peshansky, Vijay Saraswat, Vivek Sarkar, Olivier Tardieu, Pradeep Varma, Krishna Nandivada Venkata, and Christoph von Praun. Tong Wen has written many application programs in X10. Guojing Cong has helped in the development of many applications. The implementation of generics in X10 was influenced by the implementation of PolyJ [2] by Andrew Myers and Michael Clarkson.

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## 1 Introduction

## Background

The era of the mighty single-processor computer is over. Now, when more computing power is needed, one does not buy a faster uniprocessor-one buys another processor just like those one already has, or another hundred, or another million, and connects them with a high-speed communication network. Or, perhaps, one rents them instead, with a cloud computer. This gives one whatever quantity of computer cycles that one can desire and afford.

Then, one has the problem of how to use those computer cycles effectively. Programming a multiprocessor is far more agonizing than programming a uniprocessor. One can use models of computation which give somewhat of the illusion of programming a uniprocessor. Unfortunately, the models which give the closest imitations of uniprocessing are very expensive to implement, either increasing the monetary cost of the computer tremendously, or slowing it down dreadfully.
One response to this problem has been to move to a fragmented memory model. Multiple processors are programmed largely as if they were uniprocessors, but are made to interact via a relatively language-neutral message-passing format such as MPI [9]. This model has enjoyed some success: several high-performance applications have been written in this style. Unfortunately, this model leads to a loss of programmer productivity: the message-passing format is integrated into the host language by means of an application-programming interface (API), the programmer must explicitly represent and manage the interaction between multiple processes and choreograph their data exchange; large data-structures (such as distributed arrays, graphs, hash-tables) that are conceptually unitary must be thought of as fragmented across different nodes; all processors must generally execute the same code (in an SPMD fashion) etc.

One response to this problem has been the advent of the partitioned global address
space (PGAS) model underlying languages such as UPC, Titanium and Co-Array Fortran [3, 10]. These languages permit the programmer to think of a single computation running across multiple processors, sharing a common address space. All data resides at some processor, which is said to have affinity to the data. Each processor may operate directly on the data it contains but must use some indirect mechanism to access or update data at other processors. Some kind of global barriers are used to ensure that processors remain roughly synchronized.
X10 is a modern object-oriented programming language in the PGAS family. The fundamental goal of X10 is to enable scalable, high-performance, high-productivity transformational programming for high-end computers-for traditional numerical computation workloads (such as weather simulation, molecular dynamics, particle transport problems etc) as well as commercial server workloads.

X10 is based on state-of-the-art object-oriented programming ideas primarily to take advantage of their proven flexibility and ease-of-use for a wide spectrum of programming problems. X10 takes advantage of several years of research (e.g., in the context of the Java Grande forum, [7, 1]) on how to adapt such languages to the context of high-performance numerical computing. Thus X10 provides support for user-defined struct types (such as Int, Float, Complex etc), supports a very flexible form of multi-dimensional arrays (based on ideas in ZPL [4]) and supports IEEE-standard floating point arithmetic. Some capabilities for supporting operator overloading are also provided.
X10 introduces a flexible treatment of concurrency, distribution and locality, within an integrated type system. X10 extends the PGAS model with asynchrony (yielding the $A P G A S$ programming model). X10 introduces places as an abstraction for a computational context with a locally synchronous view of shared memory. An X10 computation runs over a large collection of places. Each place hosts some data and runs one or more activities. Activities are extremely lightweight threads of execution. An activity may synchronously (and atomically) use one or more memory locations in the place in which it resides, leveraging current symmetric multiprocessor (SMP) technology. An activity may shift to another place to execute a statement block. X10 provides weaker ordering guarantees for inter-place data access, enabling applications to scale. Multiple memory locations in multiple places cannot be accessed atomically. Immutable data needs no consistency management and may be freely copied by the implementation between places. One or more clocks may be used to order activities running in multiple places. DistArrays, distributed arrays, may be distributed across multiple places and support parallel collective operations. A novel exception flow model ensures that
exceptions thrown by asynchronous activities can be caught at a suitable parent activity. The type system tracks which memory accesses are local. The programmer may introduce place casts which verify the access is local at run time. Linking with native code is supported.

## 2 Overview of X10

X10 is a statically typed object-oriented language, extending a sequential core language with places, activities, clocks, (distributed, multi-dimensional) arrays and struct types. All these changes are motivated by the desire to use the new language for high-end, high-performance, high-productivity computing.

### 2.1 Object-oriented features

The sequential core of X10 is a container-based object-oriented language similar to Java and C++, and more recent languages such as Scala. Programmers write X10 code by defining containers for data and behavior called classes ( $\S 8$ ) and structs ( $\$ 9$ ), often abstracted as interfaces ( $\$ 7$ ). X10 provides inheritance and subtyping in fairly traditional ways.

## Example:

Normed describes entities with a norm() method. Normed is intended to be used for entities with a position in some coordinate system, and norm() gives the distance between the entity and the origin. A Slider is an object which can be moved around on a line; a PlanePoint is a fixed position in a plane. Both Sliders and PlanePoints have a sensible norm() method, and implement Normed.

```
interface Normed {
    def norm():Double;
}
class Slider implements Normed {
    var x : Double = 0;
    public def norm() = Math.abs(x);
    public def move(dx:Double) { x += dx; }
```

```
}
struct PlanePoint implements Normed {
    val x : Double; val y:Double;
    public def this(x:Double, y:Double) {
        this.x = x; this.y = y;
    }
    public def norm() = Math.sqrt(x*x+y*y);
}
```

Interfaces An X10 interface specifies a collection of abstract methods; Normed specifies just norm(). Classes and structs can be specified to implement interfaces, as Slider and PlanePoint implement Normed, and, when they do so, must provide all the methods that the interface demands.
Interfaces are purely abstract. Every value of type Normed must be an instance of some class like Slider or some struct like PlanePoint which implements Normed; no value can be Normed and nothing else.

Classes and Structs There are two kinds of containers: classes ( $\S 8$ ) and structs (89). Containers hold data in fields, and give concrete implementations of methods, as Slider and PlainPoint above.

Classes are organized in a single-inheritance tree: a class may have only a single parent class, though it may implement many interfaces and have many subclasses. Classes may have mutable fields, as Slider does.

In contrast, structs are headerless values, lacking the internal organs which give objects their intricate behavior. This makes them less powerful than objects (e.g., structs cannot inherit methods, though objects can), but also cheaper (e.g., they can be inlined, and they require less space than objects). Structs are immutable, though their fields may be immutably set to objects which are themselves mutable. They behave like objects in all ways consistent with these limitations; e.g., while they cannot inherit methods, they can have them - as PlanePoint does.

X10 has no primitive classes per se. However, the standard library x10.lang supplies structs and objects Boolean, Byte, Short, Char, Int, Long, Float, Double, Complex and String. The user may defined additional arithmetic structs using the facilities of the language.

Functions. X10 provides functions ( $\$ 10$ ) to allow code to be used as values. Functions are first-class data: they can be stored in lists, passed between activities, and so on. square, below, is a function which squares an Int. of4 takes an Int-to-Int function and applies it to the number 4. So, fourSquared computes of4 (square), which is square(4), which is 16 , in a fairly complicated way.

```
val square = (i:Int) => i*i;
val of4 = (f: (Int)=>Int) => f(4);
val fourSquared = of4(square);
```

Functions are used extensively in X10 programs. For example, a common way to construct and initialize an Array [Int] (1) - that is, a fixed-length one-dimensional array of numbers, like an int [] in Java - is to pass two arguments to a factory method: the first argument being the length of the array, and the second being a function which computes the initial value of the $i^{\text {th }}$ element. The following code constructs a 1 -dimensional array initialized to the squares of $0,1, \ldots, 9: r(0)==0$, $r(5)==25$, etc.

```
val r : Array[Int](1) = new Array[Int](10, square);
```

Constrained Types X10 containers may declare properties, which are fields bound immutably at the creation of the container. The static analysis system understands properties, and can work with them logically.

For example, an implementation of matrices Mat might have the numbers of rows and columns as properties. A little bit of care in definitions allows the definition of a + operation that works on matrices of the same shape, and * that works on matrices with appropriately matching shapes.

```
abstract class Mat(rows:Int, cols:Int) {
    static type Mat(r:Int, c:Int) = Mat{rows==r&&cols==c};
    abstract operator this + (y:Mat(this.rows,this.cols))
    :Mat(this.rows, this.cols);
abstract operator this * (y:Mat) {this.cols == y.rows}
    :Mat(this.rows, y.cols);
```

The following code typechecks (assuming that makeMat ( $m, n$ ) is a function which creates an $m \times n$ matrix). However, an attempt to compute axb1 + bxc or bxc * axb1 would result in a compile-time type error:

```
static def example(a:Int, b:Int, c:Int) {
    val axb1 : Mat(a,b) = makeMat(a,b);
    val axb2 : Mat(a,b) = makeMat(a,b);
    val bxc : Mat(b,c) = makeMat(b,c);
    val axc : Mat(a,c) = (axb1 +axb2) * bxc;
    //ERROR: val wrong1 = axb1 + bxc;
    //ERROR: val wrong2 = bxc * axb1;
}
```

The "little bit of care" shows off many of the features of constrained types. The (rows:Int, cols:Int) in the class definition declares two properties, rows and cols ${ }^{1}$

A constrained type looks like Mat $\{r o w s==r$ \& cols==c\}: a type name, followed by a Boolean expression in braces. The type declaration on the second line makes Mat ( $\mathrm{r}, \mathrm{c}$ ) be a synonym for Mat $\{\mathrm{rows==r}$ \& $\& \mathrm{cols==} \mathrm{c}\}$, allowing for compact types in many places.

Functions can return constrained types. The makeMat ( $\mathrm{r}, \mathrm{c}$ ) method returns a Mat $(r, c)$ - a matrix whose shape is given by the arguments to the method. In particular, constructors can have constrained return types to provide specific information about the constructed values.

The arguments of methods can have type constraints as well. The operator this + line lets $\mathrm{A}+\mathrm{B}$ add two matrices. The type of the second argument y is constrained to have the same number of rows and columns as the first argument this. Attempts to add mismatched matrices will be flagged as type errors at compilation.

At times it is more convenient to put the constraint on the method as a whole, as seen in the operator this * line. Unlike for + , there is no need to constrain both dimensions; we simply need to check that the columns of the left factor match the rows of the right. This constraint is written in $\{\ldots\}$ after the argument list. The shape of the result is computed from the shapes of the arguments.

And that is all that is necessary for a user-defined class of matrices to have shapechecking for matrix addition and multiplication. The example method compiles under those definitions.

[^0]Generic types Containers may have type parameters, permitting the definition of generic types. Type parameters may be instantiated by any X10 type. It is thus possible to make a list of integers List [Int], a list of non-zero integers List[Int\{self !=0\}], or a list of people List[Person]. In the definition of List, T is a type parameter; it can be instantiated with any type.

```
class List[T] {
    var head: T;
    var tail: List[T];
    def this(h: T, t: List[T]) { head = h; tail = t; }
    def add(x: T) {
        if (this.tail == null)
                this.tail = new List[T](x, null);
        else
            this.tail.add(x);
    }
}
```

The constructor (def this) initializes the fields of the new object. The add method appends an element to the list. List is a generic type. When instances of List are allocated, the type parameter T must be bound to a concrete type. List [Int] is the type of lists of element type Int, List[List[String]] is the type of lists whose elements are themselves lists of string, and so on.

### 2.2 The sequential core of $\mathbf{X 1 0}$

The sequential aspects of X10 are mostly familiar from C and its progeny. X10 enjoys the familiar control flow constructs: if statements, while loops, for loops, switch statements, throw to raise exceptions and try...catch to handle them, and so on.

X10 has both implicit coercions and explicit conversions, and both can be defined on user-defined types. Explicit conversions are written with the as operation: n as Int. The types can be constrained: $n$ as Int $\{$ self $!=0\}$ converts $n$ to a non-zero integer, and throws a runtime exception if its value as an integer is zero.

### 2.3 Places and activities

The full power of X10 starts to emerge with concurrency. An X10 program is intended to run on a wide range of computers, from uniprocessors to large clusters of parallel processors supporting millions of concurrent operations. To support this scale, X10 introduces the central concept of place (§13). A place can be thought of as a virtual shared-memory multi-processor: a computational unit with a finite (though perhaps changing) number of hardware threads and a bounded amount of shared memory, uniformly accessible by all threads.

An X10 computation acts on values $(8.1)$ through the execution of lightweight threads called activities(\$14). An object has a small, statically fixed set of fields, each of which has a distinct name. A scalar object is located at a single place and stays at that place throughout its lifetime. An aggregate object has many fields (the number may be known only when the object is created), uniformly accessed through an index (e.g., an integer) and may be distributed across many places. The distribution of an aggregate object remains unchanged throughout the computation, thought different aggregates may be distributed differently. Objects are garbage-collected when no longer useable; there are no operations in the language to allow a programmer to explicitly release memory.

X10 has a unified or global address space. This means that an activity can reference objects at other places. However, an activity may synchronously access data items only in the current place, the place in which it is running. It may atomically update one or more data items, but only in the current place. If it becomes necessary to read or modify an object at some other place q, the place-shifting operation at $(q ; F)$ can be used, to move part of the activity to $q$. $F$ is a specification of what information will be sent to $q$ for use by that part of the computation. It is easy to compute across multiple places, but the expensive operations (e.g., those which require communication) are readily visible in the code.

Atomic blocks. X10 has a control construct atomic S where S is a statement with certain restrictions. S will be executed atomically, without interruption by other activities. This is a common primitive used in concurrent algorithms, though rarely provided in this degree of generality by concurrent programming languages.

More powerfully - and more expensively - X10 allows conditional atomic blocks, when (B) $S$, which are executed atomically at some point when $B$ is true. Condi-
tional atomic blocks are one of the strongest primitives used in concurrent algorithms, and one of the least-often available.

Asynchronous activities. An asynchronous activity is created by a statement async $S$, which starts up a new activity running $S$. It does not wait for the new activity to finish; there is a separate statement (finish) to do that.

### 2.4 Clocks

The MPI style of coordinating the activity of multiple processes with a single barrier is not suitable for the dynamic network of heterogeneous activities in an X10 computation. X10 allows multiple barriers in a form that supports determinate, deadlock-free parallel computation, via the Clock type.

A single Clock represents a computation that occurs in phases. At any given time, an activity is registered with zero or more clocks. The X10 statement next tells all of an activity's registered clocks that the activity has finished the current phase, and causes it to wait for the next phase. Other operations allow waiting on a single clock, starting new clocks or new activities registered on an extant clock, and so on.

Clocks act as barriers for a dynamically varying collection of activities. They generalize the barriers found in MPI style program in that an activity may use multiple clocks simultaneously. Yet programs using clocks properly are guaranteed not to suffer from deadlock.

### 2.5 Arrays, regions and distributions

X10 provides DistArrays, distributed arrays, which spread data across many places. An underlying Dist object provides the distribution, telling which elements of the DistArray go in which place. Dist uses subsidiary Region objects to abstract over the shape and even the dimensionality of arrays. Specialized X10 control statements such as ateach provide efficient parallel iteration over distributed arrays.

### 2.6 Annotations

X10 supports annotations on classes and interfaces, methods and constructors, variables, types, expressions and statements. These annotations may be processed by compiler plugins.

### 2.7 Translating MPI programs to X10

While X10 permits considerably greater flexibility in writing distributed programs and data structures than MPI, it is instructive to examine how to translate MPI programs to X10.

Each separate MPI process can be translated into an X10 place. Async activities may be used to read and write variables located at different processes. A single clock may be used for barrier synchronization between multiple MPI processes. X10 collective operations may be used to implement MPI collective operations. X10 is more general than MPI in (a) not requiring synchronization between two processes in order to enable one to read and write the other's values, (b) permitting the use of high-level atomic blocks within a process to obtain mutual exclusion between multiple activities running in the same node (c) permitting the use of multiple clocks to combine the expression of different physics (e.g., computations modeling blood coagulation together with computations involving the flow of blood), (d) not requiring an SPMD style of computation.

### 2.8 Summary and future work

### 2.8.1 Design for scalability

X10 is designed for scalability, by encouraging working with local data, and limiting the ability of events at one place to delay those at another. For example, an activity may atomically access only multiple locations in the current place. Unconditional atomic blocks are dynamically guaranteed to be non-blocking, and may be implemented using non-blocking techniques that avoid mutual exclusion bottlenecks. Data-flow synchronization permits point-to-point coordination between reader/writer activities, obviating the need for barrier-based or lock-based synchronization in many cases.

### 2.8.2 Design for productivity

X 10 is designed for productivity.

Safety and correctness. Programs written in X10 are guaranteed to be statically type safe, memory safe and pointer safe, with certain exceptions given in $\$ 4.15$.
Static type safety guarantees that every location contains only values whose dynamic type agrees with the location's static type. The compiler allows a choice of how to handle method calls. In strict mode, method calls are statically checked to be permitted by the static types of operands. In lax mode, dynamic checks are inserted when calls may or may not be correct, providing weaker static correctness guarantees but more programming convenience.
Memory safety guarantees that an object may only access memory within its representation, and other objects it has a reference to. X10 does not permit pointer arithmetic, and bound-checks array accesses dynamically if necessary. X10 uses garbage collection to collect objects no longer referenced by any activity. X10 guarantees that no object can retain a reference to an object whose memory has been reclaimed. Further, X10 guarantees that every location is initialized at run time before it is read, and every value read from a word of memory has previously been written into that word.
Because places are reflected in the type system, static type safety also implies place safety. All operations that need to be performed locally are, in fact, performed locally. All data which is declared to be stored locally are, in fact, stored locally.
X10 programs that use only clocks and unconditional atomic blocks are guaranteed not to deadlock. Unconditional atomic blocks are non-blocking, hence cannot introduce deadlocks. Many concurrent programs can be shown to be determinate (hence race-free) statically.

Integration. A key issue for any new programming language is how well it can be integrated with existing (external) languages, system environments, libraries and tools.
We believe that X10, like Java, will be able to support a large number of libraries and tools. An area where we expect future versions of X10 to improve on Java like languages is native integration ( $\$ 18$ ). Specifically, X10 will permit multidimensional local arrays to be operated on natively by native code.

### 2.8.3 Conclusion

X10 is considerably higher-level than thread-based languages in that it supports dynamically spawning lightweight activities, the use of atomic operations for mutual exclusion, and the use of clocks for repeated quiescence detection.
Yet it is much more concrete than languages like HPF in that it forces the programmer to explicitly deal with distribution of data objects. In this the language reflects the designers' belief that issues of locality and distribution cannot be hidden from the programmer of high-performance code in high-end computing. A performance model that distinguishes between computation and communication must be made explicit and transparent..$^{2}$ At the same time we believe that the place-based type system and support for generic programming will allow the X10 programmer to be highly productive; many of the tedious details of distributionspecific code can be handled in a generic fashion.

[^1]
## 3 Lexical and Grammatical structure

Lexically a program consists of a stream of white space, comments, identifiers, keywords, literals, separators and operators, all of them composed of Unicode characters in the UTF-8 (or US-ASCII) encoding.

### 3.1 Whitespace

ASCII space, horizontal tab (HT), form feed (FF) and line terminators constitute white space.

### 3.2 Comments

All text included within the ASCII characters "/*" and "*/" is considered a comment and ignored; nested comments are not allowed. All text from the ASCII characters "//" to the end of line is considered a comment and is ignored.

### 3.3 Identifiers

Identifiers consist of a single letter followed by zero or more letters or digits. The letters are the ASCII characters a through z, A through Z, and _. Digits are defined as the ASCII characters 0 through 9. Case is significant; a and A are distinct identifiers, as is a keyword, but As and AS are identifiers. (However, case
is insignificant in the hexadecimal numbers, exponent markers, and type-tags of numeric literals $-0 x b a b e=0 X B A B E$.)

In addition, any string of characters may be enclosed in backquotes ' to form an identifier - though the backquote character itself, and the backslash character, must be quoted by a backslash if they are to be included. This allows, for example, keywords to be used as identifiers. The following are backquoted identifiers:
‘while‘, ‘!‘, ‘(unbalanced(‘, ‘\‘<br>‘, ‘0‘

Certain back ends and compilation options do not support all choices of identifier.

### 3.4 Keywords

X10 uses the following keywords:

| abstract | as | assert | async | at |
| :--- | :--- | :--- | :--- | :--- |
| athome | ateach | atomic | break | case |
| catch | class | clocked | continue | def |
| default | do | else | extends | false |
| final | finally | finish | for | goto |
| haszero | here | if | implements | import |
| in | instanceof | interface | native | new |
| null | offer | offers | operator | package |
| private | property | protected | public | return |
| self | static | struct | super | switch |
| this | throw | transient | true | try |
| type | val | var | void | when |
| while |  |  |  |  |

Keywords may be used as identifiers by enclosing them in backquotes: 'new ' is an identifier, new is a keyword but not an identifier.
Note that the primitive type names are not considered keywords.

### 3.5 Literals

Briefly, X10 v2.2 uses fairly standard syntax for its literals: integers, unsigned integers, floating point numbers, booleans, characters, strings, and null. The
most exotic points are (1) unsigned numbers are marked by a $u$ and cannot have a sign; (2) true and false are the literals for the booleans; and (3) floating point numbers are Double unless marked with an $f$ for Float.

Less briefly, we use the following abbreviations:

$$
\begin{aligned}
d & =\text { one or more decimal digitsonly starting with } 0 \text { if it is } 0 \\
d_{8} & =\text { one or more octal digits } \\
d_{16} & =\text { one or more hexadecimal digits, using a-f or A-F for 10-15 } \\
i & =d\left|\otimes d_{8}\right| 0 \mathbf{x} d_{16} \mid 0 \mathbf{X} d_{16} \\
s & =\text { optional }+ \text { or - } \\
b & =d|d .|d . d| \cdot d \\
x & =(\mathrm{e} \mid \mathrm{E}) s d \\
f & =b x
\end{aligned}
$$

- true and false are the Boolean literals.
- null is a literal for the null value. It has type Any\{self==null\}.
- Int literals have the form si; e.g., 123, -321 are decimal Ints, 0123 and -0321 are octal Ints, and 0x123, -0X321, 0xBED, and OXEBEC are hexadecimal Ints.
- Long literals have the form sil or siL. E.g., 1234567890L and 0xBABEL are Long literals.
- UInt literals have the form $i \mathbf{u}$ or $i \mathrm{U}$. E.g., 123u, 0123u, and 0xBEAU are UInt literals.
- ULong literals have the form $i \mathbf{u l}$ or $i l u$, or capital versions of those. For example, 123ul, 0124567012ul, 0xFLU, OXba1eful, and 0xDecafCOffeefUL are ULong literals.
- Short literals have the form sis or siS. E.g., $414 \mathrm{~S}, 0 \mathrm{xACES}$ and 7001 s are short literals.
- UShort literals form $i$ us or $i \mathbf{s u}$, or capital versions of those. For example, 609US, 107us, and 0xBeaus are unsigned short literals.
- Byte literals have the form siy or siY. (The letter B cannot be used for bytes, as it is a hexadecimal digit.) $50 Y$ and $0 \times B A B Y$ are byte literals.
- UByte literals have the form iuy or $i y u$, or capitalized versions of those. For example, 9uy and OxBUY are UByte literals.
- Float literals have the form $s f f$ or $s f F$. Note that the floating-point marker letter $f$ is required: unmarked floating-point-looking literals are Double. E.g., 1f, $6.023 \mathrm{E}+32 \mathrm{f}, 6.626068 \mathrm{E}-34 \mathrm{~F}$ are Float literals.
- Double literals have the form $s f \mathrm{l}^{1} s f \mathrm{D}$, and $s f$ d. E.g., 0.0, 0e100, 1.3D, 229792458d, and 314159265e-8 are Double literals.
- Char literals have one of the following forms:
- ' $c$ ' where $c$ is any printing ASCII character other than $\backslash$ or ', representing the character $c$ itself; e.g., '!';
- ' $\backslash \mathrm{b}$ ', representing backspace;
- ' $\backslash t$ ', representing tab;
- '\n', representing newline;
- ' $\backslash \mathrm{f}$ ', representing form feed;
- ' $\backslash r$ ', representing return;
- ' $\backslash$ ', , representing single-quote;
- ’\"', representing double-quote;
- ' $\backslash \backslash$ ', representing backslash;
- ' $\backslash d d$ ', where $d d$ is one or more octal digits, representing the one-byte character numbered $d d$; it is an error if $d d>0377$.
- String literals consist of a double-quote ", followed by zero or more of the contents of a Char literal, followed by another double quote. E.g., "hi!", " ".


### 3.6 Separators

X10 has the following separators and delimiters:
( ) $\}[$ ] ; .

[^2]
### 3.7 Operators

X10 has the following operator, type constructor, and miscellaneous symbols. (? and : comprise a single ternary operator, but are written separately.)

$$
\begin{array}{llllll}
== & != & < & > & <= & >= \\
\& \& & |\mid & \& & \mid & n & \\
\ll & \gg & \ggg & & \\
+ & - & * & / & \% & \\
++ & -- & ! & \sim & \\
\&= & \mid= & \wedge \\
\ll= & \gg= & \ggg= \\
+= & -= & *= & /= & \% & \\
= & ? & : & => & -> \\
<: & :> & @ & \cdots & \\
* * & !\sim & -< & >- &
\end{array}
$$

The precedence of the operators is as follows. Earlier rows of the table have higher precedence than later rows, binding more tightly. For example, $a+b * c<d$ parses as $(a+(b * c))<d$, and -1 as Byte parses as $-(1$ as Byte).
postfix ()
as T , postfix ++, postfix --
unary -, unary +, prefix ++, prefix --
unary operators !, ~, ^, *, |, \& , /, and \%

```
* / % **
+
<< >> >>> -> >- -< <- !
> >= < <= instanceof
== != ! ! 
&
^
|
&&
|
? :
=, *=, /=, %=, +=, -=, <<=,>>=, >>>=, &=, ^=, |=
```


### 3.8 Grammatical Notation

In this manual, ordinary BNF notation is used to specify grammatical constructions, with a few minor extensions. Grammatical rules look like this:

```
Adj ::= Adv? happy
    | Adv? sad
Adv ::= very
    | Adv Adv
```

Terms in italics are called non-terminals. They represent kinds of phrases; for example, ForStmt 20.73$)^{2}$ describes all for statements. Equation numbers refer to the full X10 grammar, in $\$ 20$. The small example has two non-terminals, $A d v$ and Adj.

Terms in fixed-width font are terminals. They represent the words and symbols of the language itself. In X10, the terminals are the words described in this chapter.
A single grammatical rule has the form $A::=X_{1} X_{2} \ldots X_{n}$, where the $X_{i}$ 's are either terminals or nonterminals. This indicates that the non-terminal $A$ could be an instance of $X_{1}$, followed by an instance of $X_{2}, \ldots$, followed by an instance of $X_{n}$. Multiple rules for the same $A$ are allowed, giving several possible phrasings of $A$ 's. For brevity, two rules with the same left-hand side are written with the left-hand side appearing once, and the right-hand sides separated by $\mid$.
In the $A d j$ example, there are two rules for $A d v, A d v::=$ very and $A d v::=$ $A d v A d v$. So, an adverb could be very, or (by three uses of the rule) very very, or, one or more verys.
The notation $A^{?}$ indicates an optional $A$. This is an ordinary non-terminal, defined by the rules:


The first
rule says that $A^{?}$ can amount to nothing; the second, that it can amount to an $A$. This concept shows up so often that it is worth having a separate notation for it. In the Adj example, an adjective phrase may be preceded by an optional adverb. Thus, it may be happy, or very happy, or very very sad, etc.

[^3]
## 4 Types

X10 is a strongly typed object-oriented language: every variable and expression has a type that is known at compile-time. Types limit the values that variables can hold.

X10 supports four kinds of values, objects, struct values, functions, and null. Objects are in the grand tradition of object-oriented languages, and the heart of most X10 computations. They are instances of classes (§8; they hold zero or more data fields that may be mutable. They respond to methods, and can inherit behavior from their superclass.

Struct values are similar to objects, though more restricted in ways that make them more efficient in space and time. Their fields cannot be mutable, and, although they respond to methods, they do not inherit behavior. They are instances of struct types ( $\$ 9$ ).

Together, objects and struct values are called containers, because they hold data.
Functions, called closures, lambda-expressions, and blocks in other languages, are instances of function types ( $\$ 10$ ). A function has zero or more formal parameters (or arguments) and a body, which is an expression that can reference the formal parameters and also other variables in the surrounding block. For instance, ( $x:$ Int) $=>x * y$ is a unary integer function which multiplies its argument by the variable $y$ from the surrounding block. Functions may be freely copied from place to place and may be repeatedly applied.

Finally, null is a constant, often found as the default value of variables of object type. While it is not an object, it may be stored in variables of class type - except for types which have a constraint $(\$ 4.5)$ which specifically excludes null.

These runtime values are classified by types. Types are used in variable declarations ( $\$ 12.2$ ), coercions and explicit conversions (\$11.9.1), object creation
( $\$ 11.21$ ), static state and method accessors ( $\$ 11.4$ ), generic classes, structs, interfaces, and methods ( $\$ 4.3$ ), type definitions ( $\$ 4.4$ ), closures ( $\$ 10$ ), class, struct, and interface declarations (§8.1.2), subtyping expressions (§11.25), and instanceof and as expressions (\$11.24).

The basic relationship between values and types is the is a value in relation: e is a value in T. We also often say "e has type T" to or "e is an element of type T". For example, 1 has type Int (the type of all integers representible in 32 bits). It has the more general type Any (since all entitites have type Any). Furthermore, it has such types as "Nonzero integer" and "Integer equal to one", and many others. These types are expressable in X10 using constrained types (\$4.5). Int $\{$ sel $f!=0\}$ is the type of Ints self ${ }^{11}$ which are not equal to zero, and Int $\{\operatorname{self}==1\}$ is the type of the Ints which are equal to one.

The basic relationship between types is subtyping: $\mathrm{T}<$ : U holds if every value in T is also a value ind U . Two important kinds of subtyping are subclassing and strengthening. Subclassing is a familiar notion from object-oriented programming. Here we use it to refer to the relationship between a class and another class it extends or an interface ( $\$ 77$ it implements. For instance, in a class hierarchy with classes Animal and Cat such that Cat extends Mammal and Mammal extends Animal, every instance of Cat is by definition an instance of Animal (and Mammal). We say that Cat is a subclass of Animal, or Cat <: Animal by subclassing. If Animal implements Thing, then Cat also implements Thing, and we say Cat <: Thing by subclassing.
Strengthening is an equally familiar notion from logic. The instances of Int \{self $==1\}$ are all elements of Int $\{\operatorname{self}!=0\}$ as well, because self $==1$ logically implies self $!=0$; so Int $\{\operatorname{self}==1\}<$ : Int $\{$ self $!=0\}$ by strengthening. X10 uses both notions of subtyping. See $\$ 4.9$ for the full definition of subtyping in X10.

### 4.1 Type System

X10 has several sorts of types. In this section, $\mathrm{S}, \mathrm{T}$, and $\mathrm{T}_{i}$ range over types. X ranges over type variables, M and $\mathrm{x}_{i}$ over identifiers, c over constraint expressions ( $\$ 4.5$ ), and $\mathrm{e}_{i}$ over expressions. For compactness, slanted brackets are used to

[^4]indicate optional elements. ${ }^{2}$


A type given by (1) is an identifier M, like Point, Int, or int. It refer to a unit - a class, struct type, or interface, ( $\$ 4.2$. Or, it can refer to a name defined by a type statement ( $\$ 4.4$;
Example: String refers to the standard class of strings, Int to the standard struct type of integers, and Any to the interface that describes all X10 values. int is an alias for the type Int, for the comfort of programmers used to other languages in the C family.
A type of the form (2), a type variable X, refers to a parameter type of a generic (parameterized) type, as described in $\$ 4.3$.

Example: The class Pair [X] below provides a simplistic way to keep two things of the same type together: ${ }^{3}$ Pair [Int] holds two integers; Pair [Pair [String]] holds two pairs of strings. Within the definition of Pair, the type variable X is the parameter type of Pair - that is, the type which this pair is a pair of.

```
class Pair[X]{
    public val first : X;
    public val second: X;
    public def this(f:X, s:X) {first = f; second = s;}
}
```

A type of form (3), $\mathrm{M}[\mathrm{T}, \mathrm{U}]$, is a use of a generic type, also described in $\$ 4.3$, or a generic type-defined type without value parameters (\$4.4). The types inside the

[^5]brackets are the actual parameters corresponding to the formal parameters of the parameterized type M. Pair[Int], above, is an example of a use of the generic type Pair.
A type of form (4), T. U , is a qualified type: a unit U appearing inside of the unit T, as described in 8.13 .

## Example:

```
class Outer {
    class Inner { /* ... */ }
}
```

then (new Outer()). new Inner() creates a value of type Outer. Inner.
A type of form (5), F, such as ( $\mathrm{x}: \mathrm{Int}$ ) $=>\mathrm{Int}$, is a function type. Its values are functions, e.g., the squaring function taking integers to integers. Function types are described in $\$ 4.6$, and computing with functions is described in $\$ 10$.
Example: square is the squaring function on integers. It is used in the assert line.

```
val square : (x:Int)=>Int
    = (x:Int)=>x*x;
assert square(5) == 25;
```

A term of form (6), such as M[T] (e), is an instance of a parameterized type definition. Such types may be parameterized by both types and values. This is described in $\$ 4.4$.
Example: Array[Int](1) is the type of one-dimensional arrays of integers. It has one type parameter giving the type of element, here Int. It has one value parameter giving the number of dimensions, here 1. Region(1) is the type of one-dimensional regions of points ( $\$ 16.3$ ).
In the function types (6), the variable names are bound. As with all bound variables in X10, they can be renamed. So, for example, the types ( $x$ : Int) $=>$ Int $\{$ self $f!=x\}$ and $(y: \operatorname{Int})=>\operatorname{Int}\{s e l f!=y\}$ are equivalent, as they differ by nothing but the names of bound variables. This is more visible with types than with, say, methods or functions, because we can test equality of types.
Furthermore, if a variable $x$ does not appear anywhere in a function type $F$ save as an argument name, it (and its ":") can be omitted. E.g., the types (x:Int) $=>$ Int and (Int) $=>$ Int are equivalent.

## Example:

```
val f : (x:Int)=>Int{self!=x} = (x:Int) => (x+1) as Int{self!=x};
val g : (y:Int)=>Int{self!=y} = f;
val t : (x:Int)=> Int = (x:Int) => x;
val u : ( Int )=>Int = t;
```

A term of form (7), $\mathrm{T}\{\mathrm{c}\}$, is a type whose values are the values of type T for which the constraint c is true. This is described in $\$ 4.5$.
Example: A variable of class Point, unconstrained, can contain null:

```
var gotNPE: Boolean = false;
val p : Point = null;
try {
    val q = p * 2; // method invocation, NPE
}
catch(NullPointerException) {
    gotNPE = true;
}
assert gotNPE;
```

A suitable constraint on that type will prevent a null from ever being assigned to the variable. The variable self, in a constraint, refers to the value being constrained, so the constraint self != null means "which is not null". So, adding $a\{\mathrm{self}!=\mathrm{null}\}$ constraint to Point results in a compile-time error, rather than a runtime null pointer exception.
// ERROR: p : Point\{self!=null\} = null;

### 4.2 Unit Types: Classes, Struct Types, and Interfaces

Most X10 computation manipulates values via the unit types: classes, struct types, and interfaces. These types share a great deal of structure, though there are important differences.

### 4.2.1 Class types

A class declaration declares a class type ( $\S 8)$, giving its name, behavior, and data. It may inherit from one parent class, and, if no parent class is specified, it
implicitly inherits from x10.lang. Object. It may also implement zero or more interfaces, each one of which becomes a supertype of it.
Example: The Position class below could describe the position of a slider control. The example method uses Position as a type. Position is a subtype of the class Object and the type Poser.

```
interface Poser {
    def pos():Int;
    }
class Position implements Poser {
    private var x : Int = 0;
    public def move(dx:Int) { x += dx; }
    public def pos() : Int = x;
    static def example() {
        var p : Position;
    }
}
```

The null value, represented by the literal null, is a value of every class type C. The type whose values are all instances of $C$ except null can be defined as C\{self != null\}.

### 4.2.2 Struct Types

A struct declaration ( $\$ 9$ ) introduces a struct type containing all instances of the struct. Struct types can include nearly all the features that classes have. They can implement interfaces, which become their supertypes just as for classes; but they do not have superclasses, and cannot extend anything.
Example: The Coords struct gives an immutable position in 3-space. It is used as a type in example():

```
struct Position \{
    public val x:Double; public val y:Double; public val z:Double;
    def this(x:Double, y:Double, z:Double) \{
        this. \(x=x ;\) this. \(y=y ; ~ t h i s . z ~=~ z ; ~\)
    \}
    static def example(p: Position, q: Array[Position]) \{
        var r : Position = p;
```

```
    }
```

\}

### 4.2.3 Interface types

An interface declaration (\$7) defines an interface type, specifying a set of instance method signatures and property method signatures which must be provided by any container declared to implement the interface. They can also declare static val fields, which are provided to all units implementing or extending the interface. They do not have code, and cannot implement anything. An interface may extend multiple interfaces. Each interface it extends becomes one of its superclasses.
Example: Named and Mobile are interfaces, each specifying a single method. Person and NamedPoint are subtypes of both of them. They are used as types in the example method.

```
interface Named {
    def name():String;
}
interface Mobile {
    def where():Int;
    def move(howFar:Int):void;
}
interface NamedPoint extends Named, Mobile {}
class Person implements Named, Mobile {
    var name:String; var pos: Int;
    public def name() = this.name;
    public def move(howFar:Int) { pos += howFar; }
    public def where() = this.pos;
    public def example(putAt:Mobile) {
        this.pos = putAt.where();
    }
}
```


### 4.2.4 Properties

Classes, interfaces, and structs may have properties, specified in parentheses after the type name. Properties are much like public val instance fields. They have
certain restrictions on their use, however, which allows the compiler to understand them much better than other public val fields. In particular, they can be used in types. E.g., the number of elements in an array is a property of the array, and an X10 program can specify that two arrays have the same number of elements.
Example: The following code declares a class named Coords with properties x and y and a move method. The properties are bound using the property statement in the constructor.

```
class Coords(x: Int, y: Int) {
    def this(x: Int, y: Int) :
        Coords{self.x==x, self.y==y} = {
        property(x, y);
    }
    def move(dx: Int, dy: Int) = new Coords(x+dx, y+dy);
}
```

Properties of self can be used in constraints. This places certain restrictions on how properties can be used, but allows a great deal of compile-time constraint checking. For a simple example, new $\operatorname{Coords}(0,0)$ is known to be an instance of Coords\{self. $x==0\}$. Details of this substantial topic are found in $\$ 4.5$.

### 4.3 Type Parameters and Generic Types

A class, interface, method, or type definition may have type parameters. Type parameters can be used as types, and will be bound to types on instantiation. For example, a generic stack class may be defined as Stack[T]\{...\}. Stacks can hold values of any type; e.g., Stack[Int] is a stack of integers, and Stack[Point \{self!=null\}] is a stack of non-null Points. Generics must be instantiated when they are used: Stack, by itself, is not a valid type. Type parameters may be constrained by a guard on the declaration ( $\$ 4.4, \$ 8.4 .5, \$ 10.3$ ).

A generic class (or struct, interface, or type definition) is a class (resp. struct, interface, or type definition) declared with $k \geq 1$ type parameters. A generic class (or struct, interface, or type definition) can be used to form a type by supplying $k$ types as type arguments within [...].
Example: Bottle[T] is a generic class. A Bottle[T]can hold a value of
type T ; the variable yup in example() is of type Bottle[Boolean] and thus can hold a Boolean. Hoever, Bottle alone is not a type..$^{4}$

```
class Bottle[T] {
    var contents : T;
    public def this(t:T) { contents = t; }
    public def putIn(t:T) { contents = t; }
    public def get() = contents;
    static def example() {
        val yup : Bottle[Boolean] = new Bottle[Boolean](true);
        //ERROR: var nope : Bottle = null;
    }
}
```

A class (whether generic or not) may have generic methods.
Example: NonGeneric has a generic method first[T](x:List%5BT%5D). An invocation of such a method may supply the type parameters explicitly (e.g., first [Int] (z)). In certain cases (e.g., first (z) type parameters may be omitted and are inferred by the compiler ( $\$ 4.12$ ).

```
class NonGeneric {
    static def first[T](x:List[T]):T = x(0);
    def m(z:List[Int]) {
        val f = first[Int](z);
        val g = first(z);
        return f == g;
    }
}
```

Limitation: X10 v2.2's C++ back end requires generic methods to be static or final; the Java back end can accomodate generic instance methods as well.

### 4.4 Type definitions

A type definition can be thought of as a type-valued function, mapping type parameters and value parameters to a concrete type.

[^6]

Formals $\quad::=$ (FormalList ${ }^{?}$ )
Guard $::=$ DepParams

During type-checking the compiler replaces the use of such a defined type with its body, substituting the actual type and value parameters in the call for the formals. This replacement is performed recursively until the type no longer contains a defined type or a predetermined compiler limit is reached (in which case the compiler declares an error). Thus, recursive type definitions are not permitted.
Type definitions are considered applicative and not generative - they do not define new types, only aliases for existing types.

Type definitions may have guards: an invocation of a type definition is illegal unless the guard is satisified when formal types and values are replaced by the actual parameters.

Type definitions may be overloaded: two type definitions with the same name are permitted provided that they have a different number of type parameters or different number or type of value parameters. The rules for type definition resolution are identical to those for method resolution.

However, T() is not allowed. If there is an argument list, it must be nonempty. This avoids a possible confusion between type $\mathrm{T}=\ldots$ and type T()$=\ldots$.

A type definition for a type T can appear:

- As a top-level definition in a file named T.x10; or
- As a static member in a container definition; or
- In a block statement.

Use of type definitions in constructor invocations If a type definition has no type parameters and no value parameters and is an alias for a container type, a new expression may be used to create an instance of the class using the type definition's name. Similarly, a parameterless alias for an interface can be used to construct an instance of an anonymous class. Given the following type definition:

```
type \(\mathrm{A}=\mathrm{C}\left[\mathrm{T}_{1}, \ldots, \mathrm{~T}_{k}\right]\{\mathrm{c}\} ;\)
```

where $C\left[\mathrm{~T}_{1}, \ldots, \mathrm{~T}_{k}\right]$ is a class type, a constructor of C may be invoked with new $A\left(\mathrm{e}_{1}, \ldots, \mathrm{e}_{n}\right)$, if the invocation new $C\left[\mathrm{~T}_{1}, \ldots, \mathrm{~T}_{k}\right]\left(\mathrm{e}_{1}, \ldots, \mathrm{e}_{n}\right)$ is legal and if the constructor return type is a subtype of A.

Example: The names of the class Cont [X] and the interface Inte [X] can be used to create an object a of type Cont [Int], and an object b which implements Inte[Int]. The two types may be given aliases A and B , which may then be used in more compact expressions to construct objects aa and bb of the same types.

```
class ConstructorExample {
    static class Cont[X]{}
    static interface Inte[X]{
            def meth():X;
        }
    public static def example() {
        val a = new Cont[Int]();
        val b = new Inte[Int](){public def meth()=3;};
        type A = Cont[Int];
        val aa = new A();
        type B = Inte[Int];
        val bb = new B(){public def meth()=4;};
    }
}
```

Automatically imported type definitions The collection of type definitions in x10.lang._ is automatically imported in every compilation unit.

### 4.4.1 Motivation and use

The primary purpose of type definitions is to provide a succinct, meaningful name for complex types and combinations of types. With value arguments, type arguments, and constraints, the syntax for X10 types can often be verbose. For example, a non-null list of non-null strings is
List[String\{self!=null\}]\{self!=null\}.
We could name that type:

```
static type LnSn = List[String{self!=null}]{self!=null};
```

Or, we could abstract it somewhat, defining a type constructor Nonnull [T] for the type of T's which are not null:

```
class Example {
    static type Nonnull[T]{T <: Object} = T{self!=null};
    var example : Nonnull[Example] = new Example();
}
```

Type definitions can also refer to values, in particular, inside constraints. The type of n-element Array[Int] (1)s is Array[Int]\{self.rank==1 \&\& self.size
$==n\}$ but it is often convenient to give a shorter name:

```
type Vec(n:Int) = Array[Int]{self.rank==1, self.size == n};
var example : Vec(78);
```

The following examples are legal type definitions,

```
import x10.util.*;
class TypeExamples {
    static type StringSet = Set[String];
    static type MapToList[K,V] = Map[K,List[V]];
    static type Int(x: Int) = Int{self==x};
    static type Dist(r: Int) = Dist{self.rank==r};
    static type Dist(r: Region) = Dist{self.region==r};
    static type Redund(n:Int, r:Region){r.rank==n}
            = Dist{rank==n && region==r};
}
```

The following code illustrates that type definitions are applicative rather than generative. B and C are both aliases for String, rather than new types, and so are interchangeable with each other and with String. Similarly, A and Int are equivalent.

```
def someTypeDefs () {
    type A = Int;
    type B = String;
    type C = String;
    a: A = 3;
    b: B = new C("Hi");
```

```
c: C = b + ", Mom!";
}
```


### 4.5 Constrained types

Basic types, like Int and List [String], provide useful descriptions of data.
However, one frequently wants to say more. One might want to know that a String variable is not null, or that a matrix is square, or that one matrix has the same number of columns as another has rows (so they can be multiplied). In the multicore setting, one might wish to know that two values are located at the same processor, or that one is located at the same place as the current computation.
In most languages, there is simply no way to say and check these things statically. Programmers must made do with comments, assert statements, and dynamic tests. X10 programs can do better, with constraints on types, and guards on class, method and type definitions.

A constraint expression is a Boolean expression e of a quite limited form (\$4.5.2). . A constraint expression c may be attached to a basic type T, giving a constrained type $\mathrm{T}\{\mathrm{c}\}$. The values of type $\mathrm{T}\{\mathrm{c}\}$ are the values of T for which c is true. Constraint expressions also serve as guards on methods (\$8.4) and functions (\$10.3), and invariants on unit types ( $\$ 8.8$.
When constraining a value of type $T$, self refers to the object of type $T$ which is being constrained. For example, Int $\{\operatorname{self}==4\}$ is the type of Ints which are equal to 4 - the best possible description of 4 , and a very difficult type to express without using self.

## Example:

- Int $\{\operatorname{self}!=0\}$ is the type of non-zero Ints.
- Int $\{\mathrm{self}==0\}$ is the type of Ints which are zero.
- Int $\{\operatorname{self}!=0$, self $!=1\}$ is the type of Ints which are neither zero nor one.
- Int\{self == 0, self == 1\} is the type of Ints which are both zero and one. There are no such values, so it is an empty type.
- String\{self != null\} is the type of non-null strings.
- Suppose that Matrix is a matrix class with properties rows and cols. Matrix\{self.rows == self.cols\} is the type of square matrices.
- One way to say that a has the same number of columns that b has rows (so that a *b is a valid matrix product), one could say:

```
val a : Matrix = someMatrix() ;
var b : Matrix{b.rows == a.cols} ;
```

$\mathrm{T}\{\mathrm{e}\}$ is a dependent type, that is, a type dependent on values. The type T is called the base type and e is called the constraint. If the constraint is omitted, it is true-that is, the base type is unconstrained.
Constraints may refer to immutable values in the local environment:

$$
\begin{aligned}
& \text { val } n=1 ; \\
& \text { var } p: \text { Point }\{r a n k==n\} ;
\end{aligned}
$$

In a val variable declaration, the variable itself is in scope in its type, and can be used in constraints.

Example: For example, val nz: Int $\{\mathrm{nz}$ != $\mathbf{0}\}=1$; declares a non-zero variable nz . In this case, nz could have been declared as val nz : Int\{self $!=0\}=1$.

### 4.5.1 Examples of Constraints

Example of entailment and subtyping involving constraints.

- Int $\{\operatorname{self}==3\}<: \operatorname{Int}\{\operatorname{self}!=14\}$. The only value of Int $\{$ self $==3\}$ is 3. All integers but 14 are members of Int\{self != 14\}, and in particular 3 is.
- Suppose we have classes Child <: Person, and Person has a ssn:Long property. If rhys : Child\{ssn == 123456789\}, then rhys is also a Person. rhys's ssn field is the same, 123456789 , whether rhys is regarded as a Child or a Person. Thus, rhys : Person\{ssn==123456789\} as well. So,

$$
\text { Child\{ssn }==123456789\}<: \text { Person\{ssn }==123456789\} .
$$

- Furthermore, since 123456789 != 555555555, is is clear that rhys : Person\{ssn != 555555555\}. So,

$$
\text { Child\{ssn == } 123456789\}<: \text { Person\{ssn != 555555555\}. }
$$

- $\mathrm{T}\{\mathrm{e}\}<: \mathrm{T}$ for any type T . That is, if you have a value v of some base type $T$ which satisfied $e$, then $v$ is of that base type $T$ (with the constraint ignored).
- If $A<: B$, then $A\{c\}<: B\{c\}$ for every constraint $\{c\}$ for which $A\{c\}$ and $\mathrm{B}\{\mathrm{c}\}$ are defined. That is, if every A is also $\mathrm{a} B$, and $\mathrm{a}: \mathrm{A}\{\mathrm{c}\}$, then $a$ is an $A$ and $c$ is true of it. So a is also a $B$ (and $c$ is still true of it), so $\mathrm{a}: \mathrm{B}\{\mathrm{c}\}$.

Constraints can be used to express simple relationships between objects, enforcing some class invariants statically. For example, in geometry, a line is determined by two distinct points; a Line struct can specify the distinctness in a type constraint $\left.\right|^{5}$

```
struct Position(x: Int, y: Int) {}
struct Line(start: Position, end: Position){start != end}
    {}
```

Extending this concept, a Triangle can be defined as a figure with three line segments which match up end-to-end. Note that the degenerate case in which two or three of the triangle's vertices coincide is excluded by the constraint on Line. However, not all degenerate cases can be excluded by the type system; in particular, it is impossible to check that the three vertices are not collinear.

```
struct Triangle
    (a: Line,
    b: Line{a.end == b.start},
    c: Line{b.end == c.start && c.end == a.start})
    {}
```

[^7]The Triangle class automatically gets a ternary constructor which takes suitably constrained $\mathrm{a}, \mathrm{b}$, and c and produces a new triangle.

A constrained type may be constrained further: the type $S\{c\}\{d\}$ is the same as the type $S\{c, d\}$. Multiple constraints are equivalent to conjoined constraints: $S\{c, d\}$ in turn is the same as $S\{c \& \& d\}$.

### 4.5.2 Syntax of constraints

Only a few kinds of expressions can appear in constraints. For fundamental reasons of mathematical logic, the more kinds of expressions that can appear in constraints, the harder it is to compute the essential properties of constrained types - in particular, the harder it is to compute $A\{c\}<: B\{d\}$ or even $E: T\{c\}$. It doesn't take much to make this basic fact undecidable. In order to make sure that it stays decidable, X10 places stringent restrictions on constraints.
Only the following forms of expression are allowed in constraints.
Value expressions in constraints may be:

1. Literal constants, like 3 and true;
2. Accessible, immutable (val) variables and parameters;
3. this, if the constraint is at a point in the program where this is defined, but not in extends or implements clauses or class invariants;
4. here, if the constraint is at a point in the program where here is defined;
5. self;
6. A field selection expression $t . f$, where $t$ is a value expression allowed in constraints, and $f$ is a field of $t$ 's type. If $t$ is self, then $f$ must be a property, not an arbitrary field.
7. Invocations of property methods, $p(a, b, \ldots, c)$ or $a . p(b, c, \ldots d)$, where the receiver and arguments must be value expressions acceptable in constraints, as long as the expansion (viz., the expression obtained by taking the body of the definition of $p$, and replacing the formal parameters by the actual parameters) of the invocation is allowed as a value expression in constraints.

For an expression self.p to be legal in a constraint, p must be a property. However terms $t . f$ may be used in constraints (where $t$ is a term other than self and $f$ is an immutable field.)

Constraints may be any of the following, where all value expressions are of the forms which may appear in constraints:

1. Equalities $e==f$;
2. Inequalities of the form e $!=f: \sqrt[6]{6}$
3. Conjunctions of Boolean expressions that may appear in constraints (but only in top-level constraints, not in Boolean expressions in constraints);
4. Subtyping and supertyping expressions: $\mathrm{T}<: \mathrm{U}$ and $\mathrm{T}:>\mathrm{U}$;
5. Type equalities and inequalities: $\mathrm{T}=\mathrm{U}$ and $\mathrm{T}!=\mathrm{U}$;
6. Invocations of a property method, $p(a, b, \ldots, c)$ or $a . p(b, c, \ldots d)$, where the receiver and arguments must be value expressions acceptable in constraints, as long as the expansion of the invocation is allowed as a constraint.
7. Testing a type for a default: T haszero.

Note that constraints on methods may include private, protected, or packageprotected fields. It is possible to have a method whose guard cannot be directly checked, or even whose result type cannot be expressed as a clause in the program, at some call sites. Nonetheless, X10 uses a broader internal type representation, not limited by access rules, and can work with fields in types even though those fields cannot be used in executable code.

Example: This phenomenon can be used to implement a form of compiletype capability checking. We give a minimal example, providing only security by obscurity: users unaware that the key method returns the required key will be unable to use the secret method. This approach can be strengthened to provide better security.

The class Keyed has a private field k . The method secret ( q ) can only be called when $\mathrm{q}==\mathrm{k}$. In a larger example, secret could be some priveleged behavior or secret, available only to callers with proper authority.

[^8]At the call site in Snooper, keyed. secret() is called. It can't be called as keyed. secret(keyed.k), because k is a private field. It can't be called as keyed.secret(8), even though keyed. $\mathrm{k}==8$, because there is no proof available that keyed. $\mathrm{k}==8$ - indeed, at this point in the code, the requirement that keyed. $\mathrm{k}==8$ cannot even be expressed in X10.
However, the value of keyed.k can be retrieved, using keyed.key(). The type of kk cannot be expressed in Snooper, because it refers to a private field of keyed. However, the compiler's internal representation is not bound by the rules of privacy, and can track the fact that kk is the same as keyed.k. So, the call keyed.secret(kk) succeeds.

```
class Keyed {
    private val k : Int;
    public def this(k : Int) {
        this.k = k;
    }
    public def secret(q:Int){q==this.k} = 11;
    public def key():Int{self==this.k} = this.k;
}
class Snooper {
    public static def main(argv:Array[String](1)) {
        val keyed : Keyed = new Keyed(8);
        //ERROR: keyed.secret(keyed.k);
        //ERROR: keyed.secret(8);
        val kk = keyed.key();
        keyed.secret(kk);
    }
}
```

Note: Constraints may not contain casts. In particular, comparisons of values of incompatible types are not allowed. If $i$ : Int, then $i==0$ is allowed as a constraint, but $i==0 L$ is an error, and $i$ as $L o n g==0 L$ is outside of the constraint language.

## Semantics of constraints

The logic of constraints is designed to allow a common and important X10 idiom:

```
class Thing(p:Int){}
static def example(){
```

```
    var x : Thing{x.p==3} = null;
}
```

That is, null must be an instance of Thing\{x.p==3\}. Of course, it cannot be the case that null. $p==3$ - nor can it equal anything else. When evaluated at runtime, null.p must throw a NullPointerException rather than returning any value at all.

So, X10's logic of constraints - unlike the logic of runtime - allows $\mathrm{x}=$ null to satisfy $\mathrm{x} . \mathrm{p}==3$. Building this logic requires a few definitions.

The property graph, at an instant in an X10 execution, is the graph whose nodes are all objects in existence at that instance, plus null, with an edge from $x$ to $y$ if $x$ is an object with a property whose value is $y$. The rules for constructors guarantee that property graphs are acyclic, which is crucial for decidability.

As is standard in mathematical logic, we introduce the concept of a valuation $v$, which is a mapping from variable names to their values - in our case, nodes of an X10 property graph. A valuation $v$ can be extended to values to all constraint formulas. The crucial definitions are:

```
\(v(\) a.b....l.m == n.o....y.z) \(=\)
    a=null \(\vee\) a.b=null \(\vee \ldots\)...b....l=null
    \(\vee\) n=null \(\vee\) n.o=null \(\vee \ldots\) n.o.... \(y=n u l l\)
    \(\vee v(\mathrm{a}) . \mathrm{b} . \ldots \mathrm{l} . \mathrm{m}=v(\mathrm{n}) . \mathrm{o} \ldots \mathrm{y}\).
\(v(\) a.b....l.m != n.o....y.z) \(=\)
    a=null \(\vee\) a.b=null \(\vee \ldots\)....b....l=null
    \(\vee\) n=null \(\vee\) n.o=null \(\vee \ldots\) n.o....y=null
    \(\vee v(\mathrm{a}) . \mathrm{b} . . . . \mathrm{l} . \mathrm{m} \neq v(\mathrm{n}) . \mathrm{o} . . . \mathrm{y}\).
```

For example, $v(\mathrm{a} \cdot \mathrm{b}==1)$ is true if either $v(\mathrm{a})=$ null or if $v(\mathrm{a})$ is a container whose b-field is equal to 1 . While such a valuation is perfectly well-defined, it has properties that need to be understood in light of the fact that $==$ is not mathematical equality. ${ }^{7}$ Given any valuation in which $v(\mathrm{a})=$ null, both $v(\mathrm{a} . \mathrm{b}==1 \quad \& \&$ $\mathrm{a} \cdot \mathrm{b}==2)$ and $v(\mathrm{a} . \mathrm{b}==1 \quad \& \& \mathrm{a} \cdot \mathrm{b}!=1)$ are true. This does not contradict logic and mathematics, it does not imply that $v$ (false) is true (it's not), and it does not assert that in X10 there is a number which is both 1 and 2. It simply reflects the fact

[^9]that, while $==$ is similar to mathematical equality in many respects, it is ultimately a different operation, and in constraints it is given a null-safe interpretation.

From this definition of valuation, we define entailment in the standard way. Given constraints cand d, we define centails d, sometimes written $c \vDash d$, if for all valuations $v$ such that $v(\mathrm{c})$ is true, $v(\mathrm{~d})$ is also true.
Limitation: Although nearly-contradictory conjunctions like x.a==1 \& $\quad x . a==2$ entail $x==n u l l$, X10's constraint solver does not currently use this rule. If you want $x==n u l l$, write $x==n u l l$.
Subtyping of constrained types is defined in terms of entailment. $\mathrm{S}[\mathrm{S} 1, \ldots$,
$\mathrm{Sm}]\{\mathrm{c}\}$ is a subtype of $\mathrm{T}[\mathrm{T} 1, \ldots, \mathrm{Tn}]\{\mathrm{d}\}$ if $\mathrm{S}[\mathrm{S} 1, \ldots, \mathrm{Sm}]$ is a subtype of $\mathrm{T}[\mathrm{T} 1, \ldots, \mathrm{Tn}]$ and c entails d.

For examples of constraints and entailment, see (\$4.5.1)

### 4.5.3 Constraint solver: incompleteness and approximation

The constraint solver is sound in that if it claims that $c$ entails $d$ then in fact it is the case that every valuation that satisfies c satisfies d .
Limitation: X10's constraint solver is incomplete. There are situations in which c entails d but the solver cannot establish it. For instance it cannot establish that a $!=b$ \&\& $a \quad!=c \& \& b \quad!=c$ entails false if $a, b$, and $c$ are of type Boolean. Similarly, although $\mathrm{a} \cdot \mathrm{b}==1$ \&\& $\mathrm{a} \cdot \mathrm{b}==2$ entails $\mathrm{a}==$ null, the constraint solver does not deduce this fact.

### 4.5.4 Acyclicity of Properties

To ensure that typechecking is decidable, X10 requires that the graph whose nodes are types, with edges from types to the properties of those types, be acyclic. This is often stated as "properties are acyclic." That is, given a container type T, T cannnot have a property of type T , nor a property which has a property of type T , nor a property which has a property with a property of type T, etc.
Example: The following is forbidden by the acyclicity requirement, as ERRORList [T] would have a property, tail, which is also an ERRORList [T].

$$
\text { class ERRORList[T] (head:T, tail: ERRORList[T]) \{\} }
$$

Without this restriction, typechecking becomes undecidable.

### 4.5.5 Limitation: Generics and Constraints at Runtime

The X10 runtime does not maintain a representation of constraints as part of the runtime representation of a type. While there various approaches which could be used, they would require far higher prices in space or time than they are worth. A representation suitable for one use of types (such as keeping a closure for testing membership in the type) is unsuitable for others (such as determining if one type is a subtype of another). Furthermore, it would be necessary to compute entailment at runtime, which is currently impractical.

Rather than pay the runtime costs for keeping and manipulating constraints (which can be considerable), X10 omits them. However, this renders certain type checks uncertain: X10 needs some information at runtime, but does not have it. In particular, casts to instances of generic types, and to type variables, are potentially troublesome.

Example: The following code illustrates the dangers of casting to generic types. It constructs an array a of Int \{self==3\}'s - integers which are statically known to be 3. The only number that can be stored into a is 3. Then it tricks the ocmpiler into thinking that it is an array of Int, without restriction on the elements, giving it the name b at that type. The cast aa as Array[Int] is a cast to an instance of a generic type, which is the problem.
But, itc an store any Int into the elements of b , thereby violating the invariant that all the elements of the array are 3. This could lead to program failures, as illustrated by the failing assertion.

With the -VERBOSE compiler option, X10 prints a warning about the declaration of b .

```
val a = new Array[Int{self==3}](0..10, 3);
// a(0) = 1; would be illegal
a(0) = 3; // LEGAL
val aa = a as Any;
val b = aa as Array[Int](1); // WARNED with -VERBOSE
b(0) = 1;
val x : Int{self==3} = a(0);
assert x == 3 : "This fails at runtime.";
```

Since constraints are not preserved at runtime, instanceof and as cannot pay attention to them. When types are used generically, they may not behave as one
would expect were one to imagine that their constraints were kept. Specifically, constraints at runtime are, in effect, simply replaced by true.
Example: The following code defines generic methods inst and cast, which look like generic versions of instanceof and as. The example() code shows that inst and cast behave quite differently from instanceof and as, due to the loss of constraint information.
The first section of asserts shows the behavior of instanceof and at. We have a value pea, such that pea. $\mathrm{p}==1$. It behaves as if its p field were 1: it answers true to self. $\mathrm{p}==1$, and false to self. $\mathrm{p}==2$. This is entirely as desired.
The following section of assert and val statements does the analogous thing, but using the generic methods inst and cast rather than the built-in operations instanceof and cast. pea answers true to inst checks concerning both Pea $\{\mathrm{p}==1\}$ and Pea $\{\mathrm{p}==2\}$, and can be cast () into both these types. This behavior is not what one would expect from runtime types that keep constraint information. It is, however, precisely what one would expect from runtime types that have their constraints replaced by true.
The cast2 line shows how to use this fact to violate the constraint system at runtime. This dynamic cast produces an object of type Pea\{p==2\} for which $\mathrm{p}!=2$.
Note that the -VERBOSE compiler flag will produce a warning that cast is unsound.

```
class Generic {
    public static def inst[T](x:Any):Boolean = x instanceof T;
    // With -VERBOSE, the following line gets a warning
    public static def cast[T](x:Any):T = x as T;
}
class Pea(p:Int) {}
class Example{
    static def example() {
        val pea : Pea = new Pea(1);
        // These are what you'd expect:
        assert (pea instanceof Pea{p==1});
        assert (pea as Pea{p==1}).p == 1;
        assert ! (pea instanceof Pea{p==2});
        // 'val x = pea as Pea{p==2};'
        // throws a FailedDynamicCheckException.
```

```
        // But the genericized versions don't do the same thing:
        assert Generic.inst[Pea{p==1}](pea);
        assert Generic.inst[Pea{p==2}](pea);
        // No exception here!
        val cast1: Pea{p==1} = Generic.cast[Pea{p==1}](pea);
        val cast2: Pea{p==2} = Generic.cast[Pea{p==2}](pea);
        assert cast2.p == 1;
        assert !(cast2 instanceof Pea{p==2});
    }
}
```

While in some cases it would be possible to keep constraints around at runtime and operate efficiently on them, in other cases it would not.

### 4.6 Function types

$$
\text { FunctionType }::=\text { TypeParams? (FormalList }{ }^{?} \text { ) Guard }{ }^{?} \text { => Type }
$$

For every sequence of types $\mathrm{T} 1, \ldots, \mathrm{Tn}, \mathrm{T}$, and n distinct variables $\mathrm{x} 1, \ldots$, xn and constraint c , the expression ( $\mathrm{x} 1: \mathrm{T} 1, \ldots, \mathrm{xn}: \mathrm{Tn}$ ) $\{\mathrm{c}\}=>\mathrm{T}$ is a function type. It stands for the set of all functions $f$ which can be applied to a list of values ( $\mathrm{v} 1, \ldots, \mathrm{vn}$ ) provided that the constraint $\mathrm{c}[\mathrm{v} 1, \ldots, \mathrm{vn}, \mathrm{p} / \mathrm{x} 1, \ldots, \mathrm{xn}]$ is true, and which returns a value of type $T[v 1, \ldots v n / x 1, \ldots, x n]$. When $c$ is true, the clause $\{c\}$ can be omitted. When $\mathrm{x} 1, \ldots, \mathrm{xn}$ do not occur in c or T , they can be omitted. Thus the type ( $\mathrm{T} 1, \ldots, \mathrm{Tn}$ ) $=>\mathrm{T}$ is actually shorthand for ( $\mathrm{x} 1: \mathrm{T} 1, \ldots, \mathrm{xn}: \mathrm{Tn}$ ) \{true\}=>T, for some variables $\mathrm{x} 1, \ldots, \mathrm{xn}$.

Limitation: Constraints on closures are not supported. They parse, but are not checked.

X10 functions, like mathematical functions, take some arguments and produce a result. X10 functions, like other X10 code, can change mutable state and throw exceptions. Closures ( $\$ 10$ ) are of function type - and so are arrays.

Example: Typical functions are the reciprocal function:

$$
\text { val recip }=(x \text { : Double) }=>1 / x \text {; }
$$

and a function which increments element i of an array r , or throws an exception if there is no such element, where, for the sake of example, we constrain the type of i to avoid one of the many integers which are not possible subscripts:

```
val inc = (r:Array[Int](1), i: Int{i != r.size}) => {
    if (i < 0 || i >= r.size) throw new DoomExn();
    r(i)++;
};
```

In general, a function type needs to list the types $\mathrm{T}_{i}$ of all the formal parameters, and their distinct names $\mathbf{x}_{i}$ in case other types refer to them; a constraint $\mathbf{c}$ on the function as a whole; a return type $T$.

$$
\left(\mathrm{x}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{x}_{n}: \mathrm{T}_{n}\right)\{\mathrm{c}\} \Rightarrow \mathrm{T}
$$

The names of the formal parameters, $\mathrm{x}_{i}$, are bound in the type. As usual with bound variables, they can be given new names without changing the meaning of the type. In particular, the names of formals in a function type do not need to be the same as the names in the function in a value of that type.
Example: The type of id uses the bound variable x. The type of ie uses the bound variable z , but is otherwise identical to that of id. The two types are the same, as shown by the assignment of id to ie. Also, id's type uses x , and id's value uses y.

```
val id : (x:Int) => Int{self==x}
    = (y:Int) => y;
val ie : (z:Int) => Int{self==z}
    = id;
```

Limitation: Function types differing only in the names of bound variables may wind up being considered different in X10 v2.2, especially if the variables appear in constraints.
The formal parameter names are in scope from the point of definition to the end of the function type-they may be used in the types of other formal parameters and in the return type. Value parameters names may be omitted if they are not used; the type of the reciprocal function can be written as (Double)=>Double.
A function type is covariant in its result type and contravariant in each of its argument types. That is, let $\mathrm{S} 1, \ldots, \mathrm{Sn}, \mathrm{S}, \mathrm{T} 1, \ldots \mathrm{Tn}, \mathrm{T}$ be any types satisfying $\mathrm{Si}<$ : Ti and $\mathrm{S}<$ : T. Then ( $\mathrm{x} 1: \mathrm{T} 1, \ldots, \mathrm{xn}: \mathrm{Tn}$ ) $\{\mathrm{c}\}=>\mathrm{S}$ is a subtype of ( $\mathrm{x} 1: \mathrm{S} 1, \ldots, \mathrm{xn}: \mathrm{Sn}$ ) $\{\mathrm{c}\}=>\mathrm{T}$.

A class or struct definition may use a function type

$$
F=(x 1: T 1, \ldots, x n: T n)\{c\}=>T
$$

in its implements clause; this is equivalent to implementing an interface requiring the single operator

```
public operator this(x1:T1,\ldots,.,xn:Tn){c}:T
```

Similarly, an interface definition may specify a function type F in its extends clause. Values of a class or struct implementing F can be used as functions of type F in all ways. In particular, applying one to suitable arguments calls the apply method.

Limitation: A class or struct may not implement two different instantiations of a generic interface. In particular, a class or struct can implement only one function type.
A function type F is not a class type in that it does not extend any type or implement any interfaces, or support equality tests. F may be implemented, but not extended, by a class or function type. Nor is it a struct type, for it has no predefined notion of equality.

### 4.7 Default Values

Some types have default values, and some do not. Default values are used in situations where variables can legitimately be used without having been initialized; types without default values cannot be used in such situations. For example, a field of an object var x:T can be left uninitialized if T has a default value; it cannot be if T does not. Similarly, a transient ( $\$ 8.2 .3$ ) field transient val x : T is only allowed if T has a default value.
Default values, or lack of them, is defined thus:

- The fundamental numeric types (Int, UInt, Long, ULong, Short, UShort, Byte, UByte, Float, Double) all have default value 0 .
- Boolean has default value false.
- Char has default value ' $\backslash 0$ '.
- If every field of a struct type $T$ has a default value, then $T$ has a default value. If any field of T has no default value, then T does not. ( $\$ 9.7$ )
- A function type has a default value of null.
- A class type has a default value of null.
- The constrained type $T\{c\}$ has the same default value as $T$ if that default value satisfies $c$. If the default value of $T$ doesn't satisfy $c$, then $T\{c\}$ has no default value.

Example: var $\mathrm{x}: \operatorname{Int}\{\mathrm{x}!=4\}$ has default value 0, which is allowed because (0) != 4 satisfies the constraint on x . var $\mathrm{y}: \operatorname{Int}\{\mathrm{y}==4\}$ has no default value, because 0 does not satisfy $\mathrm{y}==4$. The fact that $\operatorname{Int}\{\mathrm{y}==4\}$ has precisely one value, viz. 4, doesn't matter; the only candidate for its default value, as for any subtype of Int, is 0 . y must be initialized before it is used.
The predicate T haszero tells if the type T has a default value. haszero may be used in constraints.
Example: The following code defines a sort of cell holding a single value of type T. The cell is initially empty - that is, has T's zero value - but may be filled later.

```
class Cello[T]{T haszero} {
    public var contents : T;
    public def put(t:T) { contents = t; }
}
```

The built-in type Zero has the method get [T] () which returns the default value of type T.
Example: As a variation on a theme of Cello, we define a class Cell1[T] which can be initialized with a value of an arbitrary type T , or, if T has a default value, can be created with the default value. Note that T haszero is a constraint on one of the constructors, not the whole type:

```
class Cell1[T] {
    public var contents: T;
    def this(t:T) { contents = t; }
    def this(){T haszero} { contents = Zero.get[T](); }
    public def put(t:T) {contents = t;}
}
```


### 4.8 Annotated types

Any X10 type may be annotated with zero or more user-defined type annotations ( 8 17).

Annotations are defined as (constrained) interface types and are processed by compiler plugins, which may interpret the annotation symbolically.

A type T is annotated by interface types $\mathrm{A}_{1}, \ldots, \mathrm{~A}_{n}$ using the syntax ${@ \mathrm{~A}_{1}} \ldots @ \mathrm{~A}_{n}$ T.

### 4.9 Subtyping and type equivalence

Intuitively, type $T_{1}$ is a subtype of type $T_{2}$, written $T_{1}<$ : $T_{2}$, if every instance of $\mathrm{T}_{1}$ is also an instance of $\mathrm{T}_{2}$. For example, Child is a subtype of Person (assuming a suitably defined class hierarchy): every child is a person. Similarly, Int \{self $!=0\}$ is a subtype of Int - every non-zero integer is an integer.
This section formalizes the concept of subtyping. Subtyping of types depends on a type context, viz.. a set of constraints on type parameters and variables that occur in the type. For example:

```
class ConsTy[T,U] {
    def upcast(t:T){T <: U} :U = t;
}
```

Inside upcast, $T$ is constrained to be a subtype of $U$, and so $T<: U$ is true, and $t$ can be treated as a value of type $U$. Outside of upcast, there is no reason to expect any relationship between them, and T < : U may be false. However, subtyping of types that have no free variables does not depend on the context. Int \{self != 0\} <: Int is always true.

Limitation: Subtyping of type variables does not work under all circumstances in the X10 2.2 implementation.

- Reflexivity: Every type T is a subtype of itself: T < : T.
- Transitivity: If $T<: U$ and $U<: V$, then $T<: V$.
- Direct Subclassing: Let $\vec{X}$ be a (possibly empty) vector of type variables, and $\vec{Y}, \vec{Y}_{i}$ be vectors of type terms over $\vec{X}$. Let $\vec{T}$ be an instantiation of $\vec{X}$, and $\vec{U}, \vec{U}_{i}$ the corresponding instantiation of $\vec{Y}, \vec{Y}_{i}$. Let c be a constraint, and $c^{\prime}$ be the corresponding instantiation. We elide properties, and interpret empty vectors as absence of the relevant clauses. Suppose that C is declared by one of the forms:

1. class $\mathrm{C}[\vec{X}]\{\mathrm{c}\}$ extends $\mathrm{D}[\vec{Y}]\{\mathrm{d}\}$ implements $\mathrm{I}_{1}\left[\vec{Y}_{1}\right]\left\{\mathbf{i}_{1}\right\}, \ldots, \mathrm{I}_{n}\left[\vec{Y}_{n}\right]\left\{\mathbf{i}_{n}\right\}\{$
2. interface $\mathrm{C}[\vec{X}]\{\mathrm{c}\}$ extends $\mathrm{I}_{1}\left[\vec{Y}_{1}\right]\left\{\mathbf{i}_{1}\right\}, \ldots, \mathrm{I}_{n}\left[\vec{Y}_{n}\right]\left\{\mathbf{i}_{n}\right\}\{$
3. struct $C[\vec{X}]\{\mathrm{c}\}$ implements $\mathrm{I}_{1}\left[\vec{Y}_{1}\right]\left\{\mathbf{i}_{1}\right\}, \ldots, \mathrm{I}_{n}\left[\vec{Y}_{n}\right]\left\{\mathbf{i}_{n}\right\}\{$

Then:

1. $\mathrm{C}[\vec{T}]<$ : $\mathrm{D}[\vec{U}]\{\mathrm{d}\}$ for a class
2. $\mathrm{C}[\vec{T}]<: \mathrm{I}_{i}\left[\overrightarrow{U_{i}}\right]\left\{\mathbf{i}_{i}\right\}$ for all cases.
3. $\mathrm{C}[\vec{T}]<$ : $\mathrm{C}[\vec{T}]\left\{\mathrm{C}^{\prime}\right\}$ for all cases.

## - Function types:

$$
\left(\mathrm{x}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{x}_{n}: \mathrm{T}_{n}\right)\{\mathrm{c}\} \Rightarrow \mathrm{T}
$$

is a subtype of

$$
\left(\mathrm{x}_{1}^{\prime}: \mathrm{T}_{1}^{\prime}, \ldots, \mathrm{x}_{n}^{\prime}: \mathrm{T}_{n}^{\prime}\right)\left\{\mathrm{c}^{\prime}\right\} \Rightarrow \mathrm{T}^{\prime}
$$

if:

1. Each $\mathrm{T}_{i}<: \mathrm{T}_{i}^{\prime}$;
2. $\mathrm{c}\left[\mathrm{x}_{1}^{\prime}, \ldots, \mathrm{x}_{n}^{\prime} / \mathrm{x}_{1}, \ldots, \mathrm{x}_{n}\right]$ entails $\mathrm{c}^{\prime}$;
3. $\mathrm{T}^{\prime}<\mathrm{T}$;

- Constrained types: $T\{c\}$ is a subtype of $T\{d\}$ if $c$ entails $d$.
- Any: Every type T is a subtype of x 10. lang. Any.
- Type Variables: Inside the scope of a constraint C which entails $\mathrm{A}<$ : B, we have A <: B. e.g., upcast above.

Two types are equivalent, $\mathrm{T}==\mathrm{U}$, if $\mathrm{T}<\mathrm{Z} \mathrm{U}$ and $\mathrm{U}<$ : T .

### 4.10 Common ancestors of types

There are several situations where X10 must find a type T that describes values of two or more different types. This arises when X10 is trying to find a good type for:

- Conditional expressions, like test ? 0 : "non-zero" or even test ? 0 : 1;
- Array construction, like [0, "non-zero"] and [0,1];
- Functions with multiple returns, like

```
def f(a:Int) {
    if (a == 0) return 0;
    else return "non-zero";
}
```

In some cases, there is a unique best type describing the expression. For example, if $B$ and $C$ are direct subclasses of $A$, pick will have return type $A$ :

```
static def pick(t:Boolean, b:B, c:C) = t ? b : c;
```

However, in many common cases, there is no unique best type describing the expression. For example, consider the expression $E$
b ? 0 : 1 // Call this expression $E$
The best type of 0 is $\operatorname{Int}\{\operatorname{self} f=0\}$, and the best type of 1 is $\operatorname{Int}\{\operatorname{self} f=1\}$. Certainly $E$ could be given the type Int, or even Any, and that would describe all possible results. However, we actually know more. Int $\{\operatorname{self}!=2\}$ is a better description of the type of $E$-certainly the result of $E$ can never be 2 . Int \{self
$!=2$, self $!=3\}$ is an even better description; $E$ can't be 3 either. We can continue this process forever, adding integers which $E$ will definitely not return and getting better and better approximations. (If the constraint sublanguage had ||, we could give it the type $\operatorname{Int}\{\operatorname{self}==0| | \operatorname{self}==1\}$, which would be nearly perfect. But $\| \mid$ makes typechecking far more expensive, so it is excluded.) No X10 type is the best description of $E$; there is always a better one.
Similarly, consider two unrelated interfaces:

```
interface I1 {}
interface I2 {}
class A implements I1, I2 {}
class B implements I1, I2 {}
class C {
    static def example(t:Boolean, a:A, b:B) = t ? a : b;
}
```

I1 and I2 are both perfectly good descriptions of $t$ ? a : b, but neither one is better than the other, and there is no single X10 type which is better than both. (Some languages have conjunctive types, and could say that the return type of example was I1 \&\& I2. This, too, complicates typechecking.)
So, when confronted with expressions like this, X10 computes some satisfactory type for the expression, but not necessarily the best type. X10 provides certain guarantees about the common type $\mathrm{V}\{\mathrm{v}\}$ computed for $\mathrm{T}\{\mathrm{t}\}$ and $\mathrm{U}\{\mathrm{u}\}$ :

- If $T\{t\}==U\{u\}$, then $V\{v\}==T\{t\}==U\{u\}$. So, if X10's algorithm produces an utterly untenable type for a ? b : c, and you want the result to have type $T\{t\}$, you can (in the worst case) rewrite it to

$$
\mathrm{a} \text { ? } \mathrm{b} \text { as } \mathrm{T}\{\mathrm{t}\}: \mathrm{c} \text { as } \mathrm{T}\{\mathrm{t}\}
$$

- If $T==\mathrm{U}$, then $\mathrm{V}==\mathrm{T}==\mathrm{U}$. For example, X 10 will compute the type of b ? 0 : 1 as $\operatorname{Int}\{\mathrm{c}\}$ for some constraint c-perhaps simply picking Int \{true\}, viz., Int.
- X10 preserves place information about GlobalRefs, because it is so important. If both t and u entail self.home==p, then v will also entail self.home==p.
- X10 similarly preserves nullity information. If $t$ and $u$ both entail $x==$ null or x ! = null for some variable x , then v will also entail it as well.
- The computed upper bound of function types with the same argument types is found by computing the upper bound of the result types. If $\mathrm{T}=\left(\mathrm{T}_{1}\right.$, $\left.\ldots, \mathrm{T}_{n}\right)=>\mathrm{T}^{\prime}$ and $\mathrm{U}=\left(\mathrm{T}_{1}, \ldots, \mathrm{~T}_{n}\right)=>\mathrm{U}^{\prime}$, and $\mathrm{V}^{\prime}$ is the computed upper bound of $T$ ' and $U$ ', then the computed upper bound of $T$ and $U$ is $\mathrm{U}=\left(\mathrm{T}_{1}, \ldots, \mathrm{~T}_{n}\right)=>\mathrm{V}^{\prime}$. (But, if the argument types are different, the computed upper bound may be Any.)


### 4.11 Fundamental types

Certain types are used in fundamental ways by X10.

### 4.11.1 The interface Any

It is quite convenient to have a type which all values are instances of; that is, a supertype of all types ${ }^{8} \mathrm{X} 10$ 's universal supertype is the interface Any.

```
package x10.lang;
public interface Any {
    def toString():String;
    def typeName():String;
    def equals(Any):Boolean;
    def hashCode():Int;
}
```

Any provides a handful of essential methods that make sense and are useful for everything. a.toString() produces a string representation of a, and a.typeName() the string representation of its type; both are useful for debugging. a.equals (b) is the programmer-overridable equality test, and a.hashCode() an integer useful for hashing.

### 4.11.2 The class Object

The class $\times 10$. lang. Object is the supertype of all classes. A variable of this type can hold a reference to any object. Object implements Any.

### 4.12 Type inference

X10 v2.2 supports limited local type inference, permitting certain variable types and return types to be elided. It is a static error if an omitted type cannot be inferred or uniquely determined. Type inference does not consider coercions.

[^10]
### 4.12.1 Variable declarations

The type of a val variable declaration can be omitted if the declaration has an initializer. The inferred type of the variable is the computed type of the initializer. For example, val seven $=7$; is identical to
val seven: Int $\{$ self==7\} = 7;
Note that type inference gives the most precise X10 type, which might be more specific than the type that a programmer would write.
Limitation: At the moment, var declarations may not have their types elided in this way.

### 4.12.2 Return types

The return type of a method can be omitted if the method has a body (i.e., is not abstract or native). The inferred return type is the computed type of the body. In the following example, the return type inferred for isTriangle is Boolean\{self==false\}

```
class Shape {
    def isTriangle() = false;
}
```

Note that, as with other type inference, methods are given the most specific type. In many cases, this interferes with subtyping. For example, if one tried to write:

```
class Triangle extends Shape {
    def isTriangle() = true;
}
```

the compiler would reject this program for attempting to override isTriangle() by a method with the wrong type, viz., Boolean\{self==true\}. In this case, supply the type that is actually intended for isTriangle:

```
def isTriangle() : Boolean =false;
```

The return type of a closure can be omitted. The inferred return type is the computed type of the body.

The return type of a constructor can be omitted if the constructor has a body. The inferred return type is the enclosing class type with properties bound to the
arguments in the constructor's property statement, if any, or to the unconstrained class type. For example, the Spot class has two constructors, the first of which has inferred return type Spot $\{x==0\}$ and the second of which has inferred return type $\operatorname{Spot}\{\mathrm{x}==\mathrm{xx}\}$.

```
class Spot(x:Int) {
    def this() {property(0);}
    def this(xx: Int) { property(xx); }
}
```

A method or closure that has expression-free return statements (return; rather than return e; ) is said to return void. void is not a type; there are no void values, nor can void be used as the argument of a generic type. However, void takes the syntactic place of a type in a few contexts. A method returning void can be specified by def m() : void, and similarly for a closure:

```
def m():void {return;}
val f : () => void = () => {return;};
```

By a convenient abuse of language, void is sometimes lumped in with types; e.g., we may say "return type of a method" rather than the formally correct but rather more awkward "return type of a method, or void". Despite this informal usage, void is not a type. For example, given

```
static def eval[T] (f:()=>T):T = f();
```

The call eval[void] (f) does not typecheck; void is not a type and thus cannot be used as a type argument. There is no way in X10 to write a generic function which works with both functions which return a value and functions which do not. In most cases, functions which have no sensible return value can be provided with a dummy return value.

X10 preserves known information when computing return types. A constraint on a method induces a corresponding constraint on its return type.
Example: In the following code, the type inferred for x is Numb\{self. $\mathrm{p}==\mathrm{n}$, $\mathrm{n}!=0$, self!=null\}. In particular, the conjunct $\mathrm{n}!=0$ is preserved from the cast of n to $\operatorname{Int}\{\mathrm{self}!=0$ \}.

```
class Numb (p:Int) \{
    static def dup(n:Int) \{n != 0\} = new Numb(n);
    public static def example(n:Int) \{
```

```
        val x = dup(n as Int{self != 0});
        val y : Numb{self.p==n, n!=0, self!=null} = x;
    }
}
```


### 4.12.3 Inferring Type Arguments

A call to a polymorphic method may omit the explicit type arguments. X10 will compute a type from the types of the actual arguments.
(As an exception of sorts, it is an error if the method call provides no information about a type parameter that must be inferred. For example, given the method definition $\operatorname{def} m[T]$ () $\{\ldots\}$, an invocation $m()$ is considered a static error. The compiler has no idea what T the programmer intends.)

Example: Consider the following method, which chooses one of its arguments. (A more sophisticated one might sometimes choose the second argument, but that does not matter for the sake of this example.)

```
static def choose[T](a: T, b: T): T = a;
```

The type argument T can always be supplied: choose[Int] $(1,2)$ picks an integer, and choose [Any] (1, "yes") picks a value that might be an integer or a string. However, the type argument can be elided. Suppose that Sub <: Super; then the following compiles:

```
static def choose[T](a: T, b: T): T = a;
static val j : Any = choose("string", 1);
static val k : Super = choose(new Sub(), new Super());
```

The type parameter doesn't need to be the type of a variable. It can be found inside of the type of a variable; X10 can extract it.
Example: The first method below returns the first element of a one-dimensional array. The type parameter T represents the type of the array's elements. There is no parameter of type T. There is one of type Array[T]\{c\}. When doing type inference, X10 strips off the constraint \{c\} and the Array [...] type to get at the T inside.

```
static def first[T](x:Array[T](1)) = x(0);
static def example() {
```

```
    val ss <: Array[String] = ["X10", "Scala", "Thorn"];
    val s1 = first(ss);
    assert s1.equals("X10");
}
```


## Sketch of X10 Type Inference for Method Calls

When the X10 compiler sees a method call
$\mathrm{a} . \mathrm{m}\left(\mathrm{b}_{1}, \ldots, \mathrm{~b}_{n}\right)$
and attempts to infer type parameters to see if it could be a use of a method
$\operatorname{def} \mathrm{m}\left[\mathrm{X}_{1}, \ldots, \mathrm{X}_{t}\right]\left(\mathrm{y}_{1}: \mathrm{S}_{1}, \ldots, \mathrm{y}_{n}: \mathrm{S}_{n}\right)$,
it reasons as follows.
Let
$\mathrm{T}_{i}$ be the type of $\mathrm{b}_{i}$
Then, X 10 is seeking a set $B$ of type bindings

$$
B=\left\{\mathbf{x}_{1}=\mathrm{U}_{1}, \ldots, \mathrm{X}_{t}=\mathrm{U}_{t}\right\}
$$

such that $\mathrm{T}_{i}<$ : $\mathrm{S}_{i}^{*}$ for $1 \leq i \leq n$, where $\mathrm{S}^{*}$ is S with each type variable $\mathrm{X}_{j}$ replaced by the corresponding $\mathrm{U}_{j}$. If it can find such a $B$, it has a usable choice of type arguments and can do the type inference. If it cannot find $B$, then it cannot do type inference. (Note that X10's type inference algorithm is incomplete - there may be such a $B$ that X10 cannot find. If this occurs in your program, you will have to write down the type arguments explicitly.)
Let $B_{0}$ be the set $\left\{T_{i}<\right.$ : $\left.S_{i} \mid 1 \leq i \leq n\right\}$. Let $B_{n+1}$ be $B_{n}$ with one element $F<: G$ or $F=G$ removed, and $\operatorname{Strip}(F<: G)$ or $\operatorname{Strip}(F=G)$, where $\operatorname{Strip}$ is defined below, added. Repeat this until $B_{n}$ consists entirely of comparisons with type variables (viz., $\mathrm{Y}_{j}=\mathrm{U}, \mathrm{Y}_{j}<: \mathrm{U}$, and $\mathrm{Y}_{j}$ :> U ), or until some $n$ exceeds a predefined compiler limit.
The candidate inferred types may be read off of $B_{n}$. The guessed binding for $\mathrm{X}_{j}$ is:

- If there is an equality $\mathrm{X}_{j}=\mathrm{W}$ in $B_{n}$, then guess the binding $\mathrm{X}_{j}=\mathrm{W}$. Note that there may be several such equalities with different choices of $W$; pick any
one. If the chosen binding does not equal the others, the candidate binding will be rejected later and type inference will fail.
- Otherwise, if there is one or more upper bounds $\mathbf{X}_{j}<: \mathrm{V}_{k}$ in $B_{n}$, guess the binding $\mathrm{X}_{j}=\mathrm{V}_{+}$, where $\mathrm{V}_{+}$is the computed lower bound of all the $\mathrm{V}_{k}$ 's.
- Otherwise, if there is one or more lower bounds $\mathrm{R}_{k}<$ : $\mathrm{X}_{j}$, guess that $\mathrm{X}_{j}=$ $\mathrm{R}_{+}$, where $\mathrm{R}_{+}$is the computed upper bound of all the $\mathrm{R}_{k}$ 's.

If this does not yield a binding for some variable $\mathrm{X}_{j}$, then type inference fails. Furthermore, if every variable $X_{j}$ is given a binding $U_{j}$, but the bindings do not work - that is, if a.m $\left[\mathrm{U}_{1}, \ldots, \mathrm{U}_{t}\right]\left(\mathrm{b}_{1}, \ldots, \mathrm{~b}_{n}\right)$ is not a well-typed call of the original method $\operatorname{def} m\left[\mathrm{X}_{1}, \ldots, \mathrm{X}_{t}\right]\left(\mathrm{y}_{1}: \mathrm{S}_{1}, \ldots, \mathrm{y}_{n}: \mathrm{S}_{n}\right)$ - then type inference also fails.

Computation of the Replacement Elements Given a type relation $r$ of the form $F<: G$ or $F=G$, we compute the set $\operatorname{Strip}(r)$ of replacement constraints. There are a number of cases; we present only the interesting ones.

- If $F$ has the form $F^{\prime}\{c\}$, then $\operatorname{Strip}(r)$ is defined to be $F^{\prime}=G$ if $r$ is an equality, or $F^{\prime}<$ : $G$ if $r$ is a subtyping. That is, we erase type constraints. Validity is not an issue at this point in the algorithm, as we check at the end that the result is valid. Note that, if the equation had the form $\mathrm{Z}\{\mathrm{c}\}=\mathrm{A}$, it could be solved by either $\mathrm{Z}=\mathrm{A}$ or by $\mathrm{Z}=\mathrm{A}\{\mathrm{c}\}$. By dropping constraints in this rule, we choose the former solution, which tends to give more general types in results.
- Similarly, we drop constraints on $G$ as well.
- If $F$ has the form $\mathrm{K}\left[\mathrm{F}_{1}, \ldots, \mathrm{~F}_{k}\right]$ and $G$ has the form $\mathrm{K}\left[\mathrm{G}_{1}, \ldots, \mathrm{G}_{k}\right]$, then $\operatorname{Strip}(r)$ has one type relation comparing each parameter of $F$ with the corresponding one of $G$ :

$$
\operatorname{Strip}(r)=\left\{F_{l}=G_{l} \mid 1 \leq l \leq k\right\}
$$

For example, the constraint List $[\mathrm{X}]=$ List [Y] induces the constraint $\mathrm{X}=\mathrm{Y}$. List $[\mathrm{X}]<$ : List [Y] also induces the same constraint. The only way that List $[\mathrm{X}]$ could be a subtype of List [ Y$]$ in X 10 is if $\mathrm{X}=\mathrm{Y}$. List of different types are incomparable. .9

[^11]- Other cases are fairly routine. E.g., if $F$ is a type-defined abbreviation, it is expanded.

Example: Consider the program:

```
import x10.util.*;
class Cl[C1, C2, C3]{}
class Example {
    static def me[X1, X2](Cl[Int, X1, X2]) =
            new Cl[X1, X2, Point]();
    static def example() {
        val a = new Cl[Int, Boolean, String]();
        val b : Cl[Boolean, String, Point]
            = me[Boolean, String](a);
        val c : Cl[Boolean, String, Point]
                        = me(a);
    }
}
```

The method call for b has explicit type parameters. The call for c infers the parameters. The computation starts with one equation, saying that the formal parameter of me has to be able to accept the actual parameter a :

Cl[Int, Boolean, String] <: Cl[Int, X1, X2]
Note that both terms are Cl of three things. This is broken into three equations:
Int = Int
which is easy to satisfy,
X1 = Boolean
which suggests a possible value for X1, and
X2 = String
which suggests a value for X 2 . All of these equations are simple enough, so the algorithm terminates.
Then, X10 confirms that the binding $\mathrm{X} 1=\mathrm{Boolean}, \mathrm{X} 2=\mathrm{String}$ actually generates a correct call, which it does.

Example: When there is no way to infer types correctly, the type inference algorithm will fail. Consider the program:

```
public class Failsome {
    static def fail[X](a:Array[X], b:Array[X]):void {}
    public static def main(argv:Array[String](1)) {
        val aint : Array[Int] = [1,2,3];
        val abool : Array[Boolean] = [true, false];
        fail(aint, abool); // THIS IS WRONG
    }
}
```

The type inference computation starts, as always, by insisting that the types of the formals to fail are capable of accepting the actuals:

$$
B_{0}=\{\operatorname{Array}[\text { Int }]<: \operatorname{Array[X],~Array[Boolean]~}<\text { : Array }[\mathrm{X}]\}
$$

Arbitrarily picking the first relation to Strip first, we get:

$$
\left.B_{1}=\{\text { Int }=\mathrm{X}, \text { Array [Boolean }]<\text { Array }[\mathrm{X}]\right\}
$$

and then

$$
B_{2}=\{\text { Int }=\mathrm{X}, \text { Boolean }=\mathrm{X}\}
$$

(At this point it is clear to a human that $B$ is inconsistent, but the algorithm's check comes a bit later.) $B_{2}$ consists entirely of comparisons with type variables, so the loop is over. Arbitrarily picking the first equality, it guesses the binding

$$
B=\{\mathrm{X}=\text { Int }\} .
$$

In the validation step, it checks that

```
fail[Int](aint, abool)
```

is a well-typed call to fail. Of course it is not; abool would have to be a value of type Array [Int], which it is not. So type inference fails at this point. In this case it is correct: there is no way to give a proper type to this program. ${ }^{10}$

[^12]
### 4.13 Type Dependencies

Type definitions may not be circular, in the sense that no type may be its own supertype, nor may it be a container for a supertype. This forbids interfaces like interface Loop extends Loop, and indirect self-references such as interface A extends B.C where interface B extends A. The formal definition of this is based on Java's.

An entity type is a class, interface, or struct type.
Entity type $E$ directly depends on entity type $F$ if $F$ is mentioned in the extends or implements clause of $E$, either by itself or as a qualifier within a super-entitytype name.
Example: In the following, A directly depends on B, C, D, E, and F. It does not directly depend on G .

```
class A extends B.C implements D.E, F[G] {}
```

It is an ordinary programming idiom to use A as an argument to a generic interface that A implements. For example, ComparableTo [T] describes things which can be compared to a value of type T. Saying that A implements ComparableTo[A] means that one A can be compared to another, which is reasonable and useful:

```
interface ComparableTo[T] {
    def eq(T):Boolean;
}
class A implements ComparableTo[A] {
    public def eq(other:A) = this.equals(other);
}
```

Entity type $E$ depends on entity type $F$ if either $E$ directly depends on $F$, or $E$ directly depends on an entity type that depends on $F$. That is, the relation "depends on" is the transitive closure of the relation "directly depends on".
It is a static error if any entity type $E$ depends on itself.

### 4.14 Typing of Variables and Expressions

Variable declarations, field declarations, and some other expressions introduce constraints on their types. These extra constraints represent information that is
known at the point of declaration. They are used in deductions and type inference later on - as indeed all constraints are, but the automatically-added constraints are added because they are particularly useful.
Any variable declaration of the form

```
val x : A ...
```

results in declaring $x$ to have the type $A\{s e l f==x\}$, rather than simply A. (var declarations get no such addition, because vars cannot appear in constraints.)

A field or property declaration of the form:

```
class A {
    val f : B ...
}
```

results in declaring $f$ to be of type $B\{s e l f==$ this. $f\}$. And, if $y$ has type $A\{c\}$, then the type for $\mathrm{y} . f$ has a constraint self==y.f, and, additionally, preserves the information from c.

## Example:

The following code uses a method typeIs[T] (x) to confirm, statically, that the type of x is T (or a subtype of T ).

On line (A) we confirm that the type of x has $a \mathrm{self}=\mathrm{x}$ constraint. The error line (!A) confirms that a different variable doesn't have the $\mathrm{self}=\mathrm{x}$ constraint. (B) shows the extra information carried by a field's type.
(C) shows the extra information carried by a field's type when the object's type is constrained. Note that the constraint ExtraConstraint\{self.n==8\} on the type of y has to be rewritten for $\mathrm{y} . \mathrm{f}$, since the constraint Long\{self. $\mathrm{n}==8\}$ is not correct or even well-typed. In this case, the ExtraConstraint whose n-field is 8 has the name y , so we can write the desired type with a conjunct $\mathrm{y} . \mathrm{n}==8 . \square$
Note that we use one of the extra constraints here - this reasoning requires the information that the type of y has the constraint $\mathrm{sel} \mathrm{f}==\mathrm{y}$, so X10 can infer $\mathrm{y} . \mathrm{n}==8$

[^13]from self.n==8. This sort of inference is the reason why X10 adds these constraints in the first place: without them, even the simplest data flows would be beyond the ability of the type system to detect.

```
class Extra(n:Int) {
    val f : Long;
    def this(n:Int, f:Long) { property(n); this.f = f; }
    static def typeIs[T](val x:T) {}
    public static def main(argv:Array[String](1)) {
        val x : Extra = new Extra(1,2L);
        typeIs[ Extra{self==x} ] (x); //(A)
        val nx: Extra = new Extra(1,2L);
        // ERROR: typeIs[ Extra{self==x} ] (nx); //(!A)
        typeIs[ Long{self == x.f} ] (x.f); //(B)
        val y : Extra{self.n==8} = new Extra(8, 4L);
        typeIs[ Long{self == y.f, y.n == 8}] (y.f); //(C)
    }
}
```

Once in a while, the additional information will interfere with other typechecking or type inference. In this case, use as ( $\S 11.23$ ) to erase it, using expressions like x as A .

Example: The following code creates a one-element array (\$11.26) containing x.

If the ERROR line were to be used, X10 would infer that the type of this array were Array [T], where T is the type of x - that is, Array [Extra\{sel $\mathrm{f}=\mathrm{=x}\}$ ]. [ x$]$ is an array of x's, not an array of Extras. Since Array [Extra\{self==x\}] is not a subtype of Array [Extra], the array [x] cannot be used in a place where an Array[Extra] is called for.

The expression [ x as Extra] uses a type cast to erase the automatically-added extra information about $\mathrm{x} . \mathrm{x}$ as Extra simply has type Extra, and thus [ x as Extra] is an Array [Extra] as desired.
class Extra \{
static def useArray(Array[Extra]) \{\}
public static def main(argv:Array[String](1)) \{
val x : Extra = new Extra(); //ERROR: useArray([x]);

```
        useArray([x as Extra]);
    }
}
```


### 4.15 Limitations of Strict Typing

X10's type checking provides substantial guarantees. In most cases, a program that passes the X10 type checker will not have any runtime type errors. However, there are a modest number of compromises with practicality in the type system: places where a program can pass the typechecker and still have a type error.

1. As seen in $\S 4.5 .5$, generic types do not have constraint information at runtime. This allows one to write code which violates constraints at runtime, as seen in the example in that section.
2. The library type x 10 .util. IndexedMemoryChunk provides a low-level interface to blocks of memory. A few methods on that class are not typesafe. See the API if you must.
3. Custom serialization (\$13.3.2) allows user code to construct new objects in ways that can subvert the type system.
4. Code written to use the underlying Java or C++ (§18) can break X10's guarantees.

## 5 Variables

A variable is an X10 identifier associated with a value within some context. Variable bindings have these essential properties:

- Type: What sorts of values can be bound to the identifier;
- Scope: The region of code in which the identifier is associated with the entity;
- Lifetime: The interval of time in which the identifier is associated with the entity.
- Visibility: Which parts of the program can read or manipulate the value through the variable.

X10 has many varieties of variables, used for a number of purposes.

- Class variables, also known as the static fields of a class, which hold their values for the lifetime of the class.
- Instance variables, which hold their values for the lifetime of an object;
- Array elements, which are not individually named and hold their values for the lifetime of an array;
- Formal parameters to methods, functions, and constructors, which hold their values for the duration of method (etc.) invocation;
- Local variables, which hold their values for the duration of execution of a block.
- Exception-handler parameters, which hold their values for the execution of the exception being handled.

A few other kinds of things are called variables for historical reasons; e.g., type parameters are often called type variables, despite not being variables in this sense because they do not refer to X10 values. Other named entities, such as classes and methods, are not called variables. However, all name-to-whatever bindings enjoy similar concepts of scope and visibility.
Example: In the following example, n is an instance variable, and nxt is a local variable defined within the method bump. ${ }^{1}$

```
class Counter {
    private var n : Int = 0;
    public def bump() : Int {
        val nxt = n+1;
        n = nxt;
        return nxt;
        }
}
```

Both variables have type Int (or perhaps something more specific). The scope of n is the body of Counter; the scope of nxt is the body of bump. The lifetime of n is the lifetime of the Counter object holding it; the lifetime of nxt is the duration of the call to bump. Neither variable can be seen from outside of its scope.
Variables whose value may not be changed after initialization are said to be immutable, or constants ( $\$ 5.1$ ), or simply val variables. Variables whose value may change are mutable or simply var variables. var variables are declared by the var keyword. val variables may be declared by the val keyword; when a variable declaration does not include either var or val, it is considered val.
A variable-even a val - can be declared in one statement, and then initialized later on. It must be initialized before it can be used ( $\$ 19)$.
Example: The following example illustrates many of the variations on variable declaration:

```
val a : Int = 0;
// Full 'val' syntax
b : Int = 0; // 'val' implied
```

[^14]```
val c = 0; // Type inferred
var d : Int = 0; // Full 'var' syntax
var e : Int; // Not initialized
var f : Int{self != 100} = 0; // Constrained type
val g : Int; // Init. deferred
if (a > b) g = 1; else g = 2; // Init. done here.
```


### 5.1 Immutable variables

```
LocVarDeclnStmt ::= LocVarDecln;
LocVarDecln ::= Mods?VarKeyword VariableDeclrs
    | Mods?VarDeclsWType
    | Mods?VarKeyword FormalDeclrs
```

(20.106)
(20.105)

An immutable (val) variable can be given a value (by initialization or assignment) at most once, and must be given a value before it is used. Usually this is achieved by declaring and initializing the variable in a single statement, such as val $\mathrm{x}=3$, with syntax (20.105) using the VariableDeclarators or VarDelcsWType alternatives.
Example: After these declarations, a and b cannot be assigned to further, or even redeclared:

```
val a : Int = 10;
val b = (a+1)*(a-1);
// ERROR: a = 11; // vals cannot be assigned to.
// ERROR: val a = 11; // no redeclaration.
```

In two special cases, the declaration and assignment are separate. One case is how constructors give values to val fields of objects. In this case, production (20.105) is taken, with the FormalDeclarators option, such as var n:Int;
Example: The Example class has an immutable field n , which is given different values depending on which constructor was called. n can't be given its value by initialization when it is declared, since it is not knowable which constructor is called at that point.

```
class Example {
    val n : Int; // not initialized here
```

```
    def this() { n = 1; }
    def this(dummy:Boolean) { n = 2;}
}
```

The other case of separating declaration and assignment is in function and method call, described in $\$ 5.4$. The formal parameters are bound to the corresponding actual parameters, but the binding does not happen until the function is called.

Example: In the code below, x is initialized to 3 in the first call and 4 in the second.

```
val sq = (x:Int) => x*x;
x10.io.Console.OUT.println("3 squared = " + sq(3));
x10.io.Console.OUT.println("4 squared = " + sq(4));
```


### 5.2 Initial values of variables

Every assignment, binding, or initialization to a variable of type $T\{c\}$ must be an instance of type $T$ satisfying the constraint $\{c\}$. Variables must be given a value before they are used. This may be done by initialization - giving a variable a value as part of its declaration.
Example: These variables are all initialized:

```
val immut : Int = 3;
var mutab : Int = immut;
val use = immut + mutab;
```

Or, a variable may be given a value by an assignment. var variables may be assigned to repeatedly. val variables may only be assigned once; the compiler will ensure that they are assigned before they are used.
Example: The variables in the following example are given their initial values by assignment. Note that they could not be used before those assignments, nor could immu be assigned repeatedly.

```
var muta : Int;
// ERROR: println(muta);
muta = 4;
val use2A = muta * 10;
```

```
val immu : Int;
// ERROR: println(immu);
if (cointoss()) {immu = 1;}
else {immu = use2A;}
val use2B = immu * 10;
// ERROR: immu = 5;
```

Every class variable must be initialized before it is read, through the execution of an explicit initializer. Every instance variable must be initialized before it is read, through the execution of an explicit or implicit initializer or a constructor. Implicit initializers initialize vars to the default values of their types ( $\$ 4.7$ ). Variables of types which do not have default values are not implicitly initialized.
Each method and constructor parameter is initialized to the corresponding argument value provided by the invoker of the method. An exception-handling parameter is initialized to the object thrown by the exception. A local variable must be explicitly given a value by initialization or assignment, in a way that the compiler can verify using the rules for definite assignment (\$19).

### 5.3 Destructuring syntax

X10 permits a destructuring syntax for local variable declarations with explicit initializers, and for formal parameters, of type Point, 16.1 and Array, $\$ 16$. A point is a sequence of zero or more Int-valued coordinates; an array is an indexed collection of data. It is often useful to get at the coordinates or elements directly, in variables.

$$
\begin{array}{lcl}
\text { VariableDeclr }::= & \text { Id HasResultType } ?=\text { VariableInitializer } \\
& \mid \quad[\text { IdList }] \text { HasResultType } ?=\text { VariableInitializer }
\end{array}
$$

The syntax val $\left[\mathrm{a}_{1}, \ldots, \mathrm{a}_{n}\right]=\mathrm{e}$; , where e is a Point, declares $n$ Int variables, bound to the precisely $n$ components of the Point value of e ; it is an error if e is not a Point with precisely $n$ components. The syntax val $p\left[\mathrm{a}_{1}, \ldots\right.$, $\left.\mathrm{a}_{n}\right]=\mathrm{e}$; is similar, but also declares the variable p to be of type Point ( n ).
The syntax val $\left[\mathrm{a}_{1}, \ldots, \mathrm{a}_{n}\right]=\mathrm{e}$; , where e is an Array[T] for some type T , declares $n$ variables of type T , bound to the precisely $n$ components of the Array [T] value of $e$; it is an error if $e$ is not a Array [T] with rank==1 and
size $==n$. The syntax val $p\left[a_{1}, \ldots, a_{n}\right]=e$; is similar, but also declares the variable $p$ to be of type Array [T] \{rank==1, size==n\}.

Example: The following code makes an anonymous point with one coordinate 11, and binds i to 11 . Then it makes a point with coordinates 22 and 33 , binds p to that point, and j and k to 22 and 33 respectively.

```
val [i] : Point = Point.make(11);
assert i == 11;
val p[j,k] = Point.make(22,33);
assert j == 22 && k == 33;
val q[l,m] = [44,55] as Point;
assert l == 44 && m == 55;
//ERROR: val [n] = p;
```

Destructuring is allowed wherever a Point or Array[T] variable is declared, e.g., as the formal parameters of a method. Example: The methods below take a single argument each: a three-element point for example1, a three-element array for example2. The argument itself is bound to x in both cases, and its elements are bound to $\mathrm{a}, \mathrm{b}$, and c .

```
static def example1(x[a,b,c]:Point){}
static def example2(x[a,b,c]:Array[String]{rank==1,size==3}){}
```


### 5.4 Formal parameters

Formal parameters are the variables which hold values transmitted into a method or function. They are always declared with a type. (Type inference is not available, because there is no single expression to deduce a type from.) The variable name can be omitted if it is not to be used in the scope of the declaration, as in the type of the method static def main(Array[String]) : void executed at the start of a program that does not use its command-line arguments.
var and val behave just as they do for local variables, $\$ 5.5$. In particular, the following inc method is allowed, but, unlike some languages, does not increment its actual parameter. inc ( j ) creates a new local variable i for the method call, initializes $i$ with the value of $j$, increments $i$, and then returns. $j$ is never changed.

```
static def inc(var i:Int) { i += 1; }
```

```
static def example() {
    var j : Int = 0;
    assert j == 0;
    inc(j);
    assert j == 0;
}
```


### 5.5 Local variables and Type Inference

Local variables are declared in a limited scope, and, dynamically, keep their values only for so long as the scope is being executed. They may be var or val. They may have initializer expressions: var i:Int $=1$; introduces a variable $i$ and initializes it to 1 . If the variable is immutable (val) the type may be omitted and inferred from the initializer type ( $\$ 4.12$ ).
The variable declaration val $\mathrm{x}: \mathrm{T}=\mathrm{e}$; confirms that e's value is of type T , and then introduces the variable $x$ with type T. For example, consider a class Tub with a property p .

```
class Tub(p:Int){
    def this(pp:Int):Tub{self.p==pp} {property(pp);}
    def example() {
        val t : Tub = new Tub(3);
    }
}
```

produces a variable $t$ of type Tub, even though the expression new Tub(3) produces a value of type Tub\{self. $p==3\}$ - that is, a Tub whose $p$ field is 3 . This can be inconvenient when the constraint information is required.
Including type information in variable declarations is generally good programming practice: it explains to both the compiler and human readers something of the intent of the variable. However, including types in val $\mathrm{t}: \mathrm{T}=\mathrm{e}$ can obliterate helpful information. So, X10 allows a documentation type declaration, written

```
val t <: T = e
```

This has the same effect as val $t=e$, giving $t$ the full type inferred from $e$; but it also confirms statically that that type is at least $T$.

Example: The following gives t the type Tub\{self. $\mathrm{p}==3\}$ as desired. However, a similar declaration with an inappropriate type will fail to compile.

```
val t <: Tub = new Tub(3);
// ERROR: val u <: Int = new Tub(3);
```


### 5.6 Fields



Like most other kinds of variables in X10, the fields of an object can be either val or var. val fields can be static ( $\$ 8.2$. Field declarations may have optional initializer expressions, as for local variables, $\$ 5.5$. var fields without an initializer are initialized with the default value of their type. val fields without an initializer must be initialized by each constructor.
For val fields, as for val local variables, the type may be omitted and inferred from the initializer type ( $\$ 4.12$ ). var fields, like var local variables, must be declared with a type.

## 6 Names and packages

### 6.1 Names

An X10 program consists largely of giving names to entities, and then manipulating the entities by their names. The entities involved may be compile-time constructs, like packages, types and classes, or run-time constructs, like numbers and strings and objects.
X10 names can be simple names, which look like identifiers: vj, x10, AndSoOn. Or, they can be qualified names, which are sequences of two or more identifiers separated by dots: x10.lang. String, somePack.someType, a.b.c.d.e.f. Some entities have only simple names; some have both simple and qualified names.

Every declaration that introduces a name has a scope: the region of the program in which the named entity can be referred to by a simple name. In some cases, entities may be referred to by qualified names outside of their scope. E.g., a public class $C$ defined in package $p$ can be referred to by the simple name $C$ inside of p , or by the qualified name p.C from anywhere.
Many sorts of entities have members. Packages have classes, structs, and interfaces as members. Those, in turn, have fields, methods, types, and so forth as members. The member $x$ of an entity named $E$ (as a simple or qualified name) has the name E. x ; it may also have other names.

### 6.1.1 Shadowing

One declaration $d$ may shadow another declaration $d^{\prime}$ in part of the scope of $d^{\prime}$, if $d$ and $d^{\prime}$ declare variables with the same simple name $n$. When $d$ shadows $d^{\prime}$, a
use of $n$ might refer to $d$ 's $n$ (unless some $d^{\prime \prime}$ in turn shadows $d$ ), but will never refer to $d^{\prime}$ 's $n$.

X10 has four namespaces:

- Types: for classes, interfaces, structs, and defined types.
- Values: for val- and var-bound variables; fields; and formal parameters of all sorts.
- Methods: for methods of classes, interfaces, and structs.
- Packages: for packages.

A declaration $d$ in one namespace, binding a name $n$ to an entity $e$, shadows all other declarations of that name $n$ in scope at the point where $d$ is declared. This shadowing is in effect for the entire scope of $d$. Declarations in different namespaces do not shadow each other. Thus, a local variable declaration may shadow a field declaration, but not a class declaration.

Declarations which only introduce qualified names - in X10, this is only package declarations - cannot shadow anything.
The rules for shadowing of imported names are given in 86.4 .

### 6.1.2 Hiding

Shadowing is ubiquituous in X10. Another, and considerably rarer, way that one definition of a given simple name can render another definition of the same name unavailable is hiding. If a class Super defines a field named $x$, and a subclass Sub of Super also defines a field named $x$, and $b$ : Sub, then b. $x$ is Sub's $x$ field, not Super's. In this case, Super's x is said to be hidden.

Hiding is technically different from shadowing, because hiding applies in more circumstances: a use of class Sub, such as sub. x , may involve hiding of name x , though it could not involve shadowing of $x$ because $x$ need not be declared as a name at that point.

### 6.1.3 Obscuring

The third way in which a definition of a simple name may become unavailable is obscuring. This well-named concept says that, if n can be interpreted as two or more of: a variable, a type, and a package, then it will be interpreted as a variable if that is possible, or a type if it cannot be interpreted as a variable. In this case, the unavailable interpretations are obscured.
Example: In the example method of the following code, both a struct and a local variable are named eg. Following the obscuring rules, the call eg.ow() in the first assert uses the variable rather than the struct. As the second assert demonstrates, the struct can be accessed through its fully-qualified name. Note that none of this would have happened if the coder had followed the convention that structs have capitalized names, Eg, and variables have lower-case ones, eg.

```
package obscuring;
struct eg {
    static def ow()= 1;
    static struct Bite {
        def ow() = 2;
    }
    def example() {
            val eg = Bite();
            assert eg.ow() == 2;
            assert obscuring.eg.ow() == 1;
        }
}
```

Due to obscuring, it may be impossible to refer to a type or a package via a simple name in some circumstances. Obscuring does not block qualified names.

### 6.1.4 Ambiguity and Disambiguation

Neither simple nor qualified names are necessarily unique. There can be, in general, many entities that have the same name. This is perfectly ordinary, and, when done well, considered good programming practice. Various forms of disambiguation are used to tell which entity is meant by a given name; e.g., methods with the same name may be disambiguated by the types of their arguments ( $\$ 8.11$ ).

Example: In the following example, there are three static methods with qualified name DisambEx.Example.m; they can be disambiguated by their different arguments. Inside the body of the third, the simple name i refers to both the Int formal of m , and to the static method DisambEx. Example.i.

```
package DisambEx;
class Example {
    static def m() = 1;
    static def m(Boolean) = 2;
    static def i() = 3;
    static def m(i:Int) {
        if (i > 10) {
            return i() + 1;
        }
        return i;
    }
    static def example() {
        assert m() == 1;
        assert m(true) == 2;
        assert m(3) == 3;
        assert m(20) == 4;
    }
}
```


### 6.2 Access Control

X10 allows programmers access control, that is, the ability to determine statically where identifiers of most sorts are visible. In particular, X10 allows information hiding, wherein certain data can be accessed from only limited parts of the program.
There are four access control modes: public, protected, private and uninflected package-specific scopes, much like those of Java. Most things can be public or private; a few things (e.g., class members) can also be protected or package-scoped.

Accessibility of one X10 entity (package, container, member, etc.) from within a package or container is defined as follows:

- Packages are always accessible.
- If a container $C$ is public, and, if it is inside of another container $D$, container $D$ is accessible, then $C$ is accessible.
- A member m of a container C is accessible from within another container E if C is accessible, and:
- $m$ is declared public; or
- C is an interface; or
- $m$ is declared protected, and either the access is from within the same package that C is defined in, or from within the body of a subclass of C (but see $\$ 6.2 .1$ for some fine points); or
- $m$ is declared private, and the access is from within the top-level class which contains the definition of C - which may be C itself, or, if $C$ is a nested container, an outer class around $C$; or
- m has no explicit class declaration (hence using the implicit "package"level access control), and the access occurs from the same package that C is declared in.


### 6.2.1 Details of protected

protected access has a few fine points. Within the body of a subclass D of the class $C$ containing the definition of a protected member $m$,

- An access e.fld to a field, or e.m(...) to a method, is permitted precisely when the type of e is either D or a subtype of D. For example, the access to that. f in the following code is acceptable, but the access to xhax. f is not.

```
class C {
    protected var f : Int = 0;
}
class X extends C {}
class D extends C {
    def usef(that:D, xhax:X) {
        this.f += that.f;
```

```
        // ERROR: this.f += xhax.f;
    }
}
```

Limitation: The X10 compiler improperly allows access to xhax - as, indeed, some Java compilers do, despite Java having the analogous rule. The compiler allows you to do everything the spec says and a bit more.

- An access through a qualified name $\mathrm{Q} . \mathrm{N}$ is permitted precisely when the type of $Q$ is $D$ or a subtype of $D$.

Qualified access to a protected constructor is subtle. Let C be a class with a protected constructor $c$, and let $\mathbf{S}$ be the innermost class containing a use $u$ of $c$. There are three cases for $u$ :

- Superclass construction invocations, super (...) or E.super (...), are permitted.
- Anonymous class instance creations, of the forms new $C(\ldots)\{\ldots\}$ and E.new C(...) \{...\}, are permitted.
- No other accesses are permitted.


### 6.3 Packages

A package is a named collection of top-level type declarations, viz., class, interface, and struct declarations. Package names are sequences of identifiers, like x10.lang and com.ibm.museum. The multiple names are simply a convenience, though there is a tenuous relationship between packages a, a.b, and a.c. Packages can be accessed by name from anywhere: a package may contain private elements, but may not itself be private.
Packages and protection modifiers determine which top-level names can be used where. Only the public members of package pack. age can be accessed outside of pack. age itself.

```
package pack.age;
```

class Deal \{
public def make() \{\}

```
}
public class Stimulus {
    private def taxCut() = true;
    protected def benefits() = true;
    public def jobCreation() = true;
    /*package*/ def jumpstart() = true;
}
```

The class Stimulus can be referred to from anywhere outside of pack. age by its full name of pack.age. Stimulus, or can be imported and referred to simply as Stimulus. The public jobCreation() method of a Stimulus can be referred to from anywhere as well; the other methods have smaller visibility. The nonpublic class Deal cannot be used from outside of pack.age.

### 6.3.1 Name Collisions

It is a static error for a package to have two members with the same name. For example, package pack. age cannot define two classes both named Crash, nor a class and an interface with that name.

Furthermore, pack.age cannot define a member Crash if there is another package named pack.age. Crash, nor vice-versa. (This prohibition is the only actual relationship between the two packages.) This prevents the ambiguity of whether pack.age. Crash refers to the class or the package. Note that the naming convention that package names are lower-case and package members are capitalized prevents such collisions.

## 6.4 import Declarations

Any public member of a package can be referred to from anywhere through a fully-qualified name: pack.age. Stimulus.
Often, this is too awkward. X10 has two ways to allow code outside of a class to refer to the class by its short name (Stimulus): single-type imports and ondemand imports.

Imports of either kind appear at the start of the file, immediately after the package directive if there is one; their scope is the whole file.

### 6.4.1 Single-Type Import

The declaration import TypeName ; imports a single type into the current namespace. The type it imports must be a fully-qualified name of an extant type, and it must either be in the same package (in which case the import is redundant) or be declared public.

Furthermore, when importing pack. age.T, there must not be another type named T at that point: neither a T declared in pack.age, nor a inst.ant. T imported from some other package.

The declaration import E.n;, appearing in file $f$ of a package named P , shadows the following types named n when they appear in $f$ :

- Top-level types named $n$ appearing in other files of $P$, and
- Types named n imported by automatic imports (§6.4.2) in $f$.


### 6.4.2 Automatic Import

The automatic import import pack. age. *; loosely, imports all the public members of pack. age. In fact, it does so somewhat carefully, avoiding certain errors that could occur if it were done naively. Types defined in the current package, and those imported by single-type imports, shadow those imported by automatic imports. If two automatic imports provide the same short name $n$, it is an error to use n - but it is not an error if no conflicting name is ever used. Names automatically imported never shadow any other names.

### 6.4.3 Implicit Imports

The packages x10.lang, x10. array are automatically imported in all files without need for further specification. Furthermore, the public static members of the class named _ in x10.lang are imported everywhere as well. This provides a number of aliases, such as Console and int for x10.io. Console and Int.

### 6.5 Conventions on Type Names

| TypeName | $::=$ | Id |
| :--- | :---: | :--- |
|  | $\mid$ | TypeName . Id |
| PackageName | $::=$ | Id |
|  | $\mid$ PackageName . Id |  |

While not enforced by the compiler, classes and interfaces in the X10 library follow the following naming conventions. Names of types-including classes, type parameters, and types specified by type definitions-are in CamelCase and begin with an uppercase letter. (Type variables are often single capital letters, such as T.) For backward compatibility with languages such as C and Java, type definitions are provided to allow primitive types such as int and boolean to be written in lowercase. Names of methods, fields, value properties, and packages are in camelCase and begin with a lowercase letter. Names of static val fields are in all uppercase with words separated by _'s.

## 7 Interfaces

An interface specifies signatures for zero or more public methods, property methods, static vals, classes, structs, interfaces, types and an invariant.

The following puny example illustrates all these features:

```
interface Pushable{prio() != O} {
    def push(): void;
    static val MAX_PRIO = 100;
    abstract class Pushedness{}
    struct Pushy{}
    interface Pushing{}
    static type Shove = Int;
    property text():String;
    property prio():Int;
}
class MessageButton(text:String)
    implements Pushable{self.prio()==Pushable.MAX_PRIO} {
    public def push() {
        x10.io.Console.OUT.println(text + " pushed");
    }
    public property text() = text;
    public property prio() = Pushable.MAX_PRIO;
}
```

Pushable defines two property methods, one normal method, and a static value. It also establishes an invariant, that prio() != 0. MessageButton implements a constrained version of Pushable, viz. one with maximum priority. It defines the push() method given in the interface, as a public method-interface methods are implicitly public.

Limitation: X10 may not always detect that type invariants of interfaces are satisfied, even when they obviously are.

A container-a class or struct-can implement an interface, typically by having all the methods and property methods that the interface requires, and by providing a suitable implements clause in its definition.

A variable may be declared to be of interface type. Such a variable has all the property and normal methods declared (directly or indirectly) by the interface; nothing else is statically available. Values of any concrete type which implement the interface may be stored in the variable.

Example: The following code puts two quite different objects into the variable star, both of which satisfy the interface Star.

```
interface Star { def rise():void; }
class AlphaCentauri implements Star {
    public def rise() {}
}
class ElvisPresley implements Star {
    public def rise() {}
}
class Example {
    static def example() {
        var star : Star;
        star = new AlphaCentauri();
        star.rise();
        star = new ElvisPresley();
        star.rise();
    }
}
```

An interface may extend several interfaces, giving X10 a large fraction of the power of multiple inheritance at a tiny fraction of the cost.

## Example:

```
interface Star{}
interface Dog{}
class Sirius implements Dog, Star{}
class Lassie implements Dog, Star{}
```


### 7.1 Interface Syntax

| InterfaceDecln | ::= | Mods? interface Id TypeParamsI? ExtendsInterfaces? InterfaceBody | Properties? Guard? | 20.96 |
| :---: | :---: | :---: | :---: | :---: |
| TypeParamsI | ::= | [ TypeParamIList] |  | (20.171) |
| Guard | ::= | DepParams |  | (20.82) |
| ExtendsInterfaces | ::= | extends Type |  | (20.65) |
|  | \| | ExtendsInterfaces, Type |  |  |
| InterfaceBody | ::= | \{ InterfaceMemberDeclns? \} |  | (20.95) |
| InterfaceMemberDecln | ::= | MethodDecln |  | (20.97) |
|  |  | PropMethodDecln |  |  |
|  |  | FieldDecln |  |  |
|  |  | TypeDecln |  |  |

The invariant associated with an interface is the conjunction of the invariants associated with its superinterfaces and the invariant defined at the interface.
A class C implements an interface I if I, or a subtype of I, appears in the implements list of $C$. In this case, C implicitly gets all the methods and property methods of I, as abstract public methods. If C does not declare them explicitly, then they are abstract, and C must be abstract as well. If C does declare them all, C may be concrete.
If C implements I , then the class invariant ( $(8.8)$ for $\mathrm{C}, \operatorname{inv}(\mathrm{C})$, implies the class invariant for $\mathrm{I}, \operatorname{inv}(\mathrm{I})$. That is, if the interface I specifies some requirement, then every class $C$ that implements it satisfies that requirement.

### 7.2 Access to Members

All interface members are public, whether or not they are declared public. There is little purpose to non-public methods of an interface; they would specify that implementing classes and structs have methods that cannot be seen.

### 7.3 Member Specification

An interface can specify that all containers implementing it must have certain instance methods. It cannot require constructors or static methods, though.

Example: The Stat interface requires that its implementers provide an ick method. It can't insist that implementations provide a static method like meth, or a nullary constructor.

```
interface Stat {
    def ick():void;
    // ERROR: static def meth():Int;
    // ERROR: static def this();
}
class Example implements Stat {
    public def ick() {}
    def example() {
        this.ick();
    }
}
```


### 7.4 Property Methods

An interface may declare property methods. All non-abstract containers implementing such an interface must provide all the property methods specified.

### 7.5 Field Definitions

An interface may declare a val field, with a value. This field is implicitly public static val. In particular, it is not an instance field.

```
interface KnowsPi {
        PI = 3.14159265358;
    }
```

Classes and structs implementing such an interface get the interface's fields as public static fields. Unlike methods, there is no need for the implementing class to declare them.

```
class Circle implements KnowsPi {
    static def area(r:Double) = PI * r * r;
}
```

```
class UsesPi {
    def circumf(r:Double) = 2 * r * KnowsPi.PI;
}
```


### 7.5.1 Fine Points of Fields

If two parent interfaces give different static fields of the same name, those fields must be referred to by qualified names.

```
interface E1 {static val a = 1;}
interface E2 {static val a = 2;}
interface E3 extends E1, E2{}
class Example implements E3 {
    def example() = E1.a + E2.a;
}
```

If the same field a is inherited through many paths, there is no need to disambiguate it:

```
interface I1 { static val a = 1;}
interface I2 extends I1 {}
interface I3 extends I1 {}
interface I4 extends I2,I3 {}
class Example implements I4 {
    def example() = a;
}
```

The initializer of a field in an interface may be any expression. It is evaluated under the same rules as a static field of a class.

Example: In this example, a class TheOne is defined, with an inner interface WelshOrFrench, whose field UN (named in either Welsh or French) has value 1. Note that WelshOrFrench does not define any methods, so it can be trivially added to the implements clause of any class, as it is for Onesome. This allows the body of Onesome to use UN through an unqualified name, as is done in example().
class TheOne \{
static val ONE = 1;
interface WelshOrFrench \{

```
        val UN = 1;
    }
    static class Onesome implements WelshOrFrench {
        static def example() {
        assert UN == ONE;
        }
    }
}
```


### 7.6 Generic Interfaces

Interfaces, like classes and structs, can have type parameters. The discussion of generics in $\$ 4.3$ applies to interfaces, without modification.
Example:
interface ListOfFuns[T,U] extends x10.util.List[(T)=>U] \{\}

### 7.7 Interface Inheritance

The direct superinterfaces of a non-generic interface I are the interfaces (if any) mentioned in the extends clause of I's definition. If I is generic, the direct superinterfaces are of an instantiation of I are the corresponding instantiations of those interfaces. A superinterface of I is either I itself, or a direct superinterface of a superinterface of $I$, and similarly for generic interfaces.

I inherits the members of all of its superinterfaces. Any class or struct that has I in its implements clause also implements all of I's superinterfaces.

Classes and structs may be declared to implement multiple interfaces. Semantically, the interface type is the set of all objects that are instances of classes or structs that implement the interface. A class or struct implements an interface if it is declared to and if it concretely or abstractly implements all the methods and properties defined in the interface. For example, Kim implements Person, and hence Named and Mobile. It would be a static error if Kim had no name method, unless Kim were also declared abstract.

```
class Kim implements Person {
    var pos : Int = 0;
    public def name() = "Kim (" + pos + ")";
    public def move(dPos:Int) { pos += dPos; }
}
```


### 7.8 Members of an Interface

The members of an interface I are the union of the following sets:

1. All of the members appearing in I's declaration;
2. All the members of its direct super-interfaces, except those which are hidden (86.1.2) by I
3. The members of Any.

Overriding for instances is defined as for classes, $\{8.4 .7$

## 8 Classes

### 8.1 Principles of X10 Objects

### 8.1.1 Basic Design

Objects are instances of classes: the most common and most powerful sort of value in X10. The other kinds of values, structs and functions, are more specialized, better in some circumstances but not in all. x10.lang. Object is the most general class; all other classes inherit from it, directly or indirectly.

Classes are structured in a single-inheritance code hierarchy. They may have any or all of these features:

- Implementing any number of interfaces;
- Static and instance val fields;
- Instance var fields;
- Static and instance methods;
- Constructors;
- Properties;
- Static and instance nested containers.
- Static type definitions

X10 objects (unlike Java objects) do not have locks associated with them. Programmers may use atomic blocks ( $\$ 14.7$ ) for mutual exclusion and clocks ( $\$ 15$ ) for sequencing multiple parallel operations.

An object exists in a single location: the place that it was created. One place cannot use or even directly refer to an object in a different place. A special type, GlobalRef[T], allows explicit cross-place references.

The basic operations on objects are:

- Construction ( $\$ 8.10$ ). Objects are created, their var and val fields initialized, and other invariants established.
- Field access (§ 11.4 ). The static, instance, and property fields of an object can be retrieved; var fields can be set.
- Method invocation (\$11.6). Static, instance, and property methods of an object can be invoked.
- Casting ( $\$ 11.22$ ) and instance testing with instanceof (\$11.24) Objects can be cast or type-tested.
- The equality operators $==$ and $!=$. Objects can be compared for equality with the == operation. This checks object identity: two objects are == iff they are the same object.


### 8.1.2 Class Declaration Syntax

The class declaration has a list of type parameters, a list of properties, a constraint (the class invariant), a single superclass, zero or more interfaces that it implements, and a class body containing the the definition of fields, properties, methods, and member types. Each such declaration introduces a class type ( $\$ 4.2$ ).


### 8.2 Fields

Objects may have instance fields, or simply fields (called "instance variables" in C++ and Smalltalk, and "slots" in CLOS): places to store data that is pertinent to the object. Fields, like variables, may be mutable (var) or immutable (val).
Class may have static fields, which store data pertinent to the entire class of objects. See $\$ 8.6$ for more information. X10 does not permit mutable static state. A fundamental principle of the X 10 model of computation is that all mutable state be local to some place ( $\$ 13$ ), and, as static variables are globally available, they cannot be mutable. When mutable global state is necessary, programmers should use singleton classes, putting the state in an object and using place-shifting commands ( $\S 13.3$ ) and atomicity ( $\S 14.7$ ) as necessary to mutate it safely.
No two fields of the same class may have the same name. A field may have the same name as a method, although for fields of functional type there is a subtlety ( $\$ 8.11 .4$ ).

### 8.2.1 Field Initialization

Fields may be given values via field initialization expressions: val $\mathrm{f} 1=\mathrm{E}$; and var $f 2$ : Int = F;. Other fields of this may be referenced, but only those that precede the field being initialized.
Example: The following is correct, but would not be if the fields were reversed:

```
class Fld{
    val a = 1;
    val b = 2+a;
}
```


### 8.2.2 Field hiding

A subclass that defines a field $f$ hides any field $f$ declared in a superclass, regardless of their types. The superclass field $f$ may be accessed within the body of the subclass via the reference super.f.
With inner classes, it is occasionally necessary to write Cls.super.f to get at a hidden field $f$ of an outer class Cls.

Example: The $f$ field in Sub hides the $f$ field in Super The superf method provides access to the $f$ field in Super.

```
class Super{
    public val f = 1;
}
class Sub extends Super {
    val f = true;
    def superf() : Int = super.f; // 1
}
```

Example: Hidden fields of outer classes can be accessed by suitable forms:

```
class A {
    val f = 3;
}
class B extends A {
    val f = 4;
    class C extends B {
```

```
    // C is both a subclass and inner class of B
    val f = 5;
    def example() {
        assert f == 5 : "field of C";
        assert super.f == 4 : "field of superclass";
        assert B.this.f == 4 : "field of outer instance";
        assert B.super.f == 3 : "super.f of outer instance";
    }
    }
}
```


### 8.2.3 Field qualifiers

The behavior of a field may be changed by a field qualifier, such as static or transient.
static qualifier
A val field may be declared to be static, as described in 88.2 .

## transient Qualifier

A field may be declared to be transient. Transient fields are excluded from the deep copying that happens when information is sent from place to place in an at statement. The value of a transient field of a copied object is the default value of its type, regardless of the value of the field in the original. If the type of a field has no default value, it cannot be marked transient.

```
class Trans {
    val copied = "copied";
    transient var transy : String = "a very long string";
    def example() {
        at (here) { // causes copying of 'this'
            assert(this.copied.equals("copied"));
            assert(this.transy == null);
        }
```

```
    }
}
```


### 8.3 Properties

The properties of an object (or struct) are a restricted form of public val fields ${ }^{1}$ For example, every array has a rank telling how many subscripts it takes. Userdefined classes can have whatever properties are desired.
Properties differ from public val fields in a few ways:

1. Property references are allowed on self in constraints: self.prop. Field references are not.
2. Properties are in scope for all instance initialization expressions. val fields are not.
3. The graph of values reachable from a given object by following only property links is acyclic. Conversely, it is possible (and routine) for two objects to point to each other with val fields.
4. Properties are declared in the class header; val fields are defined in the class body.
5. Properties are set in constructors by a property statement. val fields are set by assignment.

Properties are defined in parentheses, after the name of the class. They are given values by the property command in constructors.

Example: Proper has a single property, t. new Proper (4) creates a Proper object with $\mathrm{t}==4$.

```
class Proper(t:Int) {
    def this(t:Int) {property(t);}
    }
```

[^15]It is a static error for a class defining a property x : T to have a subclass class that defines a property or a field with the name x .

A property $\mathrm{x}: \mathrm{T}$ induces a field with the same name and type, as if defined with:

```
public val x : T;
```

Properties are initialized in a constructor by the invocation of a special property statement. The requirement to use the property statement means that all properties must be given values at the same time: a container either has its properties or it does not.

```
property(e1,..., en);
```

The number and types of arguments to the property statement must match the number and types of the properties in the class declaration, in order. Every constructor of a class with properties must invoke property (...) precisely once; it is a static error if X10 cannot prove that this holds.
By construction, the graph whose nodes are values and whose edges are properties is acyclic. E.g., there cannot be values a and b with properties c and d such that a.c == b and b.d == a.

## Example:

```
class Proper(a:Int, b:String) {
    def this(a:Int, b:String) {
        property(a, b);
    }
    def this(z:Int) {
            val theA = z+5;
            val theB = "X"+z;
            property(theA, theB);
    }
    static def example() {
            val p = new Proper(1, "one");
            assert p.a == 1 && p.b.equals("one");
            val q = new Proper(10);
            assert q.a == 15 && q.b.equals("X10");
    }
}
```


### 8.3.1 Properties and Field Initialization

Fields with explicit initializers are evaluated immediately after the property command, and all properties are in scope when initializers are evaluated.
Example: Class Init initializes the field a to be an array of n elements, where n is a property. When new Init(4) is executed, the constructor first sets n to 4 via the property statement, and then initializes a to a 4-element array.

However, Outit uses a field rather than a property for n . If the ERROR line were present, it would not compile. n has not been definitely assigned ( $\$ 19$ ) at this point, and n has not been given its value, so a cannot be computed. (If one insisted that n be a property, a would have to be initialized in the constructor, rather than by an initialization expression.)

```
class Init(n:Int) {
    val a = new Array[String](0..n, "");
    def this(n:Int) { property(n); }
}
class Outit {
    val n : Int;
    //ERROR: val a = new Array[String](0..n, "");
    def this(m:Int) { this.n = m; }
}
```


### 8.3.2 Properties and Fields

A container with a property named $p$, or a nullary property method named $p()$, cannot have a field named $p$ - either defined in that container, or inherited from a superclass.

### 8.3.3 Acyclicity of Properties

X10 has certain restrictions that, ultimately, require that properties are simpler than their containers. For example, class A(a:A) \{\} is not allowed. Formally, this requirement is that there is a total order $\preceq$ on all classes and structs such that, if $A$ extends $B$, then $A \prec B$, and if $A$ has a property of type $B$, then $A \prec B$, where $A \prec B$ means $A \preceq B$ and $A \neq B$. For example, the preceding class

A is ruled out because we would need $A \prec A$, which violates the definition of $\prec$. The programmer need not (and cannot) specify $\preceq$, and rarely need worry about its existence.

Similarly, the type of a property may not simply be a type parameter. For example, class $A[X](x: X)\}$ is illegal.

### 8.4 Methods

As is common in object-oriented languages, objects can have methods, of two sorts. Static methods are functions, conceptually associated with a class and defined in its namespace. Instance methods are parameterized code bodies associated with an instance of the class, which execute with convenient access to that instance's fields.

Each method has a signature, telling what arguments it accepts, what type it returns, and what precondition it requires. Method definitions may be overridden by subclasses; the overriding definition may have a declared return type that is a subtype of the return type of the definition being overridden. Multiple methods with the same name but different signatures may be provided on a class (called "overloading" or "ad hoc polymorphism"). Methods may be declared public, private, protected, or given default package-level access rights.


A formal parameter may have a val or var modifier; val is the default. The body
of the method is executed in an environment in which each formal parameter corresponds to a local variable (var iff the formal parameter is var) and is initialized with the value of the actual parameter.

### 8.4.1 Forms of Method Definition

There are several syntactic forms for definining methods. The forms that include a block, such as def m() \{S\}, allow an arbitrary block. These forms can define a void method, which does not return a value.

The forms that include an expression, such as def m()$=E$, require a syntactically and semantically valid expression. These forms cannot define a void method, because expressions cannot be void.

There are no other semantic differences between the two forms.

### 8.4.2 Method Return Types

A method with an explicit return type returns that type. A method without an explicit return type is given a return type by type inference. A call to a method has type given by substituting information about the actual val parameters for the formals.

## Example:

In the example below, met 1 has an explicit return type $\operatorname{Ret}\{\mathrm{n}==\mathrm{a}\}$. met 2 does not, so its return type is computed, also to be $\operatorname{Ret}\{\mathrm{n}==\mathrm{a}\}$, because that's what the implicitly-defined constructor returns.
use 3 requires that its argument have $\mathrm{n}==3$. example shows that both met1 and met2 can be used to produce such an object. In both cases, the actual argument 3 is substituted for the formal argument a in the return type expression for the method $\operatorname{Ret}\{\mathrm{n}==\mathrm{a}\}$, giving the type $\operatorname{Ret}\{\mathrm{n}==3\}$ as required by use3.

```
class Ret(n:Int) {
    static def met1(a:Int) : Ret{n==a} = new Ret(a);
    static def met2(a:Int) = new Ret(a);
    static def use3(Ret{n==3}) {}
    static def example() {
        use3(met1(3));
```

```
        use3(met2(3));
    }
}
```


### 8.4.3 Final Methods

An instance method may be given the final qualifier. final methods may not be overridden.

### 8.4.4 Generic Instance Methods

Limitation: In X10, an instance method may be generic:

```
class Example {
    def example[T](t:T) = "I like " + t;
}
```

However, the C++ back end does not currently support generic virtual instance methods like example. It does allow generic instance methods which are final or private, and it does allow generic static methods.

### 8.4.5 Method Guards

Often, a method will only make sense to invoke under certain statically-determinable conditions. These conditions may be expressed as a guard on the method.

Example: For example, example(x) is only well-defined when x != null, as null.toString() throws a null pointer exception, and returns nothing:

```
class Example {
    var f : String = "";
    def setF(x:Object){x != null} : void = {
        this.f = x.toString();
    }
}
```

(We could have used a constrained type $0 b j e c t\{s e l f!=n u l l\}$ for x instead; in most cases it is a matter of personal preference or convenience of expression which one to use.)

The requirement of having a method guard is that callers must demonstrate to the X10 compiler that the guard is satisfied. With the STATIC_CHECKS compiler option in force ( $\$$ C.0.4), this is checked at compile time. As usual with static constraint checking, there is no runtime cost. Indeed, this code can be more efficient than usual, as it is statically provable that $\mathrm{x} \quad!=$ null.
When STATIC_CHECKS is not in force, dynamic checks are generated as needed; method guards are checked at runtime. This is potentially more expensive, but may be more convenient.

Example: The following code fragment contains a line which will not compile with STATIC_CHECKS on (assuming the guarded example method above). (X10's type system does not attempt to propagate information from ifs.) It will compile with STATIC_CHECKS off, but it may insert an extra null-test for x .

```
def exam(e:Example, x:Object) {
    if (x != null)
        e.example(x as Object{x != null});
        // If STATIC_CHECKS is in force:
        // ERROR: if (x != null) e.example(x);
}
```

The guard $\{\mathrm{c}\}$ in a guarded method def m()$\{\mathrm{c}\}=\mathrm{E}$; specifies a constraint c on the properties of the class $C$ on which the method is being defined. The method, in effect, only exists for those instances of $C$ which satisfy $c$. It is illegal for code to invoke the method on objects whose static type is not a subtype of $\mathrm{C}\{\mathrm{c}\}$.

Specifically: the compiler checks that every method invocation o.m( $\mathrm{e}_{1}, \ldots$, $\mathbf{e}_{n}$ ) is type correct. Each argument $\mathbf{e}_{i}$ must have a static type $\mathrm{S}_{i}$ that is a subtype of the declared type $\mathrm{T}_{i}$ for the $i$ th argument of the method, and the conjunction of the constraints on the static types of the arguments must entail the guard in the parameter list of the method.
The compiler checks that in every method invocation o.m $\left(\mathrm{e}_{1}, \ldots, \mathrm{e}_{n}\right)$ the static type of $o, S$, is a subtype of $C\{c\}$, where the method is defined in class $C$ and the guard for $m$ is equivalent to $c$.
Finally, if the declared return type of the method is $D\{d\}$, the return type computed for the call is $\mathrm{D}\left\{\mathrm{a}: \mathrm{S} ; \mathrm{x}_{1}: \mathrm{S}_{1} ; \ldots ; \mathrm{x}_{n}: \mathrm{S}_{n} ; \mathrm{d}[\mathrm{a} /\right.$ this] $\}$, where a is
a new variable that does not occur in $\mathrm{d}, \mathrm{S}, \mathrm{S}_{1}, \ldots, \mathrm{~S}_{n}$, and $\mathrm{x}_{1}, \ldots, \mathrm{x}_{n}$ are the formal parameters of the method.
Limitation: Using a reference to an outer class, Outer. this, in a constraint, is not supported.

### 8.4.6 Property methods

$$
\begin{aligned}
\text { PropMethodDecln }::= & \text { MethMods Id TypeParams? Formals Guard? HasResultType? } \\
& \text { MethodBody }
\end{aligned}
$$

Property methods are methods that can be evaluated in constraints, as properties can. They provide a means of abstraction over properties; e.g., interfaces can specify property methods that implementing containers must provide, but, just as they cannot specify ordinary fields, they cannot specify property fields. Property methods are very limited in computing power: they must obey the same restrictions as constraint expressions. In particular, they cannot have side effects, or even much code in their bodies.
Example: The eq() method below tells if the x and y properties are equal; the is(z) method tells if they are both equal to z . The eq and is property methods are used in types in the example method.

```
class Example(x:Int, y:Int) {
    def this(x:Int, y:Int) { property(x,y); }
    property eq() = (x==y);
    property is(z:Int) = x==z && y==z;
    def example( a : Example{eq()}, b : Example{is(3)} ) {}
}
```

A property method declared in a class must have a body and must not be void. The body of the method must consist of only a single return statement with an expression, or a single expression. It is a static error if the expression cannot be represented in the constraint system. Property methods may be abstract in abstract classes, and may be specified in interfaces, but are implicitly final in non-abstract classes.
The expression may contain invocations of other property methods. The compiler ensures that there are no circularities in property methods, so property method evaluations always terminate.

Property methods in classes are implicitly final; they cannot be overridden. It is a static error if a superclass has a property method with a given signature, and a subclass has a method or property method with the same signature. It is a static error if a superclass has a property with some name $p$, and a subclass has a nullary method of any kind (instance, static, or property) also named $p$.
A nullary property method definition may omit the def keyword. That is, the following are equivalent:

```
property def rail(): Boolean =
    rect && onePlace == here && zeroBased;
```

and
property rail(): Boolean = rect \&\& onePlace == here \&\& zeroBased;

Similarly, nullary property methods can be inspected in constraints without (). If ob's type has a property $p$, then ob. $p$ is that property. Otherwise, if it has a nullary property method $p()$, ob. $p$ is equivalent to ob.p(). As a consequence, if the type provides both a property p and a nullary method p() , then the property can be accessed as ob.p and the method as ob.p(). ${ }^{2}$
w.rail, with either definition above, is equivalent to w.rail()

## Limitation of Property Methods

Limitation: Currently, X10 forbids the use of property methods which have all the following features:

- they are abstract, and
- they have one or more arguments, and
- they appear as subterms in constraints.

[^16]Any two of these features may be combined, but the three together may not be.
Example: The constraint in example1 is concrete, not abstract. The constraint in example 2 is nullary, and has no arguments. The constraint in example3 appears at the top level, rather than as a subterm (cf. the equality expressions $\mathrm{A}==\mathrm{B}$ in the other examples). However, example4 combines all three features, and is not allowed.

```
class Cls {
    property concrete(a:Int) = 7;
}
interface Inf {
    property nullary(): Int;
    property topLevel(z:Int):Boolean;
    property allThree(z:Int):Int;
}
class Example{
    def example1(Cls{self.concrete(3)==7}) = 1;
    def example2(Inf{self.nullary()==7}) = 2;
    def example3(Inf{self.topLevel(3)}) = 3;
    //ERROR: def example4(Inf{self.allThree(3)==7}) = "fails";
}
```


### 8.4.7 Method overloading, overriding, hiding, shadowing and obscuring

The definitions of method overloading, overriding, hiding, shadowing and obscuring in X10 are familiar from languages such as Java, modulo the following considerations motivated by type parameters and dependent types.
Two or more methods of a class or interface may have the same name if they have a different number of type parameters, or they have formal parameters of different constraint-erased types (in some instantiation of the generic parameters).
Example: The following overloading of m is unproblematic.

```
class Mful{
    def m() = 1;
    def m[T]() = 2;
    def m(x:Int) = 3;
```

```
    def m[T](x:Int) = 4;
}
```

A class definition may include methods which are ambiguous in some generic instantiation. (It is a compile-time error if the methods are ambiguous in every generic instantiation, but excluding class definitions which are are ambiguous in some instantiation would exclude useful cases.) It is a compile-time error to use an ambiguous method call.

Example: The following class definition is acceptable. However, the marked method calls are ambiguous, and hence not acceptable.

```
class Two[T,U]{
    def m(x:T)=1;
    def m(x:Int)=2;
    def m[X](x:X)=3;
    def m(x:U)=4;
    static def example() {
        val t12 = new Two[Int, Any]();
        // ERROR: t12.m(2);
        val t13 = new Two[String, Any]();
        t13.m("ferret");
        val t14 = new Two[Boolean,Boolean]();
        // ERROR: t14.m(true);
    }
}
```

The call t12.m(2) could refer to either the 1 or 2 definition of m , so it is not allowed. The call t14.m(true) could refer to either the 1 or 4 definition, so it, too, is not allowed.

The call t13.m("ferret") refers only to the 1 definition. If the 1 definition were absent, type argument inference would make it refer to the 3 definition. However, X10 will choose a fully-specified call if there is one, before trying type inference, so this call unambiguously refers to 1.

X10 v2.2 does not permit overloading based on constraints. That is, the following is not legal, although either method definition individually is legal:

$$
\begin{aligned}
& \operatorname{def} \mathrm{n}(\mathrm{x}: \text { Int })\{\mathrm{x}==1\}=\text { "one"; } \\
& \operatorname{def} \mathrm{n}(\mathrm{x}: \text { Int })\{\mathrm{x}!=1\}=\text { "not"; }
\end{aligned}
$$

The definition of a method declaration $m_{1}$ "having the same signature as" a method declaration $\mathrm{m}_{2}$ involves identity of types.
The constraint erasure of a type $\mathrm{T}, \mathrm{ce}(\mathrm{T})$, is obtained by removing all the constraints outside of functions in $T$, specificially:

$$
\begin{align*}
c e(\mathrm{~T}) & =\mathrm{T} \text { if } \mathrm{T} \text { is a container or interface }  \tag{8.1}\\
c e(\mathrm{~T}\{\mathbf{c}\}) & =c e(\mathrm{~T})  \tag{8.2}\\
c e\left(\mathrm{~T}\left[\mathrm{~S}_{1}, \ldots, \mathrm{~S}_{n}\right]\right) & =c e(\mathrm{~T})\left[c e\left(\mathrm{~S}_{1}\right), \ldots, c e\left(\mathrm{~S}_{n}\right)\right]  \tag{8.3}\\
c e\left(\left(\mathrm{~S}_{1}, \ldots, \mathrm{~S}_{n}\right)=>\mathrm{T}\right) & =\left(c e\left(\mathrm{~S}_{1}\right), \ldots, c e\left(\mathrm{~S}_{n}\right)\right)=>c e(\mathrm{~T}) \tag{8.4}
\end{align*}
$$

Two methods are said to have erasedly equivalent signatures if (a) they have the same number of type parameters, (b) they have the same number of formal (value) parameters, and (c) for each formal parameter the constraint erasure of its types are erasedly equivalent. It is a compile-time error for there to be two methods with the same name and erasedly equivalent signatures in a class (either defined in that class or in a superclass), unless the signatures are identical (without erasures) and one of the methods is defined in a superclass (in which case the superclass's method is overridden by the subclass's, and the subclass's method's return type must be a subtype of the superclass's method's return type).
In addition, the guard of an overridden method must entail the guard of the overriding method. This ensures that any virtual call to the method satisfies the guard of the callee.
Example: In the following example, the call to s.recip(3) in example() will invoke Sub.recip(n). The call is legitimate because Super.recip's guard, n $!=0$, is satisfied by 3. The guard on Sub.recip(n) is simply true, which is also satisfied. However, if we had used the ERROR line's definition, the guard on Sub.recip ( n ) would be $\mathrm{n}!=0, \mathrm{n}!=3$, which is not satisfied by 3 , so - despite the call statically type-checking - at runtime the call would violate its guard and (in this case) throw an exception.

```
class Super {
    def recip(n:Int){n != 0} = 1.0/n;
}
class Sub extends Super{
    //ERROR: def recip(n:Int){n != 0, n != 3} = 1.0/(n * (n-3));
    def recip(m:Int){true} = 1.0/m;
}
```

```
class Example{
    static def example() {
        val s : Super = new Sub();
        s.recip(3);
    }
}
```

If a class $C$ overrides a method of a class or interface $B$, the guard of the method in B must entail the guard of the method in C .

A class C inherits from its direct superclass and superinterfaces all their methods visible according to the access modifiers of the superclass/superinterfaces that are not hidden or overridden. A method $M_{1}$ in a class $C$ overrides a method $M_{2}$ in a superclass $D$ if $M_{1}$ and $M_{2}$ have erasedly equivalent signatures. Methods are overriden on a signature-by-signature basis. It is a compile-time error if an instance method overrides a static method. (But is it permitted for an instance field to hide a static field; that's hiding ( $\$ 8.2 .2$ ), not overriding, and hence totally different.)

### 8.5 Constructors

Instances of classes are created by the new expression:

$$
\begin{aligned}
& \text { ObCreationExp }::=\text { new TypeName TypeArgs? (ArgumentList? ) ClassBody? } \\
& \mid \quad \text { Primary . new Id TypeArgs? (ArgumentList? ) ClassBody? } \\
& \text { FullyQualifiedName . new Id TypeArgs? (ArgumentList }{ }^{?} \text { ) } \\
& \text { ClassBody? }
\end{aligned}
$$

This constructs a new object, and calls some code, called a constructor, to initialize the newly-created object properly.
Constructors are defined like methods, except that they must be named this and ordinary methods may not be. The content of a constructor body has certain capabilities (e.g., val fields of the object may be initialized) and certain restrictions (e.g., most methods cannot be called); see 88.10 for the details.

## Example:

The following class provides two constructors. The unary constructor def this(b
: Int) allows initialization of the a field to an arbitrary value. The nullary constructor def this() gives it a default value of 10 . The example method illustrates both of these calls.

```
class C {
    public val a : Int;
    def this(b : Int) { a = b; }
    def this() {a=10; }
    static def example() {
        val two = new C(2);
        assert two.a == 2;
        val ten = new C();
        assert ten.a == 10;
    }
}
```


### 8.5.1 Automatic Generation of Constructors

Classes that have no constructors written in the class declaration are automatically given a constructor which sets the class properties and does nothing else. If this automatically-generated constructor is not valid (e.g., if the class has val fields that need to be initialized in a constructor), the class has no constructor, which is a static error.
Example: The following class has no explicit constructor. Its implicit constructor is def this( x : Int) \{property ( x ) ; \} This implicit constructor is valid, and so is the class.

```
class C(x:Int) {
    static def example() {
        val c : C = new C(4);
        assert c.x == 4;
    }
}
```

The following class has the same default constructor. However, that constructor does not initialize d , and thus is invalid. This class does not compile; it needs an explicit constructor.

```
// THIS CODE DOES NOT COMPILE
class Cfail(x:Int) {
    val d: Int;
    static def example() {
```

```
        val wrong = new Cfail(40);
    }
}
```


### 8.5.2 Calling Other Constructors

The first statement of a constructor body may be a call of the form this ( $a, b, c$ ) or super ( $a, b, c$ ). The former will execute the body of the matching constructor of the current class; the latter, of the superclass. This allows a measure of abstraction in constructor definitions; one may be defined in terms of another.
Example: The following class has two constructors. new Ctors (123) constructs a new Ctors object with parameter 123. new Ctors() constructs one whose parameter has a default value of 100:

```
class Ctors {
    public val a : Int;
    def this(a:Int) { this.a = a; }
    def this() { this(100); }
}
```

In the case of a class which implements operator () - or any other constructor and application with the same signature - this can be ambiguous. If this() appears as the first statement of a constructor body, it could, in principle, mean either a constructor call or an operator evaluation. This ambiguity is resolved so that this() always means the constructor invocation. If, for some reason, it is necessary to invoke an application operator as the first meaningful statement of a constructor, write the target of the application as (this), e.g., (this) (a,b);.

### 8.5.3 Return Type of Constructor

A constructor for class $C$ may have a return type $C\{c\}$. The return type specifies a constraint on the kind of object returned. It cannot change its class - a constructor for class C always returns an instance of class C. If no explicit return type is specified, the constructor's return type is inferred.

Example: The constructor (A) below, having no explicit return type, has its return type inferred. n is set by the property statement to 1 , so the return type is
inferred as Ret \{self. $\mathrm{n}==1\}$. The constructor (B) has Ret $\{\mathrm{n}==\mathrm{self} . \mathrm{n}\}$ as an explicit return type. The example() code shows both of these in action.

```
class Ret(n:Int) {
    def this() { property(1); } // (A)
    def this(n:Int) : Ret{n==self.n} { // (B)
        property(n);
    }
    static def typeIs[T](x:T){}
    static def example() {
        typeIs[Ret{self.n==1}](new Ret()); // uses (A)
        typeIs[Ret{self.n==3}](new Ret(3)); // uses (B)
    }
}
```


### 8.6 Static initialization

The X10 runtime implements the following procedure to ensure reliable initialization of the static state of classes.
Execution (of an entire X10 program) commences with a single thread executing the initialization phase of an X10 computation at place 0 . This phase must complete successfully before the body of the main method is executed.
The initialization phase should be thought of as if it is implemented in the following fashion. (The implementation may do something more efficient as long as it is faithful to this semantics.)

```
finish
    for every static field f of every class C
        (with type T and initializer e):
    async {
        val l = e;
        ateach (Dist.makeUnique()) {
            assign l to the static f field of
                    the local C class object;
            mark the f field of the local C
                class object as initialized;
        }
```

\}
During this phase, any read of a static field C. $f$ (where $f$ is of type T) is replaced by a call to the method C.read_f():T defined on class $C$ as follows

```
def read_f():T {
    when (initialized(C.f)){};
    return C.f;
}
```

If all these activities terminate normally, all static fields have values of their declared types, and the finish terminates normally. If any activity throws an exception, the finish throws an exception. Since no user code is executing which can catch exceptions thrown by the finish, such exceptions are printed on the console, and computation aborts.
If the activities deadlock, the implementation deadlocks.
In all cases, the main method is executed only once all static fields have been initialized correctly.
Since static state is immutable and is replicated to all places via the initialization phase as described above, it can be accessed from any place.

### 8.7 User-Defined Operators

| MethodDecln $::$ | MethMods def Id TypeParams? Formals Guard? |  |
| ---: | :--- | ---: | :--- |
|  | HasResultType? MethodBody |  |
|  | BinOpDecln |  |
|  | PrefixOpDecln |  |
| ApplyOpDecln |  |  |
|  | SetOpDecln |  |
| ConversionOpDecln |  |  |

It is often convenient to have methods named by symbols rather than words. For example, suppose that we wish to define a Poly class of polynomials - for the sake of illustration, single-variable polynomials with Int coefficients. It would be very nice to be able to manipulate these polynomials by the usual operations: + to add, * to multiply, - to subtract, and $p(x)$ to compute the value of the polynomial at argument x . We would like to write code thus:

```
public static def main(Array[String](1)):void \{
    val \(\mathrm{X}=\) new \(\operatorname{Poly}([0,1])\);
    val t <: Poly \(=7\) * \(\mathrm{X}+6\) * X * X * X ;
    val \(u<:\) Poly \(=3+5 * X-7 * X * X\);
    val v <: Poly = t * u - 1;
    for ( i in -3 .. 3) \{
        x10.io. Console.OUT.println(
            "" + i + " X:" + X(i) + " t:" + t(i)
            + " u:" + u(i) + " v:" + v(i)
        );
    \}
\}
```

Writing the same code with method calls, while possible, is far less elegant:

```
public static def uglymain() {
    val X = new UglyPoly([0,1]);
    val t <: UglyPoly
            = X.mult(7).plus(
            X.mult(X).mult(X).mult(6));
    val u <: UglyPoly
            = const(3).plus(
            X.mult(5)).minus(X.mult(X).mult(7));
    val v <: UglyPoly = t.mult(u).minus(1);
    for( i in -3 .. 3) {
        x10.io.Console.OUT.println(
            "" + i + " X:" + X.apply(i) + " t:" + t.apply(i)
            + " u:" + u.apply(i) + " v:" + v.apply(i)
        );
    }
}
```

The operator-using code can be written in X10, though a few variations are necessary to handle such exotic cases as $1+\mathrm{X}$.
Most X10 operators can be given definitions ${ }^{3}$ (However, \&\& and || are only shortcircuiting for Boolean expressions; user-defined versions of these operators have

[^17]no special execution behavior.)
The user-definable operations are (in order of precedence):

## implicit type coercions

postfix ()
as T
these unary operators: $-+!\sim \mid \& / \wedge * \%$

```
\begin{tabular}{llllllll}
\(*\) & \(/\) & \(\%\) & \(* *\) & & & \\
+ & - & & & & & \\
\(\ll\) & \(\gg\) & \(\ggg\) & \(->\) & \(<-\) & \(>-\) & \(-<\) & \(!\) \\
\(>\) & \(>=\) & \(<\) & \(<=\) & \(\sim\) & \(!\) & &
\end{tabular}

Several of these operators have no standard meaning on any library type, and are included purely for programmer convenience.
Many operators may be defined either in static or instance forms. Those defined in instance form are dynamically dispatched, just like an instance method. Those defined in static form are statically dispatched, just like a static method. Operators are scoped like methods; static operators are scoped like static methods.

\section*{Example:}
```

static class Trace(n:Int){
public static operator !(f:Trace)
= new Trace(10 * f.n + 1);
public operator -this = new Trace (10 * this.n + 2);
}
static class Brace extends Trace{

```
priveleges are (1) literals; (2) the . . operator won't compute the zeroBased and rail properties as it does for Int ranges; (3) * won't track ranks, as it does for Regions; (4) \&\& and || won't short-circuit, as they do for Booleans, (5) the built-in notion of equality \(\mathrm{a}==\mathrm{b}\) will only coincide with the programmible notion a. equals (b), as they do for most library types, if coded that way; and (6) it is impossible to define an operation like String. + which converts both its left and right arguments from any type. For example, a Polar type might have many representations for the origin, as radius 0 and any angle; these will be equals(), but will not be \(==\); whereas for the standard Complex type, the two equalities are the same.
```

    def this(n:Int) { super(n); }
    public operator -this = new Brace (10 * this.n + 3);
    static def example() {
        val t = new Trace(1);
        assert (!t).n == 11;
        assert (-t).n == 12 && (-t instanceof Trace);
        val b = new Brace(1);
        assert (!b).n == 11;
        assert (-b).n == 13 && (-b instanceof Brace);
    }
    }

```

\subsection*{8.7.1 Binary Operators}

Binary operators, illustrated by + , may be defined statically in a container A as:
```

static operator (b:B) + (c:C) = ...;

```

Or, it may be defined as as an instance operator by one of the forms:
```

operator this + (b:B) = ...;
operator (b:B) + this = ...;

```

\section*{Example:}

Defining the sum \(\mathrm{P}+\mathrm{Q}\) of two polynomials looks much like a method definition. It uses the operator keyword instead of def, and this appears in the definition in the place that a Poly would appear in a use of the operator. So, operator this
+ ( p : Poly) explains how to add this to a Poly value.
```

class Poly {

```
    public val coeff : Array[Int](1);
    public def this(coeff: Array[Int](1)) \{
        this.coeff = coeff; \(\}\)
    public def degree() = coeff.size-1;
    public def a(i:Int)
        \(=\) (i<0 || i>this.degree()) ? 0 : coeff(i);
    public operator this \(+(p: P o l y)=\) new Poly(
        new Array[Int](
            Math.max(this.coeff.size, p.coeff.size),
```

    (i:Int) => this.a(i) + p.a(i)
    ));
    // ...

```

The sum of a polynomial and an integer, \(\mathrm{P}+3\), looks like an overloaded method definition.
```

public operator this + (n : Int)
= new Poly([n as Int]) + this;

```

However, we want to allow the sum of integer and a polynomial as well: 3+P. It would be quite inconvenient to have to define this as a method on Int; changing Int is far outside of normal coding. So, we allow it as a method on Poly as well.
\[
\begin{aligned}
& \text { public operator (n : Int) + this } \\
& \text { = new Poly([n as Int]) + this; }
\end{aligned}
\]

Furthermore, it is sometimes convenient to express a binary operation as a static method on a class. The definition for the sum of two Polys could have been written:
```

public static operator (p:Poly) + (q:Poly) = new Poly(
new Array[Int](
Math.max(q.coeff.size, p.coeff.size),
(i:Int) => q.a(i) + p.a(i)
));

```

When X10 attempts to typecheck a binary operator expression like \(P+Q\), it first typechecks \(P\) and \(Q\). Then, it looks for operator declarations for + in the types of \(P\) and \(Q\). If there are none, it is a static error. If there is precisely one, that one will be used. If there are several, X10 looks for a best-matching operation, viz. one which does not require the operands to be converted to another type. For example, operator this + (n:Long) and operator this + (n:Int) both apply to \(p+1\), because 1 can be converted from an Int to a Long. However, the Int version will be chosen because it does not require a conversion. If even the best-matching operation is not uniquely determined, the compiler will report a static error.

\subsection*{8.7.2 Unary Operators}

Unary operators, illustrated by !, may be defined statically in container A as
```

static operator !(x:A) = ...;

```
or as instance operators by:
```

operator !this = ...;

```

The rules for typechecking a unary operation are the same as for methods; the complexities of binary operations are not needed.

Example: The operator to negate a polynomial is:
public operator - this = new Poly( new Array[Int] (coeff.size, (i:Int) => -coeff(i)) );

\subsection*{8.7.3 Type Conversions}

Explicit type conversions, e as A, can be defined as operators on class A, or on the container type of e. These must be static operators.

To define an operator in class A (or struct A) converting values of type B into type A, use the syntax:
```

static operator (x:B) as ? {c} = ...

```

The ? indicates the containing type A. The guard clause \(\{c\}\) may be omitted.

\section*{Example:}
```

class Poly {
public val coeff : Array[Int](1);
public def this(coeff: Array[Int](1)) { this.coeff = coeff;}
public static operator (a:Int) as ? = new Poly([a as Int]);
public static def main(Array[String](1)):void {
val three : Poly = 3 as Poly;
}
}

```

The ? may be given a bound, such as as ? <: Caster, if desired.
There is little difference between an explicit conversion e as T and a method call e.asT(). The explicit conversion does say undeniably what the result type will
be. However, as described in \(\$ 11.22 .3\), sometimes the built-in meaning of as as a cast overrides the user-defined explicit conversion.
Explicit casts are most suitable for cases which resemble the use of explicit casts among the arithmetic types, where, for example, 1.0 as Int is a way to turn a floating-point number into the corresponding integer. While there is nothing in X10 which requires it, e as T has the connotation that it gives a good approximation of e in type T, just as 1 is a good (indeed, perfect) approximation of 1.0 in type Int.

\subsection*{8.7.4 Implicit Type Coercions}

An implicit type conversion from \(U\) to \(T\) may be specified in container \(T\). The syntax for it is:
```

static operator (u:U) : T = e;

```

Implicit coercions are used automatically by the compiler on method calls (\$8.11) and assignments ( \(\$ 11.7\) ). Implicit coercions may be used when a value of type \(T\) appears in a context expecting a value of type U . If \(\mathrm{T}<\) : U , no implicit coercion is needed; e.g., a method \(m\) expecting an Int argument may be called as \(m\) (3), with an argument of type \(\operatorname{Int}\{\operatorname{self}==3\}\), which is a subtype of m's argument type Int. However, if it is not the case that \(\mathrm{T}<\) : U , but there is an implicit coercion from T to \(U\) defined in container \(U\), then this implicit coercion will be applied.
Example: We can define an implicit coercion from Int to Poly, and avoid having to define the sum of an integer and a polynomial as many special cases. In the following example, we only define + on two polynomials. The calculation \(1+\mathrm{x}\) coerces 1 to a polynomial and uses polynomial addition to add it to x .
```

public static operator (c : Int) : Poly
= new Poly([c as Int]);
public static operator (p:Poly) + (q:Poly) = new Poly(
new Array[Int](
Math.max(p.coeff.size, q.coeff.size),
(i:Int) => p.a(i) + q.a(i)
));
public static def main(Array[String](1)):void {

```
```

    val x = new Poly([0,1]);
    x10.io.Console.OUT.println("1+x=" + (1+x));
    }

```

\subsection*{8.7.5 Assignment and Application Operators}

X10 allows types to implement the subscripting / function application operator, and indexed assignment. The Array-like classes take advantage of both of these in \(a(i)=a(i)+1\).
\(a(b, c, d)\) is an operator call, to an operator defined with public operator this(b:B, c:C, d:D). It may be overloaded. For example, an ordered dictionary structure could allow subscripting by numbers with public operator this(i:Int), and by strings with public operator this(s:String).
\(a(i, j)=b\) is an operator as well, with zero or more indices \(i, j\). It may also be overloaded.

The update operations \(\mathrm{a}(\mathrm{i})+=\mathrm{b}\) (for all binary operators in place of + ) are defined to be the same as the corresponding \(a(i)=a(i)+b\). This applies for all arities of arguments, and all types, and all binary operations. Of course to use this, the + , application and assignment operators must be defined.

\section*{Example:}

The Oddvec class of somewhat peculiar vectors illustrates this.
a() returns a string representation of the oddvec, which ordinarily would be done by toString () instead. a(i) sensibly picks out one of the three coordinates of a. a()\(=\mathrm{b}\) sets all the coordinates of a to \(\mathrm{b} . \mathrm{a}(\mathrm{i})=\mathrm{b}\) assigns to one of the coordinates. \(\mathrm{a}(\mathrm{i}, \mathrm{j})=\mathrm{b}\) assigns different values to \(\mathrm{a}(\mathrm{i})\) and \(\mathrm{a}(\mathrm{j})\).
```

class Oddvec {
var v : Array[Int](1) = new Array[Int](3, (Int)=>0);
public operator this () =
"(" + v(0) + "," + v(1) + "," + v(2) + ")";
public operator this () = (newval: Int) {
for(p in v) v(p) = newval;
}
public operator this(i:Int) = v(i);
public operator this(i:Int, j:Int) = [v(i),v(j)];

```
```

public operator this(i:Int) = (newval:Int)
= {v(i) = newval;}
public operator this(i:Int, j:Int) = (newval:Int)
= { v(i) = newval; v(j) = newval+1;}
public def example() {
this(1) = 6; assert this(1) == 6;
this(1) += 7; assert this(1) == 13;
}

```

\subsection*{8.8 Class Guards and Invariants}

Classes (and structs and interfaces) may specify a class guard, a constraint which must hold on all values of the class. In the following example, a Line is defined by two distinct Pts \(\int^{4}\)
```

class Pt(x:Int, y:Int){}
class Line(a:Pt, b:Pt){a != b} {}

```

In most cases the class guard could be phrased as a type constraint on a property of the class instead, if preferred. Arguably, a symmetric constraint like two points being different is better expressed as a class guard, rather than asymmetrically as a constraint on one type:
```

class Line(a:Pt, b:Pt{a != b}) {}

```

With every container or interface T we associate a type invariant \(\operatorname{inv}(\mathrm{T})\), which describes the guarantees on the properties of values of type \(T\).

Every value of T satisfies \(\operatorname{inv}(\mathrm{T})\) at all times. This is somewhat stronger than the concept of type invariant in most languages (which only requires that the invariant holds when no method calls are active). X10 invariants only concern properties, which are immutable; thus, once established, they cannot be falsified.
The type invariant associated with \(\times 10\). lang. Any is true.
The type invariant associated with any interface or struct I that extends interfaces \(\mathrm{I}_{1}, \ldots, \mathrm{I}_{k}\) and defines properties \(\mathrm{x}_{1}: \mathrm{P}_{1}, \ldots, \mathrm{x}_{n}: \mathrm{P}_{n}\) and specifies a guard c is given by:

\footnotetext{
\({ }^{4}\) We use Pt to avoid any possible confusion with the built-in class Point.
}
```

inv( }\mp@subsup{\textrm{I}}{1}{}) \&\& ... \&\& inv ( (I ) \&\&

```

```

\&\& c

```

Similarly the type invariant associated with any class \(C\) that implements interfaces \(\mathrm{I}_{1}, \ldots, \mathrm{I}_{k}\), extends class D and defines properties \(\mathrm{x}_{1}: \mathrm{P}_{1}, \ldots, \mathrm{x}_{n}: \mathrm{P}_{n}\) and specifies a guard \(c\) is given by the same thing with the invariant of the superclass D conjoined:
```

$\operatorname{inv}\left(\mathrm{I}_{1}\right) \& \& \ldots \& \& \operatorname{inv}\left(\mathrm{I}_{k}\right)$
\&\& self. $\mathrm{x}_{1}$ instanceof $\mathrm{P}_{1} \& \& \ldots$... \& self. $\mathrm{x}_{n}$ instanceof $\mathrm{P}_{n}$
\& c
\&\& inv(D)

```

Note that the type invariant associated with a class entails the type invariants of each interface that it implements (directly or indirectly), and the type invariant of each ancestor class. It is guaranteed that for any variable v of type \(\mathrm{T}\{\mathrm{c}\}\) (where T is an interface name or a class name) the only objects o that may be stored in v are such that o satisfies \(\operatorname{inv}(\mathrm{T}[\mathrm{o} /\) this \(]) \wedge \mathrm{c}[\mathrm{o} / \mathrm{self}]\).

\subsection*{8.8.1 Invariants for implements and extends clauses}

Consider a class definition
```

ClassModifiers?
class $\mathrm{C}\left(\mathrm{x}_{1}: \mathrm{P}_{1}, \ldots, \mathrm{x}_{n}: \mathrm{P}_{n}\right)\{\mathrm{c}\}$ extends $\mathrm{D}\{\mathrm{d}\}$
implements $\mathrm{I}_{1}\left\{\mathrm{c}_{1}\right\}, \ldots, \mathrm{I}_{k}\left\{\mathrm{c}_{k}\right\}$
ClassBody

```

These two rules must be satisfied:
- The type invariant \(\operatorname{inv}(\mathrm{C})\) of C must entail \(\mathrm{c}_{i}\) [this/self] for each \(i\) in \(\{1, \ldots, k\}\)
- The return type cof each constructor in a class C must entail the invariant inv (C).

\subsection*{8.8.2 Timing of Invariant Checks}

The invariants for a container are checked immediately after the property statement in the container's constructor. This is the earliest that the invariant could possibly be checked. Recall that an invariant can mention the properties of the container (which are set, forever, at that point in the code), but cannot mention the val or var fields (which might not be set at that point), or this (which might not have been fully initialized).
If X10 can prove that the invariant always holds given the property statement and other known information, it may omit the actual check.

\subsection*{8.8.3 Invariants and constructor definitions}

A constructor for a class \(C\) is guaranteed to return an object of the class on successful termination. This object must satisfy inv (C), the class invariant associated with C (\$8.8). However, often the objects returned by a constructor may satisfy stronger properties than the class invariant. X10's dependent type system permits these extra properties to be asserted with the constructor in the form of a constrained type (the "return type" of the constructor):
\[
\begin{aligned}
\text { CtorDecln }::= & \text { Mods }^{?} \text { def this TypeParams? Formals Guard? 20.53) } \\
& \text { HasResultType }{ }^{?} \text { CtorBody }
\end{aligned}
\]

The parameter list for the constructor may specify a guard that is to be satisfied by the parameters to the list.

Example: Here is another example, constructed as a simplified version of x10. array. Region. The mockUnion method has the type, though not the value, that a true union method would have.
```

class MyRegion(rank:Int) {
static type MyRegion(n:Int)=MyRegion{rank==n};
def this(r:Int):MyRegion(r) {
property(r);
}
def this(diag:Array[Int](1)):MyRegion(diag.size){
property(diag.size);
}
def mockUnion(r:MyRegion(rank)):MyRegion(rank) = this;

```
```

    def example() {
        val R1 : MyRegion(3) = new MyRegion([4,4,4 as Int]);
        val R2 : MyRegion(3) = new MyRegion([5,4,1]);
        val R3 = R1.mockUnion(R2); // inferred type MyRegion(3)
    }
    }

```

The first constructor returns the empty region of rank r . The second constructor takes a Array[Int] (1) of arbitrary length n and returns a MyRegion( n ) (intended to represent the set of points in the rectangular parallelopiped between the origin and the diag.)
The code in example typechecks, and R3's type is inferred as MyRegion(3).
Let C be a class with properties \(\mathrm{p}_{1}: \mathrm{P}_{1}, \ldots, \mathrm{p}_{n}: \mathrm{P}_{n}\), and invariant c extending the constrained type \(D\{d\}\) (where \(D\) is the name of a class).
For every constructor in C the compiler checks that the call to super invokes a constructor for D whose return type is strong enough to entail d. Specifically, if the call to super is of the form super \(\left(\mathrm{e}_{1}, \ldots, \mathrm{e}_{k}\right)\) and the static type of each expression \(\mathrm{e}_{i}\) is \(\mathrm{S}_{i}\), and the invocation is statically resolved to a constructor def this \(\left(\mathrm{x}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{x}_{k}: \mathrm{T}_{k}\right)\{\mathrm{c}\}: \mathrm{D}\left\{\mathrm{d}_{1}\right\}\) then it must be the case that
\[
\begin{aligned}
& \mathrm{x}_{1}: \mathrm{S}_{1}, \ldots, \mathrm{x}_{i}: \mathrm{S}_{i} \text { entails } \mathrm{x}_{i}: \mathrm{T}_{i} \quad \text { (for } i \in\{1, \ldots, k\} \text { ) } \\
& \mathrm{x}_{1}: \mathrm{S}_{1}, \ldots, \mathrm{x}_{k}: \mathrm{S}_{k} \text { entails } \mathrm{c} \\
& \mathrm{~d}_{1}[\mathrm{a} / \mathrm{self}], \mathrm{x}_{1}: \mathrm{S}_{1}, \ldots, \mathrm{x}_{k}: \mathrm{S}_{k} \text { entails } \mathrm{d}[\mathrm{a} / \mathrm{self}]
\end{aligned}
\]
where \(a\) is a constant that does not appear in \(\mathrm{x}_{1}: \mathrm{S}_{1} \wedge \ldots \wedge \mathrm{x}_{k}: \mathrm{S}_{k}\).
The compiler checks that every constructor for \(C\) ensures that the properties \(p_{1}, \ldots\), \(\mathrm{p}_{n}\) are initialized with values which satisfy \(\operatorname{inv}(\mathrm{T})\), and its own return type c' as follows. In each constructor, the compiler checks that the static types \(\mathrm{T}_{i}\) of the expressions \(\mathbf{e}_{i}\) assigned to \(\mathrm{p}_{i}\) are such that the following is true:
\[
\mathrm{p}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{p}_{n}: \mathrm{T}_{n} \text { entails } \operatorname{inv}(\mathrm{T}) \wedge \mathrm{c}^{\prime}
\]
(Note that for the assignment of \(\mathrm{e}_{i}\) to \(\mathrm{p}_{i}\) to be type-correct it must be the case that \(\mathrm{p}_{i}: \mathrm{T}_{i} \wedge \mathrm{p}_{i}: \mathrm{P}_{i}\).)
The compiler must check that every invocation \(C\left(\mathrm{e}_{1}, \ldots, \mathrm{e}_{n}\right)\) to a constructor is type correct: each argument \(\mathrm{e}_{i}\) must have a static type that is a subtype of the declared type \(\mathrm{T}_{i}\) for the \(i\) th argument of the constructor, and the conjunction of static types of the argument must entail the constraint in the parameter list of the constructor.

\subsection*{8.9 Generic Classes}

Classes, like other units, can be generic. They can be parameterized by types. The parameter types are used just like ordinary types inside the body of the generic class - with a few exceptions.
Example: A Colorized[T] holds a thing of type T, and a string which is intended to represent its color. Any type can be used for T; the example method shows Int and Boolean. The thing() method retrieves the thing; note that its return type is the generic type variable T. X10 is aware that colInt.thing() is an Int and colTrue. thing() is a Boolean, and uses those typings in example.
```

class Colorized[T] {
private var thing:T;
private var color:String;
def this(thing:T, color:String) {
this.thing = thing;
this.color = color;
}
public def thing():T = thing;
public def color():String = color;
public static def example() {
val colInt : Colorized[Int]
= new Colorized[Int](3,);
assert colInt.thing() == 3
\&\& colInt.color().equals("green");
val colTrue : Colorized[Boolean]
= new Colorized[Boolean](true,);
assert colTrue.thing()
\&\& colTrue.color().equals("blue");
}
}

```

\subsection*{8.9.1 Use of Generics}

An unconstrained type variable \(X\) can be instantiated by any type. All the operations of Any are available on a variable of type X. Additionally, variables of type X may be used with \(==, \quad!=\), in instanceof, and casts.

If a type variable is constrained, the operations implied by its constraint are available as well.
Example: The interface Named describes entities which know their own name. The class NameMap [T] is a specialized map which stores and retrieves Named entities by name. The call t . name() in put() is only valid because the constraint \{ \(\mathrm{T}<\) : Named\} implies that T is a subtype of Named, and hence provides all the operations of Named.
```

interface Named { def name():String; }
class NameMap[T]{T <: Named} {
val m = new HashMap[String, T]();
def put(t:T) { m.put(t.name(), t); }
def get(s:String):T = m.getOrThrow(s);
}

```

\subsection*{8.10 Object Initialization}

X10 does object initialization safely. It avoids certain bad things which trouble some other languages:
1. Use of a field before the field has been initialized.
2. A program reading two different values from a val field of a container.
3. this escaping from a constructor, which can cause problems as noted below.

It should be unsurprising that fields must not be used before they are initialized. At best, it is uncertain what value will be in them, as in \(x\) below. Worse, the value might not even be an allowable value; \(y\), declared to be nonzero in the following example, might be zero before it is initialized.
```

// Not correct X10
class ThisIsWrong {
val x : Int;
val y : Int{y != 0};
def this() {
x10.io.Console.OUT.println("x=" + x + "; y=" + y);

```
```

        x = 1; y = 2;
    }
    }

```

One particularly insidious way to read uninitialized fields is to allow this to escape from a constructor. For example, the constructor could put this into a data structure before initializing it, and another activity could read it from the data structure and look at its fields:
```

class Wrong {
val shouldBe8 : Int;
static Cell[Wrong] wrongCell = new Cell[Wrong]();
static def doItWrong() {
finish {
async { new Wrong(); } // (A)
assert( wrongCell().shouldBe8 == 8); // (B)
}
}
def this() {
wrongCell.set(this); // (C) - ILLEGAL
this.shouldBe8 = 8; // (D)
}
}

```

In this example, the underconstructed Wrong object is leaked into a storage cell at line (C), and then initialized. The doItWrong method constructs a new Wrong object, and looks at the Wrong object in the storage cell to check on its shouldBe8 field. One possible order of events is the following:
1. doItWrong() is called.
2. (A) is started. Space for a new Wrong object is allocated. Its shouldBe8 field, not yet initialized, contains some garbage value.
3. (C) is executed, as part of the process of constructing a new Wrong object. The new, uninitialized object is stored in wrongCell.
4. Now, the initialization activity is paused, and execution of the main activity proceeds from (B).
5. The value in wrongCell is retrieved, and is shouldBe8 field is read. This field contains garbage, and the assertion fails.
6. Now let the initialization activity proceed with (D), initializing shouldBe8 - too late.

The at statement ( \(\S 13.3\) ) introduces the potential for escape as well. The following class prints an uninitialized value:
```

// This code violates this chapter's constraints
// and thus will not compile in X10.
class Example {
val a: Int;
def this() {
at(here.next()) {
// Recall that 'this' is a copy of 'this' outside 'at'.
Console.OUT.println("this.a = " + this.a);
}
this.a = 1;
}
}

```

X10 must protect against such possibilities. The rules explaining how constructors can be written are somewhat intricate; they are designed to allow as much programming as possible without leading to potential problems. Ultimately, they simply are elaborations of the fundamental principles that uninitialized fields must never be read, and this must never be leaked.

\subsection*{8.10.1 Constructors and Non-Escaping Methods}

In general, constructors must not be allowed to call methods with this as an argument or receiver. Such calls could leak references to this, either directly from a call to cell.set(this), or indirectly because toString leaks this, and the concatenation ' "Escaper \(=\) " + this' calls toString \({ }^{5}\)
// This code violates this chapter's constraints
// and thus will not compile in X10.

\footnotetext{
\({ }^{5}\) This is abominable behavior for toString, but it cannot be prevented - save by a scheme such as we present in this section.
}
```

class Escaper {
static val Cell[Escaper] cell = new Cell[Escaper]();
def toString() {
cell.set(this);
return "Evil!";
}
def this() {
cell.set(this);
x10.io.Console.OUT.println("Escaper = " + this);
}
}

```

However, it is convenient to be able to call methods from constructors; e.g., a class might have eleven constructors whose common behavior is best described by three methods. Under certain stringent conditions, it is safe to call a method: the method called must not leak references to this, and must not read vals or vars which might not have been assigned.
So, X10 performs a static dataflow analysis, sufficient to guarantee that method calls in constructors are safe. This analysis requires having access to or guarantees about all the code that could possibly be called. This can be accomplished in two ways:
1. Ensuring that only code from the class itself can be called, by forbidding overriding of methods called from the constructor: they can be marked final or private, or the whole class can be final.
2. Marking the methods called from the constructor by @NonEscaping or @NoThisAccess

\section*{Non-Escaping Methods}

A method may be annotated with @NonEscaping. This imposes several restrictions on the method body, and on all methods overriding it. However, it is the only way that a method can be called from constructors. The @NonEscaping annotation makes explicit all the X10 compiler's needs for constructor-safety.
A method can, however, be safe to call from constructors without being marked @NonEscaping. We call such methods implicitly non-escaping. Implicitly nonescaping methods need to obey the same constraints on this, super, and variable
usage as @NonEscaping methods. An implicitly non-escaping method could be marked as @NonEscaping; the compiler, in effect, infers the annotation. In addition, all non-escaping methods must be private or final or members of a final class; this corresponds to the hereditary nature of @NonEscaping (by forbidding inheritance of implicitly non-escaping methods).
We say that a method is non-escaping if it is either implicitly non-escaping, or annotated @NonEscaping.
The first requirement on non-escaping methods is that they do not allow this to escape. Inside of their bodies, this and super may only be used for field access and assignment, and as the receiver of non-escaping methods.
The following example uses the possible variations. aplomb() explicitly forbids reading any field but a . boric() is called after a and b are set, but c is not. The @NonEscaping annotation on boric() is optional, but the compiler will print a warning if it is left out. cajoled() is only called after all fields are set, so it can read anything; its annotation, too, is not required. SeeAlso is able to override aplomb(), because aplomb() is @NonEscaping; it cannot override the final method boric() or the private one cajoled().
```

import x10.compiler.*;
final class C2 {
protected val a:Int; protected val b:Int; protected val c:Int;
protected var x:Int; protected var y:Int; protected var z:Int;
def this() {
a = 1;
this.aplomb();
b = 2;
this.boric();
c = 3;
this.cajoled();
}
@NonEscaping def aplomb() {
x = a;
// this.boric(); // not allowed; boric reads b.
// z = b; // not allowed -- only 'a' can be read here
}
@NonEscaping final def boric() {
y = b;

```
```

        this.aplomb(); // allowed;
            // a is definitely set before boric is called
        // z = c; // not allowed; c is not definitely written
    }
    @NonEscaping private def cajoled() {
        z = c;
    }
    }

```

\section*{NoThisAccess Methods}

A method may be annotated @NoThisAccess. @NoThisAccess methods may be called from constructors, and they may be overridden in subclasses. However, they may not refer to this in any way - in particular, they cannot refer to fields of this, nor to super.

\section*{Example:}

The class IDed has an Float-valued id field. The method count() is used to initialize the id. For IDed objects, the id is the count of IDeds created with the same parity of its kind. Note that count () does not refer to this, though it does refer to a static field counts.
The subclass SubIDed has ids that depend on kind\%3 as well as the parity of kind. It overrides the count () method. The body of count () still cannot refer to this. Nor can it refer to super (which is self under another name). This precludes the use of a super call. This is why we have separated the body of count out as the static method kind2count - without that, we would have had to duplicate its body, as we could not call super. count (kind) in a NoThisAccess method, as is shown by the ERROR line (A).

Note that NoThisAccess is in x 10 . compiler and must be imported, and that the overriding method SubIDed. count must be declared @NoThisAccess as well as the overridden method. Line (B) is not allowed because code is a field of this, and field accesses are forbidden. Line (C) references this directly, which, of course, is forbidden by @NoThisAccess.
```

import x10.compiler.*;
class UseNoThisAccess {
static class IDed {

```
```

            protected static val counts = [0 as Int,0];
            protected var code : Int;
            val id: Float;
            public def this(kind:Int) {
            code = kind;
            this.id = this.count(kind);
        }
        protected static def kind2count(kind:Int) = ++counts(kind % 2);
        @NoThisAccess def count(kind:Int) : Float = kind2count(kind);
    }
    static class SubIDed extends IDed {
        protected static val subcounts = [0 as Int, 0, 0];
        public static val all = new x10.util.ArrayList[SubIDed]();
        public def this(kind:Int) {
            super(kind);
        }
        @NoThisAccess
        def count(kind:Int) : Float {
            val subcount <: Int = ++subcounts(kind % 3);
            val supercount <: Float = kind2count(kind);
            //ERROR: val badSuperCount = super.count(kind); //(A)
            //ERROR: code = kind; //(B)
            //ERROR: all.add(this); //(C)
            return supercount + 1.0f / subcount;
        }
    }
    }

```

\subsection*{8.10.2 Fine Structure of Constructors}

The code of a constructor consists of four segments, three of them optional and one of them implicit.
1. The first segment is an optional call to this (...) or super (...). If this is supplied, it must be the first statement of the constructor. If it is not supplied, the compiler treats it as a nullary super-call super ();
2. If the class or struct has properties, there must be a single property (...) command in the constructor, or a this(...) constructor call. Every execution path through the constructor must go through this property (...) command precisely once. The second segment of the constructor is the code following the first segment, up to and including the property () statement.

If the class or struct has no properties, the property() call must be omitted. If it is present, the second segment is defined as before. If it is absent, the second segment is empty.
3. The third segment is automatically generated. Fields with initializers are initialized immediately after the property statement. In the following example, \(b\) is initialized to \(y * 9000\) in segment three. The initialization makes sense and does the right thing; b will be \(y * 9000\) for every Overdone object. (This would not be possible if field initializers were processed earlier, before properties were set.)
4. The fourth segment is the remainder of the constructor body.

The segments in the following code are shown in the comments.
```

class Overlord(x:Int) {
def this(x:Int) { property(x); }
}//Overlord
class Overdone(y:Int) extends Overlord {
val a : Int;
val b = y * 9000;
def this(r:Int) {
super(r); // (1)
x10.io.Console.OUT.println(r); // (2)
val rp1 = r+1;
property(rp1); // (2)
// field initializations here // (3)
a = r + 2 + b; // (4)
}
def this() {
this(10); // (1), (2), (3)
val x = a + b; // (4)
}
}//Overdone

```

The rules of what is allowed in the three segments are different, though unsurprising. For example, properties of the current class can only be read in segment 3 or 4 -naturally, because they are set at the end of segment 2.

\section*{Initialization and Inner Classses}

Constructors of inner classes are tantamount to method calls on this. For example, the constructor for Inner is acceptable. It does not leak this. It leaks Outer.this, which is an utterly different object. So, the call to this.new Inner() in the Outer constructor is illegal. It would leak this. There is no special rule in effect preventing this; a constructor call of an inner class is no different from a method as far as leaking is concerned.
```

class Outer {
static val leak : Cell[Outer] = new Cell[Outer](null);
class Inner {
def this() {Outer.leak.set(Outer.this);}
}
def /*Outer*/this() {
//ERROR: val inner = this.new Inner();
}
}

```

\section*{Initialization and Closures}

Closures in constructors may not refer to this. They may not even refer to fields of this that have been initialized. For example, the closure bad1 is not allowed because it refers to this; bad2 is not allowed because it mentions a - which is, of course, identical to this.a.
```

class C {
val a:Int;
def this() {
this.a = 1;
//ERROR: val bad1 = () => this;
//ERROR: val bad2 = () => a*10;
}
}

```

\subsection*{8.10.3 Definite Initialization in Constructors}

An instance field var \(\mathrm{x}: \mathrm{T}\), when T has a default value, need not be explicitly initialized. In this case, \(x\) will be initialized to the default value of type T. For example, a Score object will have its currently field initialized to zero, below:
```

class Score {
public var currently : Int;
}

```

All other sorts of instance fields do need to be initialized before they can be used. val fields must be initialized in the constructor, even if their type has a default value. It would be silly to have a field val z : Int that was always given default value of \(Q\) and, since it is val, can never be changed. var fields whose type has no default value must be initialized as well, such as var y : Int \(\{\mathrm{y}!=0\}\), since it cannot be assigned a sensible initial value.
The fundamental principles are:
1. val fields must be assigned precisely once in each constructor on every possible execution path.
2. var fields of defaultless type must be assigned at least once on every possible execution path, but may be assigned more than once.
3. No variable may be read before it is guaranteed to have been assigned.
4. Initialization may be by field initialization expressions (val \(\mathrm{x}:\) Int \(=\) \(\mathrm{y}+\mathrm{z}\) ), or by uninitialized fields val x : Int; plus an initializing assignment \(x=y+z\). Recall that field initialization expressions are performed after the property statement, in segment 3 in the terminology of \(\$ 8.10 .2\).

\subsection*{8.10.4 Summary of Restrictions on Classes and Constructors}

The following table tells whether a given feature is (yes), is not (no) or is with some conditions (note) allowed in a given context. For example, a property method is allowed with the type of another property, as long as it only mentions the preceding properties. The first column of the table gives examples, by line of the following code body.
\begin{tabular}{||l|l|c|c|c|c|c|}
\hline & Example & Prop. & self==this(1) & Prop.Meth. & this & fields \\
\hline Type of property & (A) & yes (2) & no & no & no & no \\
\hline Class Invariant & (B) & yes & yes & yes & yes & no \\
\hline Supertype (3) & (C), (D) & yes & yes & yes & no & no \\
\hline Property Method Body & (E) & yes & yes & yes & yes & no \\
\hline Static field (4) & (F) (G) & no & no & no & no & no \\
\hline Instance field (5) & (H), (I) & yes & yes & yes & yes & yes \\
\hline Constructor arg. type & (J) & no & no & no & no & no \\
\hline Constructor guard & (K) & no & no & no & no & no \\
\hline Constructor ret. type & (L) & yes & yes & yes & yes & yes \\
\hline Constructor segment 1 & (M) & no & yes & no & no & no \\
\hline Constructor segment 2 & (N) & no & yes & no & no & no \\
\hline Constructor segment 4 & (O) & yes & yes & yes & yes & yes \\
\hline Methods & (P) & yes & yes & yes & yes & yes \\
\hline
\end{tabular}

Details:
- (1) Top-level self only.
- (2) The type of the \(i^{\text {th }}\) property may only mention properties 1 through \(i\).
- (3) Super-interfaces follow the same rules as supertypes.
- (4) The same rules apply to types and initializers.

The example indices refer to the following code:
```

class Example (
prop : Int,
proq : Int{prop != proq}, // (A)
pror : Int
)
{prop != 0} // (B)
extends Supertype[Int{self != prop}] // (C)
implements SuperInterface[Int{self != prop}] // (D)
{
property def propmeth() = (prop == pror); // (E)
static staticField
: Cell[Int{self != 0}] // (F)

```
```

    = new Cell[Int\{self != 0\}](1); // (G)
    var instanceField
    : Int \{self != prop\} // (H)
    \(=\) (prop + 1) as Int\{self != prop\}; // (I)
    def this(
    a : Int\{a != 0 \},
    b : Int \(\{\mathrm{b}\) != a\} // (J)
    )
    \{a != b\} // (K)
    : Example\{self.prop == a \&\& self.proq==b\} // (L)
    \{
    super();
    // (M)
    property(a,b,a); // (N)
    // fields initialized here
    instanceField = b as Int\{self != prop\}; // (0)
    \}
    def someMethod() =
        prop + staticField() + instanceField; // (P)
    \}

```

\subsection*{8.11 Method Resolution}

Method resolution is the problem of determining, statically, which method (or constructor or operator) should be invoked, when there are several choices that could be invoked. For example, the following class has two overloaded zap methods, one taking an Object, and the other a Resolve. Method resolution will figure out that the call zap (1..4) should call zap (Object), and zap (new Resolve()) should call zap(Resolve).

\section*{Example:}
```

class Res {
public static interface Surface {}
public static interface Deface {}
public static class Ace implements Surface {

```
```

    public static operator (Boolean) : Ace = new Ace();
    public static operator (Place) : Ace = new Ace();
    }
public static class Face implements Surface, Deface{}
public static class A {}
public static class B extends A {}
public static class C extends B {}
def m(x:A) = 0;
def m(x:Int) = 1;
def m(x:Boolean) = 2;
def m(x:Surface) = 3;
def m(x:Deface) = 4;
def example() {
assert m(100) == 1 : "Int";
assert m(new C()) == 0 : "C";
// An Ace is a Surface, unambiguous best choice
assert m(new Ace()) == 3 : "Ace";
// ERROR: m(new Face());
// The match must be exact.
// ERROR: assert m(here) == 3 : "Place";
// Boolean could be handled directly, or by
// implicit coercion Boolean -> Ace.
// Direct matches always win.
assert m(true) == 2 : "Boolean";
}

```

In the "Int" line, there is a very close match. 100 is an Int. In fact, 100 is an \(\operatorname{Int}\{\mathrm{sel} \mathrm{f}==100\}\), so even in this case the type of the actual parameter is not precisely equal to the type of the method.

In the " C " line of the example, new C() is an instance of C , which is a subtype of A, so the A method applies. No other method does, and so the A method will be invoked.

Similarly, in the "Ace" line, the Ace class implements Surface, and so new Ace() matches the Surface method.

However, a Face is both a Surface and a Deface, so there is no unique best match for the invocation m(new Face()). This invocation would be forbidden, and a compile-time error issued.

The match must be exact. There is an implicit coercion from Place to Ace, and Ace implements Surface, so the code
```

val ace : Ace = here;
assert m(ace) == 3;

```
works, by using the Surface form of m. But doing it in one step requires a deeper search than X10 performs and is not allowed.
For m(true), both the Boolean and, with the implicit coercion, Ace methods could apply. Since the Boolean method applies directly, and the Ace method requires an implicit coercion, this call resolves to the Boolean method, without an error.

The basic concept of method resolution is:
1. List all the methods that could possibly be used, inferring generic types but not performing implicit coercions.
2. If one possible method is more specific than all the others, that one is the desired method.
3. If there are two or more methods neither of which is more specific than the others, then the method invocation is ambiguous. Method resolution fails and reports an error.
4. Otherwise, no possible methods were found without implicit coercions. Try the preceding steps again, but with coercions allowed: zero or one implicit coercion for each argument. If a single most specific method is found with coercions, it is the desired method. If there are several, the invocation is ambiguous and erronious.
5. If no methods were found even with coercions, then the method invocation is undetermined. Method resolution fails and reports an error.

\footnotetext{
\({ }^{6}\) In general this search is unbounded, so X10 can't perform it.
}

After method resolution is done, there is a validation phase that checks the legality of the call, based on the STATIC_CHECKS compiler flag. With STATIC_CHECKS, the method's constraints must be satisfied; that is, they must be entailed ( \(\$ 4.5 .2\) ) by the information in force at the point of the call. With DYNAMIC_CHECKS, if the constraint is not entailed at that point, a dynamic check is inserted to make sure that it is true at runtime.

In the presence of X10's highly-detailed type system, some subtleties arise. One point, at least, is not subtle. The same procedure is used, mutatis mutandis for method, constructor, and operator resolution.

\subsection*{8.11.1 Space of Methods}

X10 allows some constructs, particularly operators, to be defined in a number of ways, and invoked in a number of ways. This section specifies which forms of definition could correspond to a given definiendum.
Method invocations a.m(b), where a is an expression, can be either of the following forms. There may be any number of arguments.
- An instance method on \(a\), of the form def \(m(B)\).
- A static method on a's class, of the form static def m(B).

The meaning of an invocation of the form \(m(b)\), with any number of arguments, depends slightly on its context. Inside of a constraint, it might mean self.m(b). Outside of a constraint, there is no self defined, so it can't mean that. The first of these that applies will be chosen.
1. Invoke a method on this, viz. this.m(b). Inside a constraint, it may also invoke a property method on self, viz.. self.m(b). It is an error if both this.m(b) and self.m(b) are possible.
2. Invoke a function named \(m\) in a local or field.
3. Construct a structure named m .

Static method invocations, A.m(b), where A is a container name, can only be static. There may be any number of arguments.
- A static method on \(A\), of the form static def \(m(B)\).

Constructor invocations, new A(b), must invoke constructors. There may be any number of arguments.
- A constructor on \(A\), of the form def this(B).

A unary operator \(\star\) a may be defined as:
- An instance operator on A, defined as operator \(\star\) this().
- A static operator on A, defined as operator \(\star(\mathrm{a}: \mathrm{A})\).

A binary operator \(\mathrm{a} \star \mathrm{b}\) may be defined as:
- An instance operator on \(A\), defined as operator this \(\star(b: B)\); or
- A right-hand operator on B, defined as operator (a:A) \(\star\) this; or
- A static operator on A, defined as operator (a:A) \(\star\) (b:B), ; or
- A static operator on B, if A and B are different classes, defined as operator (a:A) \(\star(b: B)\)

If none of those resolve to a method, then either operand may be implicitly coerced to the other. If one of the following two situations obtains, it will be done; if both, the expression causes a static error.
- An implicit coercion from \(A\) to \(B\), and an operator \(B \star B\) can be used, by coercing a to be of type B, and then using B's \(\star\).
- An implicit coercion from B to A, and an operator \(A \star A\) can be used, coercing \(b\) to be of type \(A\), and then using A's \(\star\).

An application a(b), for any number of arguments, can come from a number of things.
- an application operator on a, defined as operator this(b:B);
- If \(a\) is an identifier, \(a(b)\) can also be a method invocation equivalent to this.a(b), which invokes a as either an instance or static method on this
- If \(a\) is a qualified identifier, \(a(b)\) can also be an invocation of a struct constructor.

An indexed assignment, \(a(b)=c\), for any number of b's, can only come from an indexed assignment definition:
- operator this(b:B)=(c:C) \{...\}

An implicit coercion, in which a value \(\mathrm{a}: \mathrm{A}\) is used in a context which requires a value of some other non-subtype \(B\), can only come from implicit coercion operation defined on B :
- an implicit coercion in B: static operator (a:A):B;

An explicit conversion a as B can come from an explicit conversion operator, or an implicit coercion operator. X10 tries two things, in order, only checking 2 if 1 fails:
1. An as operator in B: static operator (a:A) as ?;
2. or, failing that, an implicit coercion in B: static operator (a:A):B.

\subsection*{8.11.2 Possible Methods}

This section describes what it means for a method to be a possible resolution of a method invocation.

Generics introduce several subtleties, especially with the inference of generic types. For the purposes of method resolution, all that matters about a method, constructor, or operator M - we use the word "method" to include all three choices for this section - is its signature, plus which method it is. So, a typical M might look like def \(m\left[\mathrm{G}_{1}, \ldots, \mathrm{G}_{g}\right]\left(\mathrm{x}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{x}_{f}: \mathrm{T}_{f}\right)\{\mathrm{c}\}=\ldots\) The code body \(\ldots\) is irrelevant for the purpose of whether a given method call means M or not, so we ignore it for this section.
All that matters about a method definition, for the purposes of method resolution, is:
1. The method name \(m\);
2. The generic type parameters of the method \(\mathrm{m}, \mathrm{G}_{1}, \ldots, \mathrm{G}_{g}\). If there are no generic type parameters, \(g=0\).
3. The types \(\mathrm{x}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{x}_{f}: \mathrm{T}_{f}\) of the formal parameters. If there are no formal parameters, \(f=0\). In the case of an instance method, the receiver will be the first formal parameter \([7\)
4. A unique identifier id, sufficient to tell the compiler which method body is intended. A file name and position in that file would suffice. The details of the identifier are not relevant.

For the purposes of understanding method resolution, we assume that all the actual parameters of an invocation are simply variables: \(x 1\).meth \((x 2, x 3)\). This is done routinely by the compiler in any case; the code tbl(i).meth(true, a+1) would be treated roughly as
```

val x1 = tbl(i);
val x2 = true;
val x3 = a+1;
x1.meth(x2,x3);

```

All that matters about an invocation I is:
1. The method name \(\mathrm{m}^{\prime}\);
2. The generic type parameters \(\mathrm{G}_{1}^{\prime}, \ldots, \mathrm{G}_{g}^{\prime}\). If there are no generic type parameters, \(g=0\).
3. The names and types \(\mathrm{x}_{1}: \mathrm{T}_{1}^{\prime}, \ldots, \mathrm{x}_{f}: \mathrm{T}_{f}^{\prime}\) of the actual parameters. If there are no actual parameters, \(f=0\). In the case of an instance method, the receiver is the first actual parameter.

The signature of the method resolution procedure is: resolve(invo : Invocation, context: Set[Method]) : MethodID. Given a particular invocation and the set context of all methods which could be called at that point of code, method resolution either returns the unique identifier of the method that should be called, or (conceptually) throws an exception if the call cannot be resolved.

The procedure for computing resolve(invo, context) is:

\footnotetext{
\({ }^{7}\) The variable names are relevant because one formal can be mentioned in a later type, or even a constraint: \(\operatorname{def} f(a:\) Int, \(b: \operatorname{Point}\{\operatorname{rank}==a\})=\ldots\)
}
1. Eliminate from context those methods which are not acceptable; viz., those whose name, type parameters, and formal parameters do not suitably match invo. In more detail:
- The method name \(m\) must simply equal the invocation name \(m^{\prime}\);
- X10 infers type parameters, by an algorithm given in 84.12 .3 .
- The method's type parameters are bound to the invocation's for the remainder of the acceptability test.
- The actual parameter types must be subtypes of the formal parameter types, or be coercible to such subtypes. Parameter \(i\) is a subtype if \(\mathrm{T}_{i}^{\prime}\) <: \(\mathrm{T}_{i}\). It is implicitly coercible to a subtype if either it is a subtype, or if there is an implicit coercion operator defined from \(\mathrm{T}_{i}^{\prime}\) to some type U , and \(\mathrm{U}<\) : \(\mathrm{T}_{i}\). . If coercions are used to resolve the method, they will be called on the arguments before the method is invoked.
2. Eliminate from context those methods which are not available; viz., those which cannot be called due to visibility constraints, such as methods from other classes marked private. The remaining methods are both acceptable and available; they might be the one that is intended.
3. If the method invocation is a super invocation appearing in class Cl , methods of Cl and its subclasses are considered unavailable as well.
4. From the remaining methods, find the unique ms which is more specific than all the others, viz., for which specific (ms,mo) = true for all other methods mo. The specificity test specific is given next.
- If there is a unique such ms, then resolve(invo, context) returns the id of ms.
- If there is not a unique such ms , then resolve reports an error.

The subsidiary procedure specific ( \(\mathrm{m} 1, \mathrm{~m} 2\) ) determines whether method m 1 is equally or more specific than m2. specific is not a total order: is is possible for each one to be considered more specific than the other, or either to be more specific. specific is computed as:
1. Construct an invocation invo1 based on m 1 :
- invo1's method name is m1's method name;
- invo1's generic parameters are those of m1— simply some type variables.
- invo1's parameters are those of m1.
2. If m 2 is acceptable for the invocation invo1, specific ( \(\mathrm{m} 1, \mathrm{~m} 2\) ) returns true;
3. Construct an invocation invo2p, which is invo1 with the generic parameters erased. Let invo2 be invo2p with generic parameters as inferred by X10's type inference algorithm. If type inference fails, specific ( \(\mathrm{m} 1, \mathrm{~m} 2\) ) returns false.
4. If m 2 is acceptable for the invocation invo2, specific ( \(\mathrm{m} 1, \mathrm{~m} 2\) ) returns true;
5. Otherwise, specific ( \(\mathrm{m} 1, \mathrm{~m} 2\) ) returns false.

\subsection*{8.11.3 Field Resolution}

An identifier p can refer to a number of things. The rules are somewhat different inside and outside of a constraint.
Outside of a constraint, the compiler chooses the first one from the following list which applies:
1. A local variable named \(p\).
2. A field of this, viz. this.p.
3. A nullary property method, this.p()
4. A member type named \(p\).
5. A package named p .

Inside of a constraint, the rules are slightly different, because self is available, and packages cannot be used per se.
1. A local variable named p .
2. A property of this or of self, viz. this.p or self.p. If both are available, report an error.
3. A nullary property method, this.p()
4. A member type named p .

\subsection*{8.11.4 Other Disambiguations}

It is possible to have a field of the same name as a method. Indeed, it is a common pattern to have private field and a public method of the same name to access it:
Example:
```

class Xhaver {
private var x: Int = 0;
public def x() = x;
public def bumpX() { x ++; }
}

```

Example: However, this can lead to syntactic ambiguity in the case where the field \(£\) of object a is a function, array, list, or the like, and where a has a method also named \(£\). The term \(\mathrm{a} . \mathrm{f}(\mathrm{b})\) could either mean "call method \(£\) of a upon b", or "apply the function \(\mathrm{a} . \mathrm{f}\) to argument b ".
```

class Ambig {
public val f : (Int)=>Int = (x:Int) => x*x;
public def f(y:int) = y+1;
public def example() {
val v = this.f(10);
// is v 100, or 11?
}
}

```

In the case where a syntactic form E.m \(\left(\mathrm{F}_{1}, \ldots, \mathrm{~F}_{n}\right)\) could be resolved as either a method call, or the application of a field E.m to some arguments, it will be treated as a method call. The application of E.m to some arguments can be specified by adding parentheses: (E.m) \(\left(\mathrm{F}_{1}, \ldots, \mathrm{~F}_{n}\right)\).

\section*{Example:}
```

class Disambig {
public val f : (Int)=>Int = (x:Int) => x*x;
public def f(y:int) = y+1;
public def example() {
assert( this.f(10) == 11 );
assert( (this.f)(10) == 100 );
}
}

```

Similarly, it is possible to have a method with the same name as a struct, say ambig, giving an ambiguity as to whether ambig() is a struct constructor invocation or a method invocation. This ambiguity is resolved by treating it as a method invocation. If the constructor invocation is desired, it can be achieved by including the optional new. That is, new ambig() is struct constructor invocation; ambig() is a method invocation.

\subsection*{8.12 Static Nested Classes}

One class (or struct or interface) may be nested within another. The simplest way to do this is as a static nested class, written by putting one class definition at top level inside another, with the inner one having a static modifier. For most purposes, a static nested class behaves like a top-level class. However, a static nested class has access to private static fields and methods of its containing class.

Nested interfaces and static structs are permitted as well.
```

class Outer {
private static val priv = 1;
private static def special(n:Int) = n*n;
public static class StaticNested {
static def reveal(n:Int) = special(n) + priv;
}
}

```

\subsection*{8.13 Inner Classes}

Non-static nested classes are called inner classes. An inner class instance can be thought of as a very elaborate member of an object - one with a full class structure of its own. The crucial characteristic of an inner class instance is that it has an implicit reference to an instance of its containing class.

Example: This feature is particularly useful when an instance of the inner class makes no sense without reference to an instance of the outer, and is closely tied to it. For example, consider a range class, describing a span of integers \(m\) to \(n\), and an iterator over the range. The iterator might as well have access to the range object, and there is little point to discussing iterators-over-ranges without discussing ranges as well. In the following example, the inner class RangeIter iterates over the enclosing Range.

It has its own private cursor field n , telling where it is in the iteration; different iterations over the same Range can exist, and will each have their own cursor. It is perhaps unwise to use the name n for a field of the inner class, since it is also a field of the outer class, but it is legal. (It can happen by accident as well-e.g., if a programmer were to add a field n to a superclass of the outer class, the inner class would still work.) It does not even interfere with the inner class's ability to refer to the outer class's n field: the cursor initialization refers to the Range's lower bound through a fully qualified name Range.this.n. The initialization of its n field refers to the outer class's \(m\) field, which is not shadowed and can be referred to directly, as m .
```

class Range(m:Int, n:Int) implements Iterable[Int]{
public def iterator () = new RangeIter();
private class RangeIter implements Iterator[Int] {
private var n : Int = m;
public def hasNext() = n <= Range.this.n;
public def next() = n++;
}
public static def main(argv:Array[String](1)) {
val r = new Range(3,5);
for(i in r) Console.OUT.println("i=" + i);
}
}

```

An inner class has full access to the members of its enclosing class, both static and instance. In particular, it can access private information, just as methods of the enclosing class can.
An inner class can have its own members. Inside instance methods of an inner class, this refers to the instance of the inner class. The instance of the outer class can be accessed as Outer.this (where Outer is the name of the outer class). If, for some dire reason, it is necessary to have an inner class within an inner class, the innermost class can refer to the this of either outer class by using its name.
An inner class can inherit from any class in scope, with no special restrictions. super inside an inner class refers to the inner class's superclass. If it is necessary to refer to the outer classes's superclass, use a qualified name of the form Outer. super.
The members of inner classes must be instance members. They cannot be static members. Classes, interfaces, static methods, static fields, and typedefs are not allowed as members of inner classes. The same restriction applies to local classes (\$8.14).
Consider an inner class IC1 of some outer class 0C1, being extended by another class IC2. However, since an IC1 only exists as a dependent of an OC1, each IC2 must be associated with an OC1 - or a subtype thereof - as well. So, IC2 must be an inner class of either \(0 C 1\) or some subclass \(0 C 2<\) : \(0 C 1\).
Example: For example, one often extends an inner class when one extends its outer class:
```

class OC1 {
class IC1 {}
}
class OC2 extends OC1 {
class IC2 extends IC1 {}
}

```

The hiding of method names has one fine point. If an inner class defines a method named doit, then all methods named doit from the outer class are hidden even if they have different argument types than the one defined in the inner class. They are still accessible via Outer.this.doit(), but not simply via doit(). The following code is correct, but would not be correct if the ERROR line were uncommented.
```

class Outer {

```
```

    def doit() {}
    def doit(String) {}
    class Inner {
        def doit(Boolean, Outer) {}
        def example() {
            doit(true, Outer.this);
            Outer.this.doit();
            //ERROR: doit("fails");
        }
    }
    }

```

\subsection*{8.13.1 Constructors and Inner Classes}

If IC is an inner class of \(O C\), then instance code in the body of \(O C\) can create instances of IC simply by calling a constructor new IC(...):
```

class OC {
class IC {}
def method(){
val ic = new IC();
}
}

```

Instances of IC can be constructed from elsewhere as well. Since every instance of IC is associated with an instance of OC, an OC must be supplied to the IC constructor. The syntax for doing so is: oc.new IC(). For example:
```

class OC {
class IC {}
static val oc1 = new OC();
static val oc2 = new OC();
static val ic1 = oc1.new IC();
static val ic2 = oc2.new IC();
}
class Elsewhere{
def method(oc : OC) {
val ic = oc.new IC();

```
```

    }
    }

```

\subsection*{8.14 Local Classes}

Classes can be defined and instantiated in the middle of methods and other code blocks. A local class in a static method is a static class; a local class in an instance method is an inner class. Local classes are local to the block in which they are defined. They have access to almost everything defined at that point in the method; the one exception is that they cannot use var variables. Local classes cannot be public, protected, or private, because they are only visible from within the block of declaration. They cannot be static.
Example: The following example illustrates the use of a local class Local, defined inside the body of method m() .
```

class Outer {
val a = 1;
def m() {
val a = -2;
val b = 2;
class Local {
val a = 3;
def m() = 100*Outer.this.a + 10*b + a;
}
val l : Local = new Local();
assert l.m() == 123;
}//end of m()
}

```

Note that the middle a, whose value is -2 , is not accessible inside of Local; it is shadowed by Local's a field. Outer's a is also shadowed, but the notation Outer.this gives a reference to the enclosing Outer object. There is no corresponding notation to access shadowed local variables from the enclosing block; if you need to get them, rename the fields of Local.

The members of inner classes must be instance members. They cannot be static members. Classes, interfaces, static methods, static fields, and typedefs are not
allowed as members of local classes. The same restriction applies to inner classes ( 88.13 ).

\subsection*{8.15 Anonymous Classes}

It is possible to define a new local class and instantiate it as part of an expression. The new class can extend an existing class or interface. Its body can include all of the usual members of a local class. It can refer to any identifiers available at that point in the expression - except for var variables. An anonymous class in a static context is a static inner class.

Anonymous classes are useful when you want to package several pieces of behavior together (a single piece of behavior can often be expressed as a function, which is syntactically lighter-weight), or if you want to extend and vary an extant class without going through the trouble of actually defining a whole new class.
The syntax for an anonymous class is a constructor call followed immediately by a braced class body: new C(1)\{def foo()=2;\}.

Example: In the following minimalist example, the abstract class Choice encapsulates a decision. A Choice has a yes() and a no() method. The choose(b) method will invoke one of the two. Choices also have names.
The main() method creates a specific Choice. c is not a immediate instance of Choice - as an abstract class, Choice has no immediate instances. c is an instance of an anonymous class which inherits from Choice, but supplies yes() and no() methods. These methods modify the contents of the Cell[Int] n. (Note that, as n is a local variable, it would take a few lines more coding to extract c's class, name it, and make it an inner class.) The call to c . choose(true) will call c.yes(), incrementing n() , in a rather roundabout manner.
```

abstract class Choice(name: String) {
def this(name:String) {property(name);}
def choose(b:Boolean) {
if (b) this.yes(); else this.no(); }
abstract def yes():void;
abstract def no():void;
}
class Example {

```
```

    static def main(Array[String]) {
        val n = new Cell[Int](0);
        val c = new Choice("Inc Or Dec") {
            def yes() { n() += 1; }
            def no() { n() -= 1; }
            };
        c.choose(true);
        Console.OUT.println("n=" + n());
    }
    }

```

Anonymous classes have many of the features of classes in general. A few features are unavailable because they don't make sense.
- Anonymous classes don't have constructors. Since they don't have names, there's no way a constructor could get called in the ordinary way. Instead, the new C(...) expression must match a constructor of the parent class C , which will be called to initialize the newly-created object of the anonymous class.
- The public, private, and protected modifiers don't make sense for anonymous classes: Anonymous classes, being anonymous, cannot be referenced at all, so references to them can't be public, private, or protected.
- Anonymous classes cannot be abstract. Since they only exist in combination with a constructor call, they must be constructable. The parent class of the anonymous class may be abstract, or may be an interface; in this case, the anonymous class must provide all the methods that the parent demands.
- Anonymous classes cannot have explicit extends or implements clauses; there's no place in the syntax for them. They have a single parent and that is that.

\section*{9 Structs}

X10 objects are a powerful general-purpose programming tool. However, the power must be paid for in space and time. In space, a typical object implementation requires some extra memory for run-time class information, as well as a pointer for each reference to the object. In time, a typical object requires an extra indirection to read or write data, and some run-time computation to figure out which method body to call.

For high-performance computing, this overhead may not be acceptable for all objects. X10 provides structs, which are stripped-down objects. They are less powerful than objects; in particular they lack inheritance and mutable fields. Without inheritance, method calls do not need to do any lookup; they can be implemented directly. Accordingly, structs can be implemented and used more cheaply than objects, potentially avoiding the space and time overhead. (Currently, the C++ back end avoids the overhead, but the Java back end implements structs as Java objects and does not avoid it.)

Structs and classes are interoperable. Both can implement interfaces; in particular, like all X10 values they implement Any. Subroutines whose arguments are defined by interfaces can take both structs and classes. (Some caution is necessary here: referring to a struct through an interface requires overhead similar to that required for an object.)

In many cases structs can be converted to classes or classes to structs, within the constraints of structs. If you start off defining a struct and decide you need a class instead, the code change required is simply changing the keyword struct to class. If you have a class that does not use inheritance or mutable fields, it can be converted to a struct by changing its keyword. Client code using the struct that was a class will need certain changes: e.g., the new keyword must be added in constructor calls, and structs (unlike classes) cannot be null.

\subsection*{9.1 Struct declaration}
\begin{tabular}{llll} 
StructDecln & \(::=\) & Mods? struct Id TypeParams \(?^{?}\) Properties? Guard? \\
& Interfaces? ClassBody
\end{tabular}

All fields of a struct must be val.
A struct \(S\) cannot contain a field of type \(S\), or a field of struct type \(T\) which, recursively, contains a field of type \(S\). This restriction is necessary to permit \(S\) to be implemented as a contiguous block of memory of size equal to the sum of the sizes of its fields.

Values of a struct C type can be created by invoking a constructor defined in C. Unlike for classes, the new keyword is optional for struct constructors.
Example: Leaving out new can improve readability in some cases:
```

struct Polar(r:Double, theta:Double){
def this(r:Double, theta:Double) {property(r,theta);}
static val Origin = Polar(0,0);
static val x0y1 = Polar(1, 3.14159/2);
static val x1y0 = new Polar(1, 0);
}

```

When a struct and a method have the same name (often in violation of the X10 capitalization convention), new may be used to resolve to the struct's constructor.
```

struct Ambig(x:Int) {
static def Ambig(x:Int) = "ambiguity please";
static def example() {
val useMethod = Ambig(1);
val useConstructor = new Ambig(2);
}
}

```

Structs support the same notions of generics, properties, and constrained types that classes do.

\section*{Example:}
```

struct Exam[T](nQuestions:Int){T <: Question} {
public static interface Question {}
// ...
}

```

\subsection*{9.2 Boxing of structs}

If a struct S implements an interface I (e.g., Any), a value v of type S can be assigned to a variable of type \(I\). The implementation creates an object o that is an instance of an anonymous class implementing I and containing v . The result of invoking a method of \(I\) on \(o\) is the same as invoking it on \(v\). This operation is termed auto-boxing. It allows full interoperability of structs and objects-at the cost of losing the extra efficiency of the structs when they are boxed.
In a generic class or struct obtained by instantiating a type parameter T with a struct S , variables declared at type T in the body of the class are not boxed. They are implemented as if they were declared at type \(S\).
Example: The array aa in the following example is an Array[Any]. It initially holds two objects. Then, its elements are replaced by two structs, both of which are auto-boxed. Note that no fussing is required to put an integer into an Array [Any]. However, an array of structs, such as ah, holds unboxed structs and does not incur boxing overhead.
```

struct Horse(x:Int){
static def example(){
val aa : Array[Any](1) = ["an Object" as Any, "another one"];
aa(0) = Horse(8);
aa(1) = 13;
val ah : Array[Horse](1) = [Horse(7), Horse(13)];
}
}

```

\subsection*{9.3 Optional Implementation of Any methods}

Two structs are equal (==) if and only if their corresponding fields are equal (==).

All structs implement x10. lang. Any. Structs are required to implement the following methods from Any. Programmers need not provide them; X10 will produce them automatically if the program does not include them.
```

public def equals(Any):Boolean;
public def hashCode():Int;
public def typeName():String;
public def toString():String;

```

A programmer who provides an explicit implementation of equals(Any) for a struct \(S\) should also consider supplying a definition for equals(S):Boolean. This will often yield better performance since the cost of an upcast to Any and then a downcast to \(S\) can be avoided.

\subsection*{9.4 Primitive Types}

Certain types that might be built in to other languages are in fact implemented as structs in package \(\times 10\). lang in X10. Their methods and operations are often provided with @Native (§18) rather than X10 code, however. These types are:

Boolean, Char, Byte, Short, Int, Long
Float, Double, UByte, UShort, UInt, ULong

\subsection*{9.4.1 Signed and Unsigned Integers}

X10 has an unsigned integer type corresponding to each integer type: UInt is an unsigned Int, and so on. These types can be used for binary programming, or when an extra bit of precision for counters or other non-negative numbers is needed in integer arithmetic. However, X10 does not otherwise encourage the use of unsigned arithmetic.

\subsection*{9.5 Example structs}
x10.lang. Complex provides a detailed example of a practical struct, suitable for use in a library. For a shorter example, we define the Pair struct. A Pair
packages two values of possibly unrelated type together in a single value, e.g., to return two values from a function.
divmod computes the quotient and remainder of \(\mathrm{a} \div \mathrm{b}\) (naively). It returns both, packaged as a Pair [UInt, UInt]. Note that the constructor uses type inference, and that the quotient and remainder are accessed through the first and second fields.
```

struct Pair[T,U] {
public val first:T;
public val second:U;
public def this(first:T, second:U):Pair[T,U] {
this.first = first;
this.second = second;
}
public def toString()
= "(" + first + ", " + second + ")";
}
class Example {
static def divmod(var a:UInt, b:UInt): Pair[UInt, UInt] {
assert b > Ou;
var q : UInt = Qu;
while (a > b) {q++; a -= b;}
return Pair(q, a);
}
static def example() {
val qr = divmod(22, 7);
assert qr.first == 3u \&\& qr.second == 1u;
}
}

```

\subsection*{9.6 Nested Structs}

Static nested structs may be defined, essentially as static nested classes except for making them structs (\$8.12). Inner structs may be defined, essentially as inner classes except making them structs ( \(\$ 8.13\) ). Limitation: Nested structs must be currently be declared static.

\subsection*{9.7 Default Values of Structs}

If all fields of a struct have default values, then the struct has a default value, viz., the struct whose fields are all set to their default values. If some field does not have a default value, neither does the struct.

\section*{Example:}

In the following code, the Example struct has a default value whose i field is Q. If an Example is ever constructed by the constructor, its i field will be 1. This program does a slightly subtle dance to get ahold of a default Example, by having an instance var (which, unlike most kinds of variables, does not need to get initialized before use (though that exemption only applies if its type has a default value)). As the assert confirms, the default Example does indeed have an \(\mathbf{i}\) field of 0 .
```

class StructDefault {
static struct Example {
val i : Int;
def this() { i = 1; }
}
var ex : Example;
static def example() {
val ex = (new StructDefault()).ex;
assert ex.i == 0;
}

```

\subsection*{9.8 Converting Between Classes And Structs}

Code written using structs can be modified to use classes, or vice versa. Caution must be used in certain places.
Class and struct definitions are syntactically nearly identical: change the class keyword to struct or vice versa. Of course, certain important class features can't be used with structs, such as inheritance and var fields.
Converting code that uses the class or struct requires a certain amount of caution. Suppose, in particular, that we want to convert the class Class2Struct to a struct, and Struct2Class to a class.
```

class Class2Struct {
val a : Int;
def this(a:Int) { this.a = a; }
def m() = a;
}
struct Struct2Class {
val a : Int;
def this(a:Int) { this.a = a; }
def m() = a;
}

```
1. Class constructors require the new keyword; struct constructors allow it but do not require it. Struct2Class(3) to will need to be converted to new Struct2Class(3).
2. Objects and structs have different notions of \(==\). For objects, == means "same object"; for structs, it means "same contents". Before conversion, both asserts in the following program succeed. After converting and fixing constructors, both of them fail.
```

val a = new Class2Struct(2);
val b = new Class2Struct(2);
assert a != b;
val c = Struct2Class(3);
val d = Struct2Class(3);
assert c==d;

```
3. Objects can be set to null. Structs cannot.
4. The rules for default values are quite different. The default value of an object type (if it exists) is null, which behaves quite differently from an ordinary object of that type; e.g., you cannot call methods on null, whereas you can on an ordinary object. The default value for a struct type (if it exists) is a struct like any other of its type, and you can call methods on it as for any other.

\section*{10 Functions}

\subsection*{10.1 Overview}

Functions, the last of the three kinds of values in X10, encapsulate pieces of code which can be applied to a vector of arguments to produce a value. Functions, when applied, can do nearly anything that any other code could do: fail to terminate, throw an exception, modify variables, spawn activities, execute in several places, and so on. X10 functions are not mathematical functions: the \(f(1)\) may return true on one call and false on an immediately following call.
A function literal ( \(\mathrm{x} 1: \mathrm{T} 1, \ldots, \mathrm{xn}: \mathrm{Tn}\) ) \(\{\mathrm{c}\}: \mathrm{T}=>\mathrm{e}\) creates a function of type ( \(\mathrm{x} 1: \mathrm{T} 1, \ldots, \mathrm{xn}: \mathrm{Tn}\) ) \(\{\mathrm{c}\}=>\mathrm{T}(\$ 4.6\) ). For example, \((\mathrm{x}:\) Int) : Int \(=>\mathrm{x} * \mathrm{x}\) is a function literal describing the squaring function on integers. null is also a function value.
Limitation: X10 functions cannot have type arguments or constraints.
Function application is written \(f(a, b, c)\), following common mathematical usage.
The function body may be a block. To compute integer squares by repeated addition (inefficiently), one may write:
```

val sq: (Int) => Int
= (n:Int) => {
var s : Int = 0;
val abs_n = n < 0 ? -n : n;
for (i in 1..abs_n) s += abs_n;
s
};

```

A function literal evaluates to a function entity \(f\). When \(f\) is applied to a suitable list of actual parameters a1 through an, it evaluates e with the formal parameters
bound to the actual parameters. So, the following are equivalent, where \(e\) is an expression involving \(\times 1\) and \(\times 2^{11}\)
```

    {
    ```
    val \(f=(x 1: T 1, x 2: T 2)\{\) true \(\}: T=>e ;\)
    val a1 : T1 = arg1();
    val a2 : T2 = arg2();
    result \(=f(a 1, a 2)\);
\}
and
```

{
val a1 : T1 = arg1();
val a2 : T2 = arg2();
{
val x1 : T1 = a1;
val x2 : T2 = a2;
result = e;
}
}

```

This equivalence does not hold if the body is a statement rather than an expression. A few language features are forbidden (break or continue of a loop that surrounds the function literal) or mean something different (return inside a function returns from the function, not the surrounding block).

Function types may be used in implements clauses of class definitions. Suitable operator definitions must be supplied, with public operator this(x1:T1, \(\ldots, \mathrm{xn}: \mathrm{Tn}\) ) declarations. Instances of such classes may be used as functions of the given type. Indeed, an object may behave like any (fixed) number of functions, since the class it is an instance of may implement any (fixed) number of function types. e.g. Instances of the Funny class behave like two functions: a constant function on Booleans, and a linear function on pairs of Ints.
```

class Funny implements (Boolean) => Int,
(Int, Int) => Int
{

```

\footnotetext{
\({ }^{1}\) Strictly, there are a few other requirements; e.g., result must be a var of type T defined outside the outer block, the variables a1 and a2 had better not appear in e, and everything in sight had better typecheck properly.
}
```

    public operator this(Boolean) = 1;
    public operator this(x:Int, y:Int) = 10*x+y;
    static def example() {
        val f <: Funny = new Funny();
        assert f(true) == 1; // (Boolean)=>Int behavior
        assert f(1,2) == 12; // (Int,Int)=>Int behavior
    }
    }

```

\subsection*{10.2 Function Application}

The basic operation on functions is function application. (Since, e.g., array lookup has the same type as function application, these rules are used for array lookup as well, and so on.)

A function with type \(\left(\mathrm{x}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{x}_{n}: \mathrm{T}_{n}\right)\{\mathrm{c}\} \Rightarrow \mathrm{T}\) can be applied to a sequence of expressions \(\mathrm{e}_{1}, \ldots, \mathrm{e}_{n}\) if:
- \(\mathrm{e}_{1}\) is of type \(\mathrm{T}_{1}\left[\mathrm{e}_{1} / \mathrm{x}_{1}\right]\),
- ...,
- \(\mathrm{e}_{n}\) is of type \(\mathrm{T}_{n}\left[\mathrm{e}_{1} / \mathrm{x}_{1}, \ldots, \mathrm{e}_{n} / \mathrm{x}_{n}\right]\),
- X10 can prove that \(\mathrm{c}\left[\mathrm{e}_{1} / \mathrm{x}_{1}, \ldots, \mathrm{e}_{n} / \mathrm{x}_{n}\right]\) holds.

In this case, if the application terminates normally, it returns a value of type \(\mathrm{T}\left[\mathrm{e}_{1} / \mathrm{x}_{1}, \ldots, \mathrm{e}_{n} / \mathrm{x}_{n}\right]\).
Example: Consider
\[
f:(a: \operatorname{Int}\{a!=0\}, b: \operatorname{Int}\{b!=a\})\{b!=0\} \Rightarrow \operatorname{Int}\{\operatorname{self}!=a\}
\]

Then the call \(£(3,4)\) is allowed, because:
- 3 is of type \(\operatorname{Int}\{\mathrm{a}!=0\}\) with a replaced by 3 , viz. Int \(\{3!=0\}\);
- 4 is of type \(\operatorname{Int}\{\mathrm{b}!=\mathrm{a}\}\) with a replaced by 3 and b replaced by 4 , viz. \(\operatorname{Int}\{3!=4\}\).
- The guard \(\mathrm{b}!=0\), with a replaced by 3 and b replaced by 4 , is \(4!=\mathbb{0}\), which is true.

So, \(£(3,4)\) will return a value of type \(\operatorname{Int}\{\operatorname{sel} f!=a\}\) with a replaced by 3 and b replaced by 4 , which is to say, Int \(\{\) self \(!=3\}\).

\subsection*{10.3 Function Literals}

X10 provides first-class, typed functions, often called closures.
\begin{tabular}{lcl} 
ClosureExp & \(::=\) Formals Guard? \(^{2}\) HasResultType? \(=>\) ClosureBody \\
Formals & \(::=\) ( FormalList? \\
Guard & \(::=\) DepParams \\
HasResultType & \(::=\) ResultType \\
& \(\mid\) & \(<\) : Type \\
ClosureBody & \(::=\) Exp \\
& \(\mid\) & Annotations? \{ BlockStmts? LastExp \(\}\) \\
& & Annotations? Block
\end{tabular}

Functions have zero or more formal parameters and an optional return type. The body has the same syntax as a method body; it may be either an expression, a block of statements, or a block terminated by an expression to return. In particular, a value may be returned from the body of the function using a return statement (\$12.13).
The type of a function is a function type as described in \(\S 4.6\). In some cases the return type T is also optional and defaults to the type of the body. If a formal xi does not occur in any \(\mathrm{Tj}, \mathrm{c}, \mathrm{T}\) or e, the declaration xi:Ti may be replaced by just Ti. E.g., (Int) \(=>7\) is the integer function returning 7 for all inputs.
As with methods, a function may declare a guard to constrain the actual parameters with which it may be invoked. The guard may refer to the type parameters, formal parameters, and any vals in scope at the function expression.
Example:
\[
\begin{aligned}
& \text { val } \begin{aligned}
\mathrm{n} & =3 ; \\
\text { val } \mathrm{f} & :(\mathrm{x}: \operatorname{Int})\{\mathrm{x}!=\mathrm{n}\} \Rightarrow \text { Int } \\
& =(\mathrm{x}: \operatorname{Int})\{\mathrm{x}!=\mathrm{n}\} \Rightarrow(12 /(\mathrm{n}-\mathrm{x})) ;
\end{aligned} \\
& \text { Console.OUT.println("f(5)="+f(5));}
\end{aligned}
\]

The body of the function is evaluated when the function is invoked by a call expression ( \(\$ 11.6\) ), not at the function's place in the program text.
As with methods, a function with return type void cannot have a terminating expression. If the return type is omitted, it is inferred, as described in \(\$ 4.12\), It is a static error if the return type cannot be inferred. E.g., (Int)=>null is not well-specified; X10 does not know which type of null is intended. But (Int):Array[Double] (1) \(=>\) null is legal.
Example: The following method takes a function parameter and uses it to test each element of the list, returning the first matching element. It returns no if no element matches.
```

def find[T](f: (T) => Boolean, xs: List[T], no:T): T = \{
for ( $\mathrm{x}: \mathrm{T}$ in xs )
if ( $f(x)$ ) return $x$;
no
\}

```

The method may be invoked thus, to find a positive element of xs , or return 0 if there is no positive element.
```

xs: List[Int] = new ArrayList[Int]();
x: Int = find((x: Int) => x>0, xs, 0);

```

\subsection*{10.3.1 Outer variable access}

In a function \(\left.\left(\mathrm{x}_{1}: \mathrm{T}_{1}, \ldots, \mathrm{x}_{n}: \mathrm{T}_{n}\right)\{\mathrm{c}\} \Rightarrow>\mathrm{s}\right\}\) the types \(\mathrm{T}_{i}\), the guard c and the body \(s\) may access many, though not all, sorts of variables from outer scopes. Specifically, they can access:
- All fields of the enclosing object(s) and class(es);
- All type parameters;
- All val variables;
var variables cannot be accessed.
The function body may refer to instances of enclosing classes using the syntax C. this, where C is the name of the enclosing class. this refers to the instance of the immediately enclosing class, as usual.
e.g. The following is legal. Note that a is not a local var variable. It is a field of this. A reference to a is simply short for this.a, which is a use of a val variable (this).
```

class Lambda {
var a : Int = 0;
val b = 0;
def m(var c : Int, val d : Int) {
var e : Int = 0;
val f : Int = 0;
val closure = (var i: Int, val j: Int) => {
return a + b + d + f + i
+ j + this.a + Lambda.this.a;
// c and e are not usable here
};
return closure;
}
}

```

\subsection*{10.4 Functions as objects of type Any}

Two functions \(f\) and \(g\) are equal if both were obtained by the same evaluation of a function literal \(\left.\right|^{2}\) Further, it is guaranteed that if two functions are equal then they refer to the same locations in the environment and represent the same code, so their executions in an identical situation are indistinguishable. (Specifically, if \(f==g\), then \(f(1)\) can be substituted for \(g(1)\) and the result will be identical. However, there is no guarantee that \(f(1)==g(1)\) will evaluate to true. Indeed, there is no guarantee that \(f(1)==f(1)\) will evaluate to true either, as \(f\) might be a function which returns \(n\) on its \(n^{\text {th }}\) invocation. However, \(f(1)==f(1)\) and \(f(1)==g(1)\) are interchangeable.)
Every function type implements all the methods of Any. f. equals ( g ) is equivalent to \(f==g\). The behavior of hashCode, toString, and typeName is up to the implementation, but respect equals and the basic contracts of Any.

\footnotetext{
\({ }^{2}\) A literal may occur in program text within a loop, and hence may be evaluated multiple times.
}

\section*{11 Expressions}

X10 has a rich expression language. Evaluating an expression produces a value, or, in a few cases, no value. Expression evaluation may have side effects, such as change of the value of a var variable or a data structure, allocation of new values, or throwing an exception.

\subsection*{11.1 Literals}

Literals denote fixed values of built-in types. The syntax for literals is given in \(\$ 3.5\)
The type that X10 gives a literal often includes its value. E.g., 1 is of type Int \(\{s e l f==1\}\), and true is of type Boolean\{self==true\}.

\section*{11.2 this}
\[
\begin{aligned}
\text { Primary } & ::=\text { this } \\
& \mid \text { ClassName. this }
\end{aligned}
\]

The expression this is a local val containing a reference to an instance of the lexically enclosing class. It may be used only within the body of an instance method, a constructor, or in the initializer of a instance field - that is, the places where there is an instance of the class under consideration.
Within an inner class, this may be qualified with the name of a lexically enclosing class. In this case, it represents an instance of that enclosing class.
Example: Outer is a class containing Inner. Each instance of Inner has a reference Outer. this to the Outer involved in its creation. Inner has access
to the fields of Outer.this. Note that Inner has its own three field, which is different from and not even the same type as Outer. this. three.
```

class Outer {
val three = 3;
class Inner {
val three = "THREE";
def example() {
assert Outer.this.three == 3;
assert three.equals("THREE");
assert this.three.equals("THREE");
}
}
}

```

The type of a this expression is the innermost enclosing class, or the qualifying class, constrained by the class invariant and the method guard, if any.

The this expression may also be used within constraints in a class or interface header (the class invariant and extends and implements clauses). Here, the type of this is restricted so that only properties declared in the class header itself, and specifically not any members declared in the class body or in supertypes, are accessible through this.

\subsection*{11.3 Local variables}
\[
I d::=\text { IDENTIFIER }
\]

A local variable expression consists simply of the name of the local variable, field of the current object, formal parameter in scope, etc. It evaluates to the value of the local variable.

Example: n in the second line below is a local variable expression. The n in the first line is not; it is part of a local variable declaration.
\[
\begin{aligned}
& \text { val } \mathrm{n}=22 ; \\
& \text { val } \mathrm{m}=\mathrm{n}+56 ;
\end{aligned}
\]

\subsection*{11.4 Field access}
\[
\begin{array}{rll}
\text { FieldAccess } & ::= & \text { Primary . Id } \\
& \mid & \text { super . Id } \\
& \mid & \text { ClassName . super . Id }
\end{array}
\]

A field of an object instance may be accessed with a field access expression.
The type of the access is the declared type of the field with the actual target substituted for this in the type.

Example: The declaration of below has a constraint involving this. The use of an instance of it, \(\mathrm{f} . \mathrm{b}\), has the same constraint involving f instead of this, as required.
```

class Fielded {
public val a : Int = 1;
public val b : Int{this.a == b} = this.a;
static def example() {
val f : Fielded = new Fielded();
assert f.a == 1 \&\& f.b == 1;
val fb : Int{fb == f.a} = f.b;
assert fb == 1;
}
}

```

The field accessed is selected from the fields and value properties of the static type of the target and its superclasses.
If the field target is given by the keyword super, the target's type is the superclass of the enclosing class. This form is used to access fields of the parent class hidden by same-named fields of the current class.
If the field target is Cls.super, then the target's type is Cl s, which must be an enclosing class. This (admittedly obscure) form is used to access fields of an ancestor class which are shadowed by same-named fields of some more recent ancestor.

Example: This illustrates all four cases of field access.
```

class Uncle {
public static val f = 1;

```
```

}
class Parent {
public val f = 2;
}
class Ego extends Parent {
public val f = 3;
class Child extends Ego {
public val f = 4;
def example() {
assert Uncle.f == 1;
assert Ego.super.f == 2;
assert super.f == 3;
assert this.f == 4;
assert f == 4;
}
}
}

```

If the field target is null, a NullPointerException is thrown. If the field target is a class name, a static field is selected. It is illegal to access a field that is not visible from the current context. It is illegal to access a non-static field through a static field access expression. However, it is legal to access a static field through a non-static reference.

\subsection*{11.5 Function Literals}

Function literals are described in \(\S 10\).

\subsection*{11.6 Calls}
\begin{tabular}{|c|c|c|c|}
\hline MethodInvo & : \(=\) & ```
MethodName TypeArgs?(ArgumentList?)
Primary . Id TypeArgs? (ArgumentList?)
super . Id TypeArgs?(ArgumentList?)
ClassName . super . Id TypeArgs? ( ArgumentList?)
Primary TypeArgs? (ArgumentList?)
``` & 20.113 \\
\hline ArgumentList & : \(=\) & Exp & 20.8 \\
\hline & & ArgumentList, Exp & \\
\hline \multirow[t]{2}{*}{MethodName} & \multirow[t]{2}{*}{::=} & \multirow[t]{2}{*}{\begin{tabular}{l}
Id \\
FullyQualifiedName . Id
\end{tabular}} & (20.114) \\
\hline & & & \\
\hline
\end{tabular}

A MethodInvocation may be to either a static method, an instance method, or a closure.

The syntax for method invocations is ambiguous. ob.m() could either be the invocation of a method named \(m\) on object ob, or the application of a function held in a field ob.m. If both are defined on the same class, X10 resolves ob.m() to the invocation of the method. If the application of a function in a field is desired, use an alternate syntax which makes the intent clear to X10, such as (ob.m) ().

\section*{Example:}
```

class Callsome {
static val closure : () => Int = () => 1;
static def method() = 2;
static def example() {
assert Callsome.closure() == 1;
assert Callsome.method() == 2;
}
}

```

However, adding a static method [mis]named closure makes Callsome. closure() refer to the method, rather than the closure
```

static def closure () = 3;
static def example() {
assert Callsome.closure() == 3;
assert (Callsome.closure)() == 1;
}

```

The application form \(e(f, g)\), when e evaluates to an object or struct, invokes the application operator, defined in the form
```

public operator this(f:F, g:G) = "value";

```

Method selection rules are given in 8.11 .
Guard satisfaction depends on the STATIC_CHECKS compiler flag. With the flag on, it is a static error if a method's Guard is not statically satisfied by the caller. With STATIC_CHECKS off, the guard will be checked at runtime if necessary.
Example: In this example, a DivideBy object provides the service of dividing numbers by denom - so long as denom is not zero. X10's strictness of checking this is under control of the STATIC_CHECKS compiler option (§C.0.4).
With STATIC_CHECKS turned on, the example method will not compile. The call this. \(\operatorname{div}(100)\) is not allowed; there is no guarantee that denom \(!=0\). Casting this to a type whose constraint implies denom !=0 permits the method call.
With STATIC_CHECKS turned off, the call will compile. X10 will insert a dynamic check that the denominator is non-zero, and will fail at runtime if it is zero.
```

class DivideBy(denom:Int) {
def div(numer:Int){denom != O} = numer / denom;
def example() {
val thisCast = (this as DivideBy{self.denom != 0});
thisCast.div(100);
//ERROR (with STATIC_CHECKS): this.div(100);
}
}

```

\subsection*{11.6.1 super calls}

The expression super. \(f(e 1 \ldots\) en) may appear in an instance method definition. This causes the method invocation to be a super invocation, as described in \(\$ 8.11\). Informally, suppose the invocation appears in class Cl , which extends class Sup. An invocation this. \(f()\) will call a nullary method named \(f\) that appears in class Cl itself, if there is one. An invocation super. \(f()\) will call the nullary \(f\) method in Sup or an ancestor thereof, but not one in Cl . Note that super. f() may be used to invoke an \(f\) method in Sup which has been overridden by one appearing in Cl .

Note that there's only one choice for which f is invoked by super. f()\(-v i z\). the lowest one in the class hierarchy above Cl . So, super. \(f()\) performs static dispatch, like a static method call. This is generally more efficient than a dynamic dispatch, like an instance method call.

\subsection*{11.7 Assignment}


The assignment expression \(\mathrm{x}=\mathrm{e}\) assigns a value given by expression e to a variable x . Most often, x is mutable, a var variable. The same syntax is used for delayed initialization of a val, but vals can only be initialized once.
```

var x : Int;
val y : Int;
x = 1;
y = 2; // Correct; initializes y
x = 3;
// ERROR: y = 4;

```

There are three syntactic forms of assignment:
1. \(x=e\); assigning to a local variable, formal parameter, field of this, etc.
2. \(x . f=e ;\), assigning to a field of an object.
3. \(\mathrm{a}\left(\mathbf{i}_{1}, \ldots, \mathrm{i}_{n}\right)=\mathrm{v}\);, where \(n \geq 0\), assigning to an element of an array or some other such structure. This is an operator call (§8.7). For well-behaved classes it works like array assignment, mutatis mutandis, but there is no actual guarantee, and the compiler makes no assumptions about how this works for arbitrary a. Naturally, it is a static error if no suitable assignment operator for a exists..

For a binary operator \(\diamond\), the \(\diamond\)-assignment expression \(\mathrm{x} \diamond=\mathrm{e}\) combines the current value of \(x\) with the value of e by \(\diamond\), and stores the result back into \(x\). i \(+=2\), for example, adds 2 to i. For variables and fields,
\[
x \diamond=e
\]
behaves just like
\[
x=x \diamond e .
\]

The subscripting forms of a (i) \(\diamond=\mathrm{b}\) are slightly subtle. Subexpressions of a and \(i\) are only evaluated once. However, \(a(i)\) and \(a(i)=c\) are each executed oncein particular, there is one call to the application operator, and one to the assignment operator. If subscripting is implemented strangely for the class of a, the behavior is not necessarily updating a single storage location. Specifically, A() (I)) \(+=\mathrm{B}()\) is tantamount to the following code, except for the unspecified order of evaluation of the expressions:
```

{
// The order of these evaluations is not specified
val aa = A(); // Evaluate A() once
val ii = I(); // Evaluate I() once
val bb = B(); // Evaluate B() once
// But they happen before this:
val tmp = aa(ii) + bb; // read aa(ii)
aa(ii) = tmp; // write sum back to aa(ii)
}

```

\subsection*{11.8 Increment and decrement}

The operators ++ and -- increment and decrement a variable, respectively. \(\mathrm{x}++\) and ++x both increment x , just as the statement \(\mathrm{x}+=(1 \mathrm{as} \mathrm{T}\) ) would (where \(x: T\) ), and similarly for --
The difference between the two is the return value. ++x and --x return the new value of \(x\), after incrementing or decrementing. \(x++\) and \(x--\) return the old value of \(x\), before incrementing or decrementing.

These operators work for any x for which 1 as T is defined, where T is the type of x .

\subsection*{11.9 Numeric Operations}

Numeric types (Byte, Short, Int, Long, Float, Double, Complex, and unsigned variants of fixed-point types) are normal X10 structs, though most of their methods are implemented via native code. They obey the same general rules as other X10 structs. For example, numeric operations, coercions, and conversions are defined by operator definitions, the same way you could for any struct.
Promoting a numeric value to a longer numeric type preserves the sign of the value. For example, ( 255 as UByte) as UInt is 255.
Most of these operations can be defined on user-defined types as well. While it is good practice to keep such operations consistent with the numeric operations whenever possible, the compiler neither enforces nor assumes any particular semantics of user-defined operations.

\subsection*{11.9.1 Conversions and coercions}

Specifically, each numeric type can be converted or coerced into each other numeric type, perhaps with loss of accuracy.

\section*{Example:}
```

val n : Byte = 123 as Byte; // explicit
val f : (Int)=>Boolean = (Int) => true;
val ok = f(n); // implicit

```

\subsection*{11.9.2 Unary plus and unary minus}

The unary + operation on numbers is an identity function. The unary - operation on signed numbers is a negation function. On unsigned numbers, these are two'scomplement arithmetic; the unsigned number types are closed under unary -. For example, - (0x0F as UByte) is (0xF1 as UByte).

\subsection*{11.10 Bitwise complement}

The unary ~ operator, only defined on integral types, complements each bit in its operand.

\subsection*{11.11 Binary arithmetic operations}

The binary arithmetic operators perform the familiar binary arithmetic operations: + adds, - subtracts, * multiplies, / divides, and \% computes remainder.
On integers, the operands are coerced to the longer of their two types, and then operated upon. Floating point operations are determined by the IEEE 754 standard. The integer / and \% throw an exception if the right operand is zero.

\subsection*{11.12 Binary shift operations}

When operands of the binary shift operations are of integral type, the expression performs bitwise shifts. The type of the result is the type of the left operand. The right operand, describing a number of bits, must be unsigned: \(x \ll 1 U\).
If the promoted type of the left operand is Int, the right operand is masked with \(0 x 1 f\) using the bitwise AND (\&) operator, giving a number at most the number of bits in an Int. If the promoted type of the left operand is Long, the right operand is masked with \(0 x 3 f\) using the bitwise AND (\&) operator, giving a number at most the number of bits in a Long.
The << operator left-shifts the left operand by the number of bits given by the right operand. The >> operator right-shifts the left operand by the number of bits given by the right operand. The result is sign extended; that is, if the right operand is
\(k\), the most significant \(k\) bits of the result are set to the most significant bit of the operand.

The >>> operator right-shifts the left operand by the number of bits given by the right operand. The result is not sign extended; that is, if the right operand is \(k\), the most significant \(k\) bits of the result are set to 0 . This operation is deprecated, and may be removed in a later version of the language.

\subsection*{11.13 Binary bitwise operations}

The binary bitwise operations operate on integral types, which are promoted to the longer of the two types. The \& operator performs the bitwise AND of the promoted operands. The \(\mid\) operator performs the bitwise inclusive OR of the promoted operands. The \({ }^{\wedge}\) operator performs the bitwise exclusive OR of the promoted operands.

\subsection*{11.14 String concatenation}

The + operator is used for string concatenation as well as addition. If either operand is of static type x10.lang. String, the other operand is converted to a String, if needed, and the two strings are concatenated. String conversion of a non-null value is performed by invoking the toString() method of the value. If the value is null, the value is converted to "null".

The type of the result is String.
For example, "one " \(+2+\) true evaluates to one 2 true.

\subsection*{11.15 Logical negation}

The unary! operator applied to type \(\times 10.1\) ang. Boolean performs logical negation. The type of the result is Boolean. If the value of the operand is true, the result is false; if if the value of the operand is false, the result is true.

\subsection*{11.16 Boolean logical operations}

The binary operations \& and | at type Boolean perform Boolean logical operations.

The \& operator evaluates to true if both of its operands evaluate to true; otherwise, the operator evaluates to false.

The | operator evaluates to false if both of its operands evaluate to false; otherwise, the operator evaluates to true.

\subsection*{11.17 Boolean conditional operations}

The binary \&\& and || operations, on Boolean values, give conditional or shortcircuiting Boolean operations.
The \&\& operator evaluates to true if both of its operands evaluate to true; otherwise, the operator evaluates to false. Unlike the logical operator \&, if the first operand is false, the second operand is not evaluated.
The || operator evaluates to false if both of its operands evaluate to false; otherwise, the operator evaluates to true. Unlike the logical operator \|I, if the first operand is true, the second operand is not evaluated.

\subsection*{11.18 Relational operations}

The relational operations on numeric types compare numbers, producing Boolean results.

The < operator evaluates to true if the left operand is less than the right. The <= operator evaluates to true if the left operand is less than or equal to the right. The \(>\) operator evaluates to true if the left operand is greater than the right. The >= operator evaluates to true if the left operand is greater than or equal to the right.

Floating point comparison is determined by the IEEE 754 standard. Thus, if either operand is NaN, the result is false. Negative zero and positive zero are considered to be equal. All finite values are less than positive infinity and greater than negative infinity.

\subsection*{11.19 Conditional expressions}

ConditionalExp \(::=\) ConditionalOrExp ? Exp : ConditionalExp
A conditional expression evaluates its first subexpression (the condition); if true the second subexpression (the consequent) is evaluated; otherwise, the third subexpression (the alternative) is evaluated.
The type of the condition must be Boolean. The type of the conditional expression is some common ancestor (as constrained by \(\S 4.10\) ) of the types of the consequent and the alternative.
Example: \(\mathrm{a}==\mathrm{b}\) ? \(1: 2\) evaluates to 1 if a and b are the same, and 2 if they are different. As the type of 1 is \(\operatorname{Int}\{\mathrm{self}==1\}\) and of 2 is \(\operatorname{Int}\{s e l f==2\}\), the type of the conditional expression has the form \(\operatorname{Int}\{\mathrm{c}\}\), where \(\mathrm{self} \mathrm{f}=1\) and sel \(\mathrm{f}==2\) both imply c . For example, it might be Int \{true\} - or perhaps it might be a more accurate type, like \(\operatorname{Int}\{\mathrm{self}!=8\}\). Note that this term has no most accurate type in the X10 type system.
The subexpression not selected is not evaluated.
Example: The following use of the conditional expression prevents division by zero. If \(\mathrm{den}==\mathbb{0}\), the division is not performed at all.
\[
\text { (den }==0) \text { ? } 0 \text { : num/den }
\]

Similarly, the following code performs a method call if op is non-null, and avoids the null pointer error if it is null. Defensive coding like this is quite common when working with possibly-null objects.
(ob == null) ? null : ob.toString();

\subsection*{11.20 Stable equality}
\[
\begin{array}{l|l}
\text { EqualityExp }::= & \text { RelationalExp } \\
& \left\lvert\, \begin{array}{l}
\text { EqualityExp }==\text { RelationalExp } \\
\\
\\
\\
\text { EqualityExp }!=\text { RelationalExp } \\
\text { Type }==\text { Type }
\end{array}\right.
\end{array}
\]

The \(==\) and \(!=\) operators provide a fundamental, though non-abstract, notion of equality. \(a==b\) is true if the values of \(a\) and \(b\) are extremely identical.
- If \(a\) and \(b\) are values of object type, then \(a==b\) holds if \(a\) and \(b\) are the same object.
- If one operand is null, then \(a==b\) holds iff the other is also null.
- The structs in \(\times 10\). lang have unsurprising concepts of \(==\) :
- In Boolean, true == true and false == false.
- In Char, \(c==\mathrm{diff} \mathrm{c} . \operatorname{ord}()==\mathrm{d} . \operatorname{ord}(\) ).
- Equality in Double and Float is IEEE floating-point equality.
- Two GlobalRefs are == if they refer to the same object.
- The integral types, Byte, Short, Int, Long, and their unsigned versions, use binary equality.
- If the operands both have struct type and are not in x10.lang, then they must be structurally equal; that is, they must be instances of the same struct and all their fields or components must be \(==\).
- The definition of equality for function types is specified in \(\$ 10.4\).
- No implicit coercions are performed by ==.
- It is a static error to have an expression \(a==b\) if the types of \(a\) and \(b\) are disjoint.
\(\mathrm{a}!=\mathrm{b}\) is true iff \(\mathrm{a}==\mathrm{b}\) is false.
The predicates \(==\) and \(!=\) may not be overridden by the programmer.
== provides a stable notion of equality. If two values are \(==\) at any time, they remain \(==\) forevermore, regardless of what happens to the mutable state of the program.
Example: Regardless of the values and types of a and b , or the behavior of any_code_at_all (which may, indeed, be any code at all-not just a method call), the value of \(\mathrm{a}==\mathrm{b}\) does not change:
```

val a = something();
val b = something_else();
val eq1 = (a == b);
any_code_at_all();
val eq2 = (a == b);
assert eq1 == eq2;

```

\subsection*{11.20.1 No Implicit Coercions for ==}
== is a primitive operation in X 10 - one of very few. Most operations, like + and \(<=\), are defined as operators. == and != are not. As non-operators, they need not and do not follow the general method resolution procedure of \(\S 8.11\). In particular, while operators perform implicit conversions on their arguments, == and \(!=\) do not.

The advantage of this restriction is that \(==\) 's behavior is as simple and efficient as possible. It never runs user-defined code, and the compiler can analyze and understand it in detail - and guarantee that it is efficient.

The disadvantage is that certain straightforward-looking idioms do not work. One may not test that a Long variable is \(==\) to an integer like \(\theta\) :
```

//ERROR: for(var i : Long = 0; i != 100; i++) {}

```

A Long like i can never == an Int like 100.
We can write i = i + 1;, adding an Int to i. This works because the expression uses + , an ordinary operator. There is an implicit coercion from Int to Long, so the 1 can be converted to 1 L , which can be added to \(i\).

However, == does not permit implicit coercions, and so the 100 stays an Int. The loop must be written with a comparison of two Longs:
```

for(var i : Long = 0; i != 100L; i++) {}

```

Incidentally, it could also be written
```

for(var i : Long = 0; i <= 100; i++) {}

```

The operation <= is a regular operator, and thus uses coercions in its arguments, so 100 gets coerced to 100 L .

Example: If numbers are cast to Any, they are compared as values of type Any, not as numbers. For example, 1 as Any \(==1 \mathrm{ul}\) as Any is not a static error (because it is comparing two values of type Any), and returns false (because the two Any values refer to different values - indeed, to values of different types, Int and ULong).

\subsection*{11.20.2 Non-Disjointness Requirement}

It is, in many cases, a static error to have an expression \(a==b\) where \(a\) and \(b\) could not possibly be equal, based on their types. (In one case it is a static error even though they could be equal.) This is a practical codicil to \(\$ 11.20 .1\). Consider the illegal code
```

// NOT ALLOWED
for(var i : Long = 0; i != 100; i++)

```

100 and 100L are different values; they are not \(==\). A coercion could make them equal, but \(==\) does not allow coercions. So, if \(100==100 \mathrm{~L}\) were going to return anything, it would have to return false. This would have the unfortunate effect of making the for loop run forever.
Since this and related idioms are so common, and since so many programmers are used to languages which are less precise about their numeric types, X10 avoids the mistake by declaring it a static error in most cases. Specifically, \(a==b\) is not allowed if, by inspection of the types, a and b could not possibly be equal.
Example: Nonetheless, it is possible to wind up comparing values of different numeric types. Even though, say, 0 and 0 L represent the same number, they are different values and of different types, and hence, 0 != 0L. The expression \(0==\)
OL does not compile. However, if you hide type information from X10, you can get a similar expression to compile:
```

val a : Any = 0;
val b : Any = OL;
assert a != b;

```
- Numbers of different base types cannot be equal, and thus cannot compared for equality. \(100==100 \mathrm{~L}\) is a static error. To compare numbers, explicitly cast them to the same type: 100 as Long \(==100 \mathrm{~L}\).
- Indeed, structs of different types cannot be equal, and so they cannot be compared for equality.
- For objects, the story is different. Unconstrained object types can always be compared for equality. Given objects of unrelated classes a:Person and b : Theory, \(\mathrm{a}==\mathrm{b}\) could be true if \(\mathrm{a}==\) null and \(\mathrm{b}==\mathrm{null}\). Despite this,
\(a==b\) is a static error, because it is generally a programming mistake. a as Object \(==\mathrm{b}\) as Object can be used to express the equality, if it is necessary.
- Constraints are ignored in determining whether an equality is statically allowed. For example, the following is allowed:
\[
\operatorname{def} m(a: \operatorname{Int}\{s e l f==1\}, b: \operatorname{Int}\{s e l f==2\})=(a==b) ;
\]
- Explicit casts erase type information. If you wanted to have a comparison a==b for \(a: P e r s o n\{s e l f!=n u l l\}\) and \(b\) :Theory, you could write it as a as Object == b as Object. It would, of course, return false, but it would not be a compiler error \(]^{1}\) A struct and an object may both be cast to Any and compared for equality, though they, too, will always be different.

\subsection*{11.21 Allocation}
\[
\begin{aligned}
\text { ObCreationExp }::= & \text { new TypeName TypeArgs? (ArgumentList? }{ }^{?} \text { ) ClassBody? } \\
& \left\lvert\, \begin{array}{l}
\text { Primary . new Id TypeArgs? (ArgumentList }{ }^{?} \text { ) ClassBody? } \\
\\
\\
\\
\\
\\
\\
\text { FullyQualifiedName . new Id TypeArgs? (ArgumentList }{ }^{?} \text { ) }
\end{array}\right.
\end{aligned}
\]

An allocation expression creates a new instance of a class and invokes a constructor of the class. The expression designates the class name and passes type and value arguments to the constructor.
The allocation expression may have an optional class body. In this case, an anonymous subclass of the given class is allocated. An anonymous class allocation may also specify a single super-interface rather than a superclass; the superclass of the anonymous class is x 10. lang. Object.
If the class is anonymous-that is, if a class body is provided-then the constructor is selected from the superclass. The constructor to invoke is selected using the same rules as for method invocation ( \(\$ 11.6\) ).
The type of an allocation expression is the return type of the constructor invoked, with appropriate substitutions of actual arguments for formal parameters, as specified in \(\$ 11.6\).

\footnotetext{
\({ }^{1}\) Code generators often find this trick to be useful.
}
88.13 .1 describes allocation expressions for inner classes.

It is illegal to allocate an instance of an abstract class. The usual visibility rules apply to allocations: it is illegal to allocate an instance of a class or to invoke a constructor that is not visible at the allocation expression.
Note that instantiating a struct type can use function application syntax; new is optional. As structs do not have subclassing, there is no need or possibility of a ClassBody.

\subsection*{11.22 Casts and Conversions}
\[
\begin{array}{rll}
\text { CastExp }::= & \text { Primary } \\
& \mid & \text { ExpName } \\
& \text { CastExp as Type }
\end{array}
\]

The cast and conversion operation e as T may be used to force an expression into a given type \(T\), if is permissible at run time, and either a compile-time error or a runtime exception (x10.lang. TypeCastException) if it is not.
The e as T operation comes in two forms. Which form applies depends on both the source type (the type of e) and the target type T.
- Cast: A cast makes a value have a different type, without changing the value's identity. For example, "a String" as Object simply reconsiders the String object as an Object. This cast does not need to do any run-time computation, since every String is an Object; a cast in the reverse direction, from Object to String, would need a run-time check that the Object was in fact a String. Casts are all system-defined, following from the X10 type system.
- Conversions: A conversion takes a value of one type and produces one of a different type which, conceptually, means the same thing. For example, 1 as Float is a conversion. It performs some computation on 1 to come up with a Float value. Conversions are all library- or user-defined.

\subsection*{11.22.1 Casts}

A cast v as T 2 re-imagines a value v of one type T 1 as being a value of another type T2. The value itself does not change, nor is a new value computed. The only
run-time computation that happens is to check that \(v\) is indeed a value of type T2 (which, in many cases, is unnecessary), and auto-boxing ( \(\$ 9.2\) ).
Casts to generic types can be unsound. The instantiations of the generic types have constraints, but the runtime does not preserve the representation of these types. See \(\$ 4.5 .5\) for more details.
There are two forms of casts. Upcasts happen when T1 <: T2, that is, when a value is being cast to a more general type. Upcasts often don't require any runtime computation at all, since, if T1 <: T2 <: Object, every value of type T1 is automatically one of type T2. For example, "A String" as Object is an upcast: every String is already an Object, and no work need be done to make it one. Other upcasts may require auto-boxing, such as 1 as Any.

Downcasts are casts which are not upcasts. Often they are recasting something from a more general to a more specific type, though casts that cross the type hierarchy laterally are also called downcasts.
```

val ob : Object = "a String" as Object; // upcast
val st : String = ob as String; // downcast
assert st == ob;

```

\section*{Example:}

In the following example, Snack and Crunchy are unrelated interfaces: neither inherits from the other. Some objects are both; some are one but not the other. Casting from a Crunchy to a Snack requires confirming that the value being cast is indeed a Snack.
```

interface Snack {}
interface Crunchy {}
class Pretzel implements Snack, Crunchy{}
class Apricot implements Snack{}
class Gravel implements Crunchy{}
class Example{
def example(crunchy : Crunchy) {
if (crunchy instanceof Snack) {
val snack = crunchy as Snack;
} } }

```

An upcast v as T 2 requires no computation. A downcast v as T 2 requires testing that \(v\) really is a value of type T 2 . In either case, the cast returns the value v ; casts do not change value identity.

When evaluating \(E\) as \(T\{c\}\), first the value of \(E\) is converted to type \(T\) (which may fail), and then the constraint \(\{c\}\) is checked (which may also fail).
- If T is a class, then the first half of the cast succeeds if the run-time value of \(E\) is an instance of class \(T\), or of a subclass.
- If T is an interface, then the first half of the cast succeeds if the run-time value of \(E\) is an instance of a class or struct implementing \(T\).
- If \(T\) is a struct type, then the first half of the cast succeeds if the run-time value of \(E\) is an instance of \(T\).
- If T is a function type, then the first half of the cast succeeds if the run-time value of X is a function of that type, or an object or struct which implements it.

If the first half of the cast succeeds, the second half - the constraint \(\{c\}\) - must be checked. In general this will be done at runtime, though in special cases it can be checked at compile time. For example, \(n\) as \(\operatorname{Int}\{\) self \(!=w\}\) succeeds if \(n\)
\(!=\mathrm{w}\) - even if w is a value read from input, and thus not determined at compile time.

The compiler may forbid casts that it knows cannot possibly work. If there is no way for the value of \(E\) to be of type \(T\{c\}\), then \(E\) as \(T\{c\}\) can result in a static error, rather than a runtime error. For example, 1 as \(\operatorname{Int}\{s e l f==2\}\) may fail to compile, because the compiler knows that 1 , which has type \(\operatorname{Int}\{s e l f==1\}\), cannot possibly be of type Int \(\{\) self \(==2\}\).
If, for some reason, you need to write one of these forbidden casts, cast to Any first. (1 as Any) as Int \(\{\operatorname{self}==2\}\) always returns false, but compiles.

\subsection*{11.22.2 Explicit Conversions}

Explicit conversions are written with the same syntax as casts: v as T2. Explicit conversions transform a value of one type T 1 to an unrelated type T 2 . Unlike casts, conversions do execute code, and may (and generally do) return new values.
Explicit conversions do not arise spontaneously, as casts do. They may be programmed directly, using the operator syntax of 8.7.3. Implicit coercions can
also be called explicitly as conversions. (The reverse is not true - explicit conversions cannot be used as implicit conversions.)

The numeric types in x10. lang have explicit conversions, as described in \(\S 11.23 .1\). These conversions enable 1 as Float and the like.

Example: The following class has an explicit conversion from Int to Knot, and an implicit one from String to Knot. a uses the explicit conversion, b uses the implicit coercion, and c uses the implicit coercion explicitly.
```

class Knot(s:String){
public def is(t:String):Boolean = s.equals(t);
// explicit conversion
public static operator (n:Int) as Knot = new Knot("knot-" + n);
// implicit coercion
public static operator (s:String):Knot = new Knot(s);
// using them
public static def example() {
val a : Knot = 1 as Knot;
val b : Knot = "frayed";
val c : Knot = "three" as Knot;
assert a.is("knot-1") \&\& b.is("frayed") \&\& c.is("three");
}
}

```

\subsection*{11.22.3 Resolving Ambiguity}

If \(v\) as \(T\) could either be a cast or an explicit coercion, X10 treats its as a cast. With the VERBOSE compiler flag, this is flagged as a warning.

Example: The Person class provides an explicit conversion from its subclass Fop to itself. However, since Fop is a subclass of Person, using the as operator invokes the upcast, rather than the explicit conversion. This is visible in the example because the user-defined operator \(£\) as Person returns new Person() (just like the asPerson method), while the upcast returns \(£\) itself.
```

class Person {
static operator (f:Fop) as Person = new Person();
static def asPerson(f:Fop) = new Person();
public static def example() {

```
```

        val f = new Fop();
        val cast = f as Person; // WARNING on this line
        assert cast == f;
        val meth = asPerson(f);
        assert meth != f;
    }
    }
class Fop extends Person {}

```

The definition of an explicit conversion in this case is of little value, since any use of it in the \(f\) as Person syntax will invoke the upcast.

\subsection*{11.23 Coercions and conversions}

A coercion does not change object identity; a coerced object may be explicitly coerced back to its original type through a cast. A conversion may change object identity if the type being converted to is not the same as the type converted from. X10 permits both user-defined coercions and conversions ( \(\$ 11.23 .2\) ).

\subsection*{11.23.1 Coercions}
\[
\begin{aligned}
& \text { CastExp }::=\text { Primary } \\
& \mid \\
& \text { ExpName } \\
& \text { CastExp as Type }
\end{aligned}
\]

Subsumption coercion. A value of a subtype may be implicitly coerced to any supertype.
Example: If Child <: Person and val rhys:Child, then rhys may be used in any context that expects a Person. For example,
```

class Example {
def greet(Person) = "Hi!";
def example(rhys: Child) {
greet(rhys);
}
}

```

Similarly, 2 (whose innate type is \(\operatorname{Int}\{\mathrm{sel} \mathrm{f}==2\}\) ) is usable in a context requiring a non-zero integer (Int \{self != 0\}).

Explicit Coercion (Casting with as) All classes and interfaces allow the use of the as operator for explicit type coercion. Any class or interface may be cast to any interface. Any interface may be cast to any class. Also, any interface can be cast to a struct that implements (directly or indirectly) that interface.

Example: In the following code, a Person is cast to Childlike. There is nothing in the class definition of Person that suggests that a Person can be Childlike. However, the Person in question, p, is actually a HappyChild - a subclass of Person - and is, in fact, Childlike.

Similarly, the Childlike value cl is cast to Happy. Though these two interfaces are unrelated, the value of cl is, in fact, Happy. And the Happy value hc is cast to the class Child, though there is no relationship between the two, but the actual value is a HappyChild, and thus the cast is correct at runtime.

Cyborg is a struct rather than a class. So, it cannot have substructs, and all the interfaces of all Cyborgs are known: a Cyborg is Personable, but not Childlike or Happy. So, it is correct and meaningful to cast r to Personable. There is no way that a cast to Childlike could succeed, so r as Childlike is a static error.
```

interface Personable {}
class Person implements Personable {}
interface Childlike extends Personable {}
class Child extends Person implements Childlike {}
struct Cyborg implements Personable {}
interface Happy {}
class HappyChild extends Child implements Happy {}
class Example {
static def example() {
var p : Person = new HappyChild();
// class -> interface
val cl : Childlike = p as Childlike;
// interface -> interface
val hc : Happy = cl as Happy;
// interface -> class
val ch : Child = hc as Child;

```
```

        var r : Cyborg = Cyborg();
        val rl : Personable = r as Personable;
        // ERROR: val no = r as Childlike;
    }
    }

```

If the value coerced is not an instance of the target type, and no coercion operators that can convert it to that type are defined, a ClassCastException is thrown. Casting to a constrained type may require a run-time check that the constraint is satisfied.

It is a static error, rather than a ClassCastException, when the cast is statically determinable to be impossible.

Effects of explicit numeric coercion Coercing a number of one type to another type gives the best approximation of the number in the result type, or a suitable disaster value if no approximation is good enough.
- Casting a number to a wider numeric type is safe and effective, and can be done by an implicit conversion as well as an explicit coercion. For example, 4 as Long produces the Long value of 4 .
- Casting a floating-point value to an integer value truncates the digits after the decimal point, thereby rounding the number towards zero. 54.321 as Int is 54 , and -54.321 as Int is -54 . If the floating-point value is too large to represent as that kind of integer, the coercion returns the largest or smallest value of that type instead: 1 e 110 as Int is Int.MAX_VALUE, viz. 2147483647.
- Casting a Double to a Float normally truncates binary digits:
0.12345678901234567890 as Float is approximately 0.12345679 f.

This can turn a nonzero Double into 0.0f, the zero of type Float: 1e-100 as Float is 0.0f. Since Doubles can be as large as about 1.79 E 308 and Floats can only be as large as about 3.4E38f, a large Double will be converted to the special Float value of Infinity: 1 e 100 as Float is Infinity.
- Integers are coerced to smaller integer types by truncating the high-order bits. If the value of the large integer fits into the smaller integer's range, this
gives the same number in the smaller type: 12 as Byte is the Byte-sized 12, -12 as Byte is -12 . However, if the larger integer doesn' \(t\) fit in the smaller type, the numeric value and even the sign can change: 254 as Byte is the Bytesized \(-2 y\).
- Casting an unsigned integer type to a signed integer type of the same size (e.g., UInt to Int) preserves 2's-complement bit pattern (e.g., UInt. MAX_VALUE as Int \(==-1\). Casting an unsigned integer type to a signed integer type of a different size is equivalent to first casting to an unsigned integer type of the target size, and then casting to a signed integer type.
- Casting a signed integer type to an unsigned one is similar.

\section*{User-defined Coercions}

Users may define coercions from arbitrary types into the container type \(B\), and coercions from B to arbitrary types, by providing static operator definitions for the as operator in the definition of \(B\).

\section*{Example:}
```

class Bee {
public static operator (x:Bee) as Int = 1;
public static operator (x:Int) as Bee = new Bee();
def example() {
val b:Bee = 2 as Bee;
assert (b as Int) == 1;
}
}

```

\subsection*{11.23.2 Conversions}

Widening numeric conversion. A numeric type may be implicitly converted to a wider numeric type. In particular, an implicit conversion may be performed between a numeric type and a type to its right, below:
```

Byte < Short < Int < Long < Float < Double
UByte < UShort < UInt < ULong

```

Furthermore, an unsigned integer value may be implicitly coerced to a signed type large enough to hold any value of the type: UByte to Short, UShort to Int, UInt to Long. There are no implicit conversions from signed to unsigned numbers, since they cannot treat negatives properly.

There are no implicit conversions in cases when overflow is possible. For example, there is no implicit conversion between Int and UInt. If it is necessary to convert between these types, use n as Int or n as UInt, generally with a test to ensure that the value will fit and code to handle the case in which it does not.

String conversion. Any value that is an operand of the binary + operator may be converted to String if the other operand is a String. A conversion to String is performed by invoking the toString() method.

User defined conversions. The user may define implicit conversion operators from type A to a container type B by specifying an operator in B's definition of the form:
```

public static operator (r: A): T = ...

```

The return type T should be a subtype of B. The return type need not be specified explicitly; it will be computed in the usual fashion if it is not. However, it is good practice for the programmer to specify the return type for such operators explicitly. The return type can be more specific than simply B, for cases when there is more information available.

Example: The code for \(\mathrm{x} 10 . \mathrm{l}\) ang. Point contains a conversion from onedimensional Arrays of integers to Points of the same length:
```

public operator (r: Array[Int](1)): Point(r.size)
= make(r);

```

This conversion is used whenever an array of integers appears in a context that requires a Point, such as subscripting. Note that a requires a Point of rank 2 as a subscript, and that a two-element Array (like \([2,4]\) ) is converted to a Point(2).
```

val a = new Array[String]((2..3) * (4..5), "hi!");
a([2,4]) = "converted!";

```

\subsection*{11.24 instanceof}

X10 permits types to be used in an in instanceof expression to determine whether an object is an instance of the given type:
\begin{tabular}{|c|c|}
\hline RelationalExp & \begin{tabular}{l}
ShiftExp \\
HasZeroConstraint \\
SubtypeConstraint \\
RelationalExp < ShiftExp \\
RelationalExp \(>\) ShiftExp \\
RelationalExp \(<=\) ShiftExp \\
RelationalExp >=ShiftExp \\
RelationalExp instanceof Type
\end{tabular} \\
\hline
\end{tabular}

In the above expression, Type is any type. At run time, the result of e instanceof \(T\) is true if the value of \(e\) is an instance of type \(T\). Otherwise the result is false. This determination may involve checking that the constraint, if any, associated with the type is true for the given expression.
For example, 3 instanceof \(\operatorname{Int}\{\) self==x\} is an overly-complicated way of saying \(3==x\).
However, it is a static error if e cannot possibly be an instance of C\{c\}; the compiler will reject 1 instanceof Int\{self \(==2\}\) because 1 can never satisfy Int \(\{s e l f==2\}\). Similarly, 1 instanceof String is a static error, rather than an expression always returning false.
If \(x\) instanceof \(T\) returns true for some value \(x\) and type \(T\), then \(x\) as \(T\) will evaluate normally.
Limitation: X10 does not currently handle instanceof of generics in the way you might expect. For example, r instanceof Array[Int \{self !=0 \(\}\) ] does not test that every element of \(r\) is non-zero; instead, the compiler gives an unsound cast warning.

\subsection*{11.24.1 Nulls in Constraints in as and instanceof}

Both as and instanceof expressions can throw NullPointerExceptions, if the constraints involve selecting fields or properties of variables which are bound to null.

These operations give some guarantees for any type \(T\), constraint c , and class SomeObj with an a field:
1. null instanceof \(T\) always returns false. It never throws an exception. It never returns true, not even in cases where null could be assigned to a variable of type T .
2. null can be assigned to a variable of type SomeObj\{self.a==b\}, or, more broadly, to a variable of a constrained object type whose constraint does not explicitly exclude null. This is the case even though null.a==b would throw a NullPointerException rather than evaluate to either true ' or false.
3. If \(x\) instanceof \(T\) returns true, then \(x\) as \(T\) is a cast rather than an explicit conversion, and will succeed and have static type \(T\).
4. If the static type of \(x\) is \(T\), then \(x\) instanceof \(T\) and \(x\) as \(T\) will do one of these:
- Succeed, with x instanceof T returning true, and x as T being a cast and returning value of type T ; or
- Throw a NullPointerException.
- If \(x==n u l l\), then \(x\) instanceof \(T\) will always return false, and \(x\) as T will either return a null of type T , or, if T has a constraint which tries to extract a field of x , will throw a NullPointerException.
5. If \(x\) instanceof SomeObj\{self.a==b\} is true, then \(x . a==b\) evaluates to true (rather than a null pointer exception). Indeed, in general, if \(x\) instanceof \(T\{c\}\) succeeds, then cc evaluates to true, where cc is c with suitable occurrences of self replaced by \(x\).

\subsection*{11.25 Subtyping expressions}

SubtypeConstraint ::= Type <: Type
(20.149)

The subtyping expression \(\mathrm{T}_{1}<: \mathrm{T}_{2}\) evaluates to true if \(\mathrm{T}_{1}\) is a subtype of \(\mathrm{T}_{2}\).

The expression \(T_{1}:>T_{2}\) evaluates to true if \(T_{2}\) is a subtype of \(T_{1}\).
The expression \(\mathrm{T}_{1}==\mathrm{T}_{2}\) evaluates to true if \(\mathrm{T}_{1}\) is a subtype of \(\mathrm{T}_{2}\) and if \(\mathrm{T}_{2}\) is a subtype of \(\mathrm{T}_{1}\).
Example: Subtyping expressions are particularly useful in giving constraints on generic types. \(\mathrm{x} 10 . \mathrm{util}\). Ordered[T] is an interface whose values can be compared with values of type T . In particular, \(\mathrm{T}<\) : x10. util. Ordered[T] is true if values of type T can be compared to other values of type T . So, if we wish to define a generic class OrderedList [T], of lists whose elements are kept in the right order, we need the elements to be ordered. This is phrased as a constraint on T :
```

class OrderedList[T]{T <: x10.util.Ordered[T]} {
// ...
}

```

\subsection*{11.26 Array Constructors}
```

Primary ::= [ ArgumentList?]

```

X10 includes short syntactic forms for constructing one-dimensional arrays. Enclose some expressions in brackets to put them in an array:
```

val ints <: Array[Int](1) = [1,3,7,21];

```

The expression \(\left[\mathrm{e}_{1}, \ldots, \mathrm{e}_{n}\right.\) ] produces an n-element Array [T] (1), where T is the computed common supertype ( 84.10 ) of the types of of the expressions \(\mathbf{e}_{i}\).
Example: The type of \([0,1,2]\) is Array[Int] (1). The type of [0] is Array[Int\{self==0\}] (1).
To make an Array[Int] (1) containing just a 0, use [0 as Int]. The as Int masks more detailed type information, such as the fact that 0 is zero.
Example: Occasionally one does actually need Array[Int \{self==0\}] (1), or, say, Array[Eel\{self != null\}] (1), an array of non-null Eels. For these cases, cast one or more of the elements of the array to the desired type, and the array constructor will do the right thing.
```

val zero <: Array[Int{self == 0}](1)
= [0];

```
```

val non1 <: Array[Int{self != 1}](1)
= [0 as Int{self != 1}];
val eels <: Array[Eel{self != null}](1)
= [new Eel() as Eel{self != null},
new Eel(), new Eel()];

```

\subsection*{11.27 Parenthesized Expressions}

If \(E\) is any expression, ( \(E\) ) is an expression which, when evaluated, produces the same result as E .
Example: The main use of parentheses is to write complex expressions for which the standard precedence order of operations is not appropriate: \(1+2 * 3\) is 7 , but \((1+2) * 3\) is 9 .
Similarly, but perhaps less familiarly, parentheses can disambiguate other expressions. In the following code, funny. \(£\) is a field-selection expression, and so (funny.f) () means "select the \(£\) field from funny, and evaluate it". However, funny. f() means "evaluate the f method on object funny."
```

class Funny {
def f () = 1;
val f = () => 2;
static def example() {
val funny = new Funny();
assert funny.f() == 1;
assert (funny.f)() == 2;
}
}

```

Note that this does not mean that E and (E) are identical in all respects; for example, if \(i\) is an Int variable, \(i++\) increments \(i\), but ( \(i\) )++ is not allowed. ++ is an assignment; it operates on variables, not merely values, and (i) is simply an expression whose value is the same as that of \(i\).

\section*{12 Statements}

This chapter describes the statements in the sequential core of X10. Statements involving concurrency and distribution are described in \(\$ 14\)

\subsection*{12.1 Empty statement}

The empty statement ; does nothing.

Example: Sometimes, the syntax of X 10 requires a statement in some position, but you do not actually want to do any computation there. The following code searches the array a for the value v , assumed to appear somewhere in a, and returns the index at which it was found. There is no computation to do in the loop body, so we use an empty statement there.
```

static def search[T](a: Array[T](1), v: T):Int {
var i : Int;
for(i = a.region.min(0); a(i) != v; i++)
;
return i;
}

```

\subsection*{12.2 Local variable declaration}


Short-lived variables are introduced by local variables declarations, as described in \(\S 12.2\). Local variables may be declared only within a block statement ( \(\$ 12.3\) ). The scope of a local variable declaration is the subsequent statements in the block.
```

if (a > 1) {
val b = a/2;
var c : Int = 0;
// b and c are defined here
}
// b and c are not defined here.

```

Variables declared in such statements shadow variables of the same name declared elsewhere. A local variable of a given name, say x, cannot shadow another local variable or parameter named x unless there is an intervening method, constructor, initializer, or closure declaration.

Example: The following code illustrates both legal and illegal uses of shadowing. Note that a shadowed field name x can still be accessed as this. x .
```

class Shadow{
var x : Int;
def this(x:Int) {
// Parameter can shadow field
this.x = x;
}
def example(y:Int) {

```
```

        val x = "shadows a field";
        // ERROR: val y = "shadows a param";
        val z = "local";
        for (a in [1,2,3]) {
        // ERROR: val x = "can't shadow local var";
        }
        async {
            // ERROR: val x = "can't shadow through async";
        }
        val f = () => {
            val x = "can shadow through closure";
            x
        };
        class Local {
            val f = at(here.next()){ val x = "can here"; x };
            def this() { val x = "can here, too"; }
        }
    }
    }

```

Example: Note that recursive definitions of local variables is not allowed. There are few useful recursive declarations of objects and structs; \(\mathbf{x}\), in the following example, has no meaningful definition. Recursive declarations of local functions is forbidden, even though (like f below) there are meaningful uses of it.
```

val x : Int = x + 1; // ERROR: recursive local declaration
val f : (Int)=>Int
= (n:Int) => (n <= 2) ? 1 : f(n-1) + f(n-2);
// ERROR: recursive local declaration

```

\subsection*{12.3 Block statement}
\begin{tabular}{lll} 
Block & \(::=\) \{ BlockStmts? \\
BlockStmts & \(:=\) & BlockInteriorStmt \\
& \(\mid\) & BlockStmts BlockInteriorStmt \\
BlockInteriorStmt & \(:=\) & LocVarDeclnStmt \\
& \(\mid\) & ClassDecln \\
& \(|\)\begin{tabular}{ll} 
StructDecln
\end{tabular} \\
& TypeDefDecln & \\
& & Stmt
\end{tabular}

A block statement consists of a sequence of statements delimited by "\{" and " \(\}\) ". When a block is evaluated, the statements inside of it are evaluated in order. Blocks are useful for putting several statements in a place where X10 asks for a single one, such as the consequent of an if, and for limiting the scope of local variables.
```

if (b) {
// This is a block
val v = 1;
S1(v);
S2(v);
}

```

\subsection*{12.4 Expression statement}

Any expression may be used as a statement.
```

ExpStmt ::= StmtExp ;
StmtExp ::= Assignment
StmtExp ::= Assignment
| PreIncrementExp
| PreDecrementExp
| PostIncrementExp
| PostDecrementExp
| MethodInvo
| ObCreationExp

```

The expression statement evaluates an expression. The value of the expression is not used. Side effects of the expression occur, and may produce results used by following statements. Indeed, statement expressions which terminate without side effects cannot have any visible effect on the results of the computation.

\section*{Example:}
```

class StmtEx {
def this() {
x10.io.Console.OUT.println("New StmtEx made"); }
static def call() {
x10.io.Console.OUT.println("call!");}
def example() {
var a : Int = 0;
a = 1; // assignment
new StmtEx(); // allocation
call(); // call
}
}

```

\subsection*{12.5 Labeled statement}

\section*{LabeledStatement \(::=\quad\) Id \(:\) Statement}

Statements may be labeled. The label may be used to describe the target of a break statement appearing within a substatement (which, when executed, ends the labeled statement), or, in the case of a loop, a continue as well (which, when executed, proceeds to the next iteration of the loop). The scope of a label is the statement labeled.

Example: The label on the outer for statement allows continue and break statements to continue or break it. Without the label, continue or break would only continue or break the inner for loop.
```

lbl : for (i in 1..10) {
for (j in i..10) {
if (a(i,j) == 0) break lbl;
if (a(i,j) == 1) continue lbl;
if (a(i,j) == a(j,i)) break lbl;

```
```

    }
    }

```

In particular, a block statement may be labeled: L: \{S\}. This allows the use of break L within S to leave S, which can, if carefully used, avoid deeply-nested ifs.

\section*{Example:}
```

multiphase: {
if (!exists(filename)) break multiphase;
phase1(filename);
if (!suitable_for_phase_2(filename)) break multiphase;
phase2(filename);
if (!suitable_for_phase_3(filename)) break multiphase;
phase3(filename);
}
// Now the file has been phased as much as possible

```

Limitation: Blocks cannot currently be labeled.

\subsection*{12.6 Break statement}
\[
\text { BreakStmt }::=\text { break } I d^{?} \text {; }
\]

An unlabeled break statement exits the currently enclosing loop or switch statement. A labeled break statement exits the enclosing statement with the given label. It is illegal to break out of a statement not defined in the current method, constructor, initializer, or closure. break is only allowed in sequential code.
Example: The following code searches for an element of a two-dimensional array and breaks out of the loop when it is found:
```

var found: Boolean = false;
outer: for (var i: Int = 0; i < a.size; i++)
for (var j: Int = 0; j < a(i).size; j++)
if (a(i)(j) == v) {
found = true;
break outer;
}

```

\subsection*{12.7 Continue statement}

ContinueStmt \(::=\) continue \(I d^{?}\);
An unlabeled continue skips the rest of the current iteration of the innermost enclosing loop, and proceeds on to the next. A labeled continue does the same to the enclosing loop with that label. It is illegal to continue a loop not defined in the current method, constructor, initializer, or closure. continue is only allowed in sequential code.

\subsection*{12.8 If statement}
\[
\begin{array}{ll}
\text { IfThenStmt } & ::=\text { if (Exp ) Stmt } \\
\text { IfThenElseStmt } & ::=\text { if (Exp ) Stmt else Stmt }
\end{array}
\]
20.90
20.89)

An if statement comes in two forms: with and without an else clause.
The if-then statement evaluates a condition expression, which must be of type Boolean. If the condition is true, it evaluates the then-clause. If the condition is false, the if-then statement completes normally.
The if-then-else statement evaluates a Boolean expression and evaluates the thenclause if the condition is true; otherwise, the else-clause is evaluated.

As is traditional in languages derived from Algol, the if-statement is syntactically ambiguous. That is,
```

if (B1) if (B2) S1 else S2

```
could be intended to mean either
```

if (B1) { if (B2) S1 else S2 }

```
or
```

if (B1) {if (B2) S1} else S2

```

X10, as is traditional, attaches an else clause to the most recent if that doesn't have one. This example is interpreted as if (B1) \{ if (B2) S1 else S2 \}.

\subsection*{12.9 Switch statement}
\begin{tabular}{lcl} 
SwitchStmt & \(::=\) & switch (Exp ) SwitchBlock \\
SwitchBlock & \(::=\) & \{ SwitchBlockGroups? SwitchLabels? \(\}\) \\
SwitchBlockGroups & \(::=\) & SwitchBlockGroup \\
& \(\mid\) & SwitchBlockGroups SwitchBlockGroup \\
SwitchBlockGroup & \(:=\) & SwitchLabels BlockStmts \\
SwitchLabels & \(::=\) & SwitchLabel \\
& \(\mid:\) & SwitchLabels SwitchLabel \\
SwitchLabel & \(:=\) & case ConstantExp : \\
& \(\mid\) & default :
\end{tabular}

A switch statement evaluates an index expression and then branches to a case whose value is equal to the value of the index expression. If no such case exists, the switch branches to the default case, if any.

Statements in each case branch are evaluated in sequence. At the end of the branch, normal control-flow falls through to the next case, if any. To prevent fall-through, a case branch may be exited using a break statement.

The index expression must be of type Int. Case labels must be of type Int, Byte, or Short, and must be compile-time constants. Case labels cannot be duplicated within the switch statement.

Example: In this switch, case 1 falls through to case 2. The other cases are separated by breaks.
```

switch (i) {
case 1: println("one, and ");
case 2: println("two");
break;
case 3: println("three");
break;
default: println("Something else");
break;
}

```

\subsection*{12.10 While statement}
\[
\text { WhileStmt }::=\text { while (Exp) Stmt }
\]

A while statement evaluates a Boolean-valued condition and executes a loop body if true. If the loop body completes normally (either by reaching the end or via a continue statement with the loop header as target), the condition is reevaluated and the loop repeats if true. If the condition is false, the loop exits.
Example: A loop to execute the process in the Collatz conjecture (a.k.a. 3n+1 problem, Ulam conjecture, Kakutani's problem, Thwaites conjecture, Hasse's algorithm, and Syracuse problem) can be written as follows:
```

while (n > 1) {
n = (n % 2 == 1) ? 3*n+1 : n/2;
}

```

\subsection*{12.11 Do-while statement}
\[
\text { DoStmt }::=\text { do Stmt while (Exp) ; }
\]

A do-while statement executes the loop body, and then evaluates a Booleanvalued condition expression. If true, the loop repeats. Otherwise, the loop exits.

\subsection*{12.12 For statement}
\begin{tabular}{|c|c|c|c|}
\hline ForStmt & ::= & BasicForStmt & 20.73 \\
\hline & - & EnhancedForStmt & \\
\hline BasicForStmt & ::= & for (ForInit? ; Exp? ; ForUpdate? ) Stmt & 20.22 \\
\hline ForInit & ::= & StmtExpList & (20.72) \\
\hline & | & LocVarDecln & \\
\hline ForUpdate & ::= & StmtExpList & 20.74 \\
\hline StmtExpList & ::= & StmtExp & 20.147 \\
\hline & & StmtExpList , StmtExp & \\
\hline EnhancedForStmt & ::= & for (LoopIndex in Exp ) Stmt & 20.57 \\
\hline & & for (Exp) Stmt & \\
\hline
\end{tabular}
for statements provide bounded iteration, such as looping over a list. It has two forms: a basic form allowing near-arbitrary iteration, a la C, and an enhanced form designed to iterate over a collection.

A basic for statement provides for arbitrary iteration in a somewhat more organized fashion than a while. The loop for (init; test; step)body is similar to:
```

{
init;
while(test) {
body;
step;
}
}

```
except that continue statements which continue the for loop will perform the step, which, in the while loop, they will not do.
init is performed before the loop, and is traditionally used to declare and/or initialize the loop variables. It may be a single variable binding statement, such as var i:Int = 0 or var i:Int=0, j:Int=100. (Note that a single variable binding statement may bind multiple variables.) Variables introduced by init may appear anywhere in the for statement, but not outside of it. Or, it may be a sequence of expression statements, such as \(i=0, j=100\), operating on alreadydefined variables. If omitted, init does nothing.
test is a Boolean-valued expression; an iteration of the loop will only proceed if test is true at the beginning of the loop, after init on the first iteration or after step on later ones. If omitted, test defaults to true, giving a loop that will run until stopped by some other means such as break, return, or throw.
step is performed after the loop body, between one iteration and the next. It traditionally updates the loop variables from one iteration to the next: e.g., i++ and \(i++, j--\). If omitted, step does nothing.
body is a statement, often a code block, which is performed whenever test is true. If omitted, body does nothing.
An enhanced for statement is used to iterate over a collection, or other structure designed to support iteration by implementing the interface Iterable[T]. The loop variable must be of type \(T\), or destructurable from a value of type \(T\) ( \(\$ 5\) ).

Each iteration of the loop binds the iteration variable to another element of the collection. The loop for ( \(x\) in c) S behaves like:
```

val iterator: Iterator[T] = c.iterator();
while (iterator.hasNext()) {
val x : T = iterator.next();
S();
}

```

A number of library classes implement Iterable, and thus can be iterated over. For example, iterating over a Region iterates the Points in the region, and iterating over an Array iterates over the Points at which the array is defined.
The type of the loop variable may be supplied as \(x<\) : T. In this case the iterable c must have type Iterable \([\mathrm{U}\}\) for some \(\mathrm{U}<\) : T , and x will be given the type U .
Example: This loop adds up the elements of a List [Int]. Note that iterating over a list yields the elements of the list, as specified in the List API.
```

static def sum(a:x10.util.List[Int]):Int {
var s : Int = 0;
for(x in a) s += x;
return s;
}

```

The following code sums the elements of an integer array. Note that the for loop iterates over the indices of the array, not the elements, as specified in the Array API.
```

static def sum(a: Array[Int]): Int {
var s : Int = 0;
for(p in a) s += a(p);
return s;
}

```

Iteration over an IntRange (§16.2) is quite common. This allows looping while varying an integer index:
```

var sum : Int = 0;
for(i in 1..10) sum += i;
assert sum == 55;

```

Iteration variables have the for statement as scope. They shadow other variables of the same names.

\subsection*{12.13 Return statement}
\[
\text { ReturnStmt }::=\text { return Exp? }
\]

Methods and closures may return values using a return statement. If the method's return type is explicitely declared void, the method must return without a value; otherwise, it must return a value of the appropriate type.
Example: The following code illustrates returning values from a closure and a method. The return inside of closure returns from closure, not from method.
```

def method(x:Int) {
val closure = (y:Int) => {return x+y;};
val res = closure(Q);
assert res == x;
return res == x;
}

```

\subsection*{12.14 Assert statement}
\[
\begin{align*}
\text { AssertStmt }::= & \text { assert Exp ; } \\
& \mid \text { assert Exp : Exp ; }
\end{align*}
\]

The statement assert E checks that the Boolean expression E evaluates to true, and, if not, throws an x10.lang.Error exception. The annotated assertion statement assert E : F; checks E, and, if it is false, throws an x10.lang. Error exception with F's value attached to it.
Example: The following code compiles properly.
```

class Example {
public static def main(argv:Array[String](1)) {
val a = 1;
assert a != 1 : "Changed my mind about a.";
}
}

```

However, when run, it prints a stack trace starting with
x10.lang.Error: Changed my mind about a.

\subsection*{12.15 Exceptions in X10}

X10 programs can throw Exceptions to indicate unusual or problematic situations; this is abrupt termination. Exceptions, as data values, are objects which which inherit from x10.lang. Throwable. Exceptions may be thrown intentionally with the throw statement. Many primitives and library functions throw exceptions if they encounter problems; e.g., dividing by zero throws an instance of x10.lang.ArithmeticException.

When an exception is thrown, statically and dynamically enclosing try-catch blocks in the same activity can attempt to handle it. If the throwing statement in inside some try clause, and some matching catch clause catches that type of exception, the corresponding catch body will be executed, and the process of throwing is finished. If no statically-enclosing try-catch block can handle the exception, the current method call returns (abnormally), throwing the same exception from the point at which the method was called.

This process continues until the exception is handled or there are no more calling methods in the activity. In the latter case, the activity will terminate abnormally, and the exception will propagate to the activity's root; see \(\$ 14.1\) for details.

Unlike some statically-typed languages with exceptions, X10's exceptions are all unchecked. Methods do not declare which exceptions they might throw; any method can, potentially, throw any exception.

\subsection*{12.16 Throw statement}
\[
\text { ThrowStmt }::=\text { throw Exp ; }
\]
throw \(E\) throws an exception whose value is \(E\), which must be an instance of a subtype of \(x 10\). lang. Throwable.

Example: The following code checks if an index is in range and throws an exception if not.
```

if (i < 0 || i >= x.size)
throw new MyIndexOutOfBoundsException();

```

\subsection*{12.17 Try-catch statement}
\begin{tabular}{lll} 
TryStmt & \(::=\) try Block Catches \\
& \(\mid \quad\) try Block Catches? Finally & \\
Catches & \(:=\) & CatchClause \\
& \(\mid\) & Catches CatchClause \\
CatchClause & \(:=\) & catch ( Formal) Block \\
Finally & \(::=\) finally Block
\end{tabular}

Exceptions are handled with a try statement. A try statement consists of a try block, zero or more catch blocks, and an optional finally block.
First, the try block is evaluated. If the block throws an exception, control transfers to the first matching catch block, if any. A catch matches if the value of the exception thrown is a subclass of the catch block's formal parameter type.
The finally block, if present, is evaluated on all normal and exceptional controlflow paths from the try block. If the try block completes normally or via a return, a break, or a continue statement, the finally block is evaluated, and then control resumes at the statement following the try statement, at the branch target, or at the caller as appropriate. If the try block completes exceptionally, the finally block is evaluated after the matching catch block, if any, and when and if the finally block finishs normally, the exception is rethrown.
The parameter of a catch block has the block as scope. It shadows other variables of the same name.
Example: The example() method below executes without any assertion errors
```

class Example {
class ThisExn extends Throwable {}
class ThatExn extends Throwable {}
var didFinally : Boolean = false;
def example(b:Boolean) {
try {
throw b ? new ThatExn() : new ThisExn();
}
catch(ThatExn) {return true;}
catch(ThisExn) {return false;}
finally {
this.didFinally = true;

```
```

        }
    }
    static def doExample() {
    val e = new Example();
    assert e.example(true);
    assert e.didFinally == true;
    }
    }

```

Limitation: Constraints on exception types in catch blocks are not currently supported.

\subsection*{12.18 Assert}

The assert statement assert B; checks that the Boolean expression B evaluates to true. If so, computation proceeds. If not, it throws \(\times 10\). lang. AssertionError.

The extended form assert B:A; is similar, but provides more debugging information. The value of the expression \(A\) is available as part of the AssertionError, e.g., to be printed on the console.

Example: assert is useful for confirming properties that you believe to be true and wish to rely on. In particular, well-chosen asserts make a program robust in the face of code changes and unexpected uses of methods. For example, the following method compute percent differences, but asserts that it is not dividing by zero. If the mean is zero, it throws an exception, including the values of the numbers as potentially useful debugging information.
```

static def percentDiff(x:Double, y:Double) {
val diff = x-y;
val mean = (x+y)/2;
assert mean != 0.0 : [x,y];
return Math.abs(100 * (diff / mean));
}

```

At times it may be considered important not to check assert statements; e.g., if the test is expensive and the code is sufficiently well-tested. The -noassert command line option causes the compiler to ignore all assert statements.

\section*{13 Places}

An X10 place is a repository for data and activities, corresponding loosely to a process or a processor. Places induce a concept of "local". The activities running in a place may access data items located at that place with the efficiency of on-chip access. Accesses to remote places may take orders of magnitude longer. X10's system of places is designed to make this obvious. Programmers are aware of the places of their data, and know when they are incurring communication costs, but the actual operation to do so is easy. It's not hard to use non-local data; it's simply hard to to do so accidentally.
The set of places available to a computation is determined at the time that the program is started, and remains fixed through the run of the program. See the README documentation on how to set command line and configuration options to set the number of places.
Places are first-class values in X10, as instances x10.lang.Place. Place provides a number of useful ways to query places, such as Place.places, which is a Sequence[Place] of the places available to the current run of the program.
Objects and structs (with one exception) are created in a single place - the place that the constructor call was running in. They cannot change places. They can be copied to other places, and the special library struct GlobalRef allows values at one place to point to values at another.

\subsection*{13.1 The Structure of Places}

Places are numbered 0 through Place.MAX_PLACES-1; the number is stored in the field pl.id. The Sequence[Place] Place.places() contains the places of the program, in numeric order. The program starts by executing a main method at Place.FIRST_PLACE, which is Place.places() ( \(\theta\) ) ; see \(\$ 14.4\)

Operations on places include pl.next(), which gives the next entry (looping around) in Place.places and its opposite pl.prev(). In multi-place executions, here.next () is a convenient way to express "a place other than here". There are also a number of tests, like pl.isSPE() and pl.isCUDA(), which test for particular kinds of processors.

\section*{13.2 here}

The variable here is always bound to the place at which the current computation is running, in the same way that this is always bound to the instance of the current class (for non-static code), or self is bound to the instance of the type currently being constrained. here may denote different places in the same method body or even the same expression, due to place-shifting operations.
This is not unusual for automatic variables: self denotes two different values (one List, one Int) when one describes a non-null list of non-zero numbers as List[Int \(\{\operatorname{self}!=\mathbb{Q}\}]\{\) sel \(f!=\) null \(\}\). In the following code, here has one value at h 0 , and a different one at h 1 (unless there is only one place).
```

val h0 = here;
at (here.next()) {
val h1 = here;
assert (h0 != h1);
}

```
(Similar examples show that self and this have the same behavior: self can be shadowed by constrained types appearing inside of type constraints, and this by inner classes.)
The following example looks through a list of references to Things. It finds those references to things that are here, and deals with them.
```

public static def deal(things: List[GlobalRef[Thing]]) {
for(gr in things) {
if (gr.home == here) {
val grHere =
gr as GlobalRef[Thing]{gr.home == here};
val thing <: Thing = grHere();
dealWith(thing);

```
```

        }
    }
    }

```

\section*{13.3 at: Place Changing}

An activity may change place synchronously using the at statement or at expression. Like any parallel operation, it is potentially expensive, as it requires, at a minimum, two messages and the copying of all data used in the operation, and must be used with care - but it provides the basis for multicore programming in X10.
\[
\begin{aligned}
& \text { AtStmt }::=\text { at (Exp) Stmt } \\
& \text { AtExp }::=\text { at (Exp ) ClosureBody }
\end{aligned}
\]

The PlaceExp must be an expression of type Place or some subtype.
Example: The following example creates an array a located here, and copies it to another place. a in the second place (here.next()) refers to the copy. The copy is modified and examined. After the at finishes, the original is also examined, and (since only the copy, not the original, was modified) is observed to be unchanged.
```

val a = [1,2,3];
at(here.next()) {
a(1) = 4;
assert }\textrm{a}(0)==1 \&\& a(1)==4 \&\& a(2)==3
}
assert }\textrm{a}(0)==1 \&\& a(1)==2 \&\& a(2)==3

```

\subsection*{13.3.1 Copying Values}

An activity executing at (q)S at a place \(p\) evaluates \(q\) at place \(p\), which should be a Place. It then moves to place \(q\) to execute \(S\). The values variables that \(S\) refers to are copied ( \(\$ 13.3 .2\) ) to \(q\), and bound to the variables of the same name. If the at is inside of an instance method and S uses this, this is copied as well. Note that a field reference this.fld or a method call this.meth() will cause this
to be copied - as will their abbreviated forms \(f l d\) and meth(), despite the lack of a visible this.
Note that the value obtained by evaluating q is not necessarily distinct from p (e.g., q may be here). This does not alter the behavior of at. at (here) S will copy all the values mentioned in \(S\), even though there is no actual change of place, and even though the original values already exist there.

On normal termination of \(S\) control returns to \(p\) and execution is continued with the statement following at (q) S. If S terminates abruptly with exception E, E is serialized into a buffer, the buffer is communicated to \(p\) where it is deserialized into an exception E1 and at (p) S throws E1.
Since at (p) S is a synchronous construct, usual control-flow constructs such as break, continue, return and throw are permitted in S. All concurrency related constructs - async, finish, atomic, when are also permitted.
The at-expression \(a t(p) E\) is similar, except that, in the case of normal termination of \(E\), the value that E produces is serialized into a buffer, transported to the starting place, and deserialized, and the value of the at-expression is the result of deserialization.
Limitation: X10 does not currently allow break, continue, or return to exit from an at.

\subsection*{13.3.2 How at Copies Values}

The values mentioned in \(S\) are copied to place \(p\) by at (p) \(S\) as follows.
First, the original-expressions are evaluated to give a vector of X10 values. Consider the graph of all values reachable from these values (except for transient fields ( \(\$ 13.3 .5\), GlobalRefs ( \(\$ 13.3 .6\); also custom serialization ( \(\$ 13.3 .2\) may alter this behavior)).
Second this graph is serialized into a buffer and transmitted to place q. Third, the vector of X 10 values is re-created at q by deserializing the buffer at q . Fourth, S is executed at q , in an environment in which each variable v declared in F refers to the corresponding deserialized value.
Note that since values accessed across an at boundary are copied, the programmer may wish to adopt the discipline that either variables accessed across an at boundary contain only structs or stateless objects, or the methods invoked on them do not access any mutable state on the objects. Otherwise the programmer has to
ensure that side effects are made to the correct copy of the object. For this the struct x10.lang. GlobalRef[T] is often useful.

\section*{Serialization and deserialization.}

The X10 runtime provides a default mechanism for serializing/deserializing an object graph with a given set of roots. This mechanism may be overridden by the programmer on a per class or struct basis as described in the API documentation for \(\mathrm{x} 10 . i o . C u s t o m S e r i a l i z a t i o n . ~ T h e ~ d e f a u l t ~ m e c h a n i s m ~ p e r f o r m s ~\) a deep copy of the object graph (that is, it copies the object or struct and, recursively, the values contained in its fields), but does not traverse or copy transient fields. transient fields are omitted from the serialized data. On deserialization, transient fields are initialized with their default values (\$4.7). The types of transient fields must therefore have default values.

A struct s of type \(x 10 . l a n g . G l o b a l \operatorname{Ref}[T] 13.3 .6\) is serialized as a unique global reference to its contained object o (of type T). Please see the documentation of x 10. lang. GlobalRef[T] for more details.

\subsection*{13.3.3 at and Activities}
at (p)S does not start a new activity. It should be thought of as transporting the current activity to \(p\), running \(S\) there, and then transporting it back. async is the only construct in the language that starts a new activity. In different contexts, each one of the following makes sense: (1) async at (p) S (spawn an activity locally to execute \(S\) at \(p\); here \(p\) is evaluated by the spawned activity), (2) at (p) async \(S\) (evaluate \(p\) and then at \(p\) spawn an activity to execute \(S\) ), and, (3) async at (p) async \(S\). In most cases, async at (p) S is preferred to at (p) async \(S\), since the former returns instantly, but the latter blocks waiting for the remote activity to be spawned.

Since at (p) S does not start a new activity, \(S\) may contain constructs which only make sense within a single activity. For example,
```

for(x in globalRefsToThings)
if (at(x.home) x().isNice())
return x();

```
returns the first nice thing in a collection. If we had used async at(x.home), this would not be allowed; you can't return from an async.
Limitation: X10 does not currently allow break, continue, or return to exit from an at.

\subsection*{13.3.4 Copying from at}
at (p) \(S\) copies data required in \(S\), and sends it to place \(p\), before executing \(S\) there. The only things that are not copied are values only reachable through GlobalRefs and transient fields, and data omitted by custom serialization.

\section*{Example:}
```

val c = new Cell[Int](9); // (1)
at (here) { // (2)
assert(c() == 9); // (3)
c.set(8); // (4)
assert(c() == 8); // (5)
}
assert(c() == 9); // (6)

```

The at statement copies the Cell and its contents. After (1), c is a Cell containing 9; call that cell \(c_{1} A t\) (2), that cell is copied, resulting in another cell \(c_{2}\) whose contents are also 9, as tested at (3). (Note that the copying behavior of at happens even when the destination place is the same as the starting place- even with at (here).) At (4), the contents of \(c_{2}\) are changed to 8, as confirmed at (5); the contents of \(c_{1}\) are of course untouched. Finally, at (c), outside the scope of the at started at line (2), c refers to its original value \(c_{1}\) rather than the copy \(c_{2}\).
The at statement induces a deep copy. Not only does it copy the values of variables, it copies values that they refer to through zero or more levels of reference. Structures are preserved as well: if two fields \(x . f\) and \(x . g\) refer to the same object \(o_{1}\) in the original, then x.f and x.g will both refer to the same object \(o_{2}\) in the copy.

Example: In the following variation of the preceding example, a's original value \(a_{1}\) is an array with two references to the same Cell [Int] \(c_{1}\). The fact that \(a_{1}(0)\) and \(a_{1}(1)\) are both identical to \(c_{1}\) is demonstrated in (A)-(C), as \(a_{1}(0)\) is modified and \(a_{1}(1)\) is observed to change. In (D)-(F), the copy \(a_{2}\) is tested in the same way, showing that \(a_{2}(0)\) and \(a_{2}(1)\) both refer to the same Cell [Int] \(c_{2}\).

However, the test at \((\mathrm{G})\) shows that \(c_{2}\) is a different cell from \(c_{1}\), because changes to \(c_{2}\) did not propagate to \(c_{1}\).
```

val c = new Cell[Int](5);
val a : Array[Cell[Int]](1) = [c,c as Cell[Int]];
assert(a(0)() == 5 \&\& a(1)() == 5); // (A)
c.set(6); // (B)
assert(a(0)() == 6 \&\& a(1)() == 6); // (C)
at(here) {
assert(a(0)() == 6 \&\& a(1)() == 6); // (D)
c.set(7); // (E)
assert(a(0)() == 7 \&\& a(1)() == 7); // (F)
}
assert(a(0)() == 6 \&\& a(1)() == 6); // (G)

```

\subsection*{13.3.5 Copying and Transient Fields}

Recall that fields of classes and structs marked transient are not copied by at. Instead, they are set to the default values for their types. Types that do not have default values cannot be used in transient fields.
Example: Every Trans object has an a-field equal to 1. However, despite the initializer on the b field, it is not the case that every Trans has \(\mathrm{b}==2\). Since b is transient, when the Trans value this is copied at at (here) \{...\} in example(), its b field is not copied, and the default value for an Int, 0 , is used instead. Note that we could not make a transient field c : Int \{c != 0\}, since the type has no default value, and copying would in fact set it to zero.
```

class Trans {
val a : Int = 1;
transient val b : Int = 2;
//ERROR: transient val c : Int{c != O} = 3;
def example() {
assert(a == 1 \&\& b == 2);
at(here) {
assert(a == 1 \&\& b == 0);
}
}
}

```

\subsection*{13.3.6 Copying and GlobalRef}

A GlobalRef[T] (say g) contains a reference to a value v of type T , in a form which can be transmitted, and a Place g.home indicating where the value lives. When a GlobalRef is serialized an opaque, globally unique handle to \(v\) is created.

Example: The following example does not copy the value huge. However, huge would have been copied if it had been put into a Cell, or simply used directly.
```

val huge = "A potentially big thing";
val href = GlobalRef(huge);
at (here) {
use(href);
}
}

```

Values protected in GlobalRefs can be retrieved by the application operation g()\(. \mathrm{g}()\) is guarded; it can only be called when g . home \(==\) here. If you want to do anything other than pass a global reference around or compare two of them for equality, you need to placeshift back to the home place of the reference, often with at (g.home).

Example: The following program, for reasons best known to the programmer, modifies the command-line argument array.
```

public static def main(argv: Array[String](1)) {
val argref = GlobalRef[Array[String](1)](argv);
at(here.next())
use(argref);
}
static def use(argref : GlobalRef[Array[String](1)]) {
at(argref) {
val argv = argref();
argv(0) = "Hi!";
}
}

```

There is an implicit coercion from GlobalRef[T] to Place, so at (argref)S goes to argref. home.

\subsection*{13.3.7 Warnings about at}

There are two dangers involved with at:
- Careless use of at can result in copying and transmission of very large data structures. In particular, it is very easy to capture this - a field reference will do it - and accidentally copy everything that this refers to, which can be very large. A disciplined use of copy specifiers to make explicit just what gets copied can ameliorate this issue.
- As seen in the examples above, a local variable reference x may refer to different objects in different nested at scopes. The programmer must either ensure that a variable accessed across an at boundary has no mutable state or be prepared to reason about which copy gets modified. A disciplined use of copy specifiers to give different names to variables can ameliorate this concern.

\section*{14 Activities}

An activity is a statement being executed, independently, with its own local variables; it may be thought of as a very light-weight thread. An X10 computation may have many concurrent activities executing at any give time. All X10 code runs as part of an activity; when an X10 program is started, the main method is invoked in an activity, called the root activity.

Activities coordinate their execution by various control and data structures. For example, when \((x==0)\); blocks the current activity until some other activity sets \(x\) to zero. However, activities determine the places at which they may be blocked and resumed, by when and similar constructs. There are no means by which one activity can arbitrarily interrupt, block, or resume another.

An activity may be running, blocked on some condition or terminated. If it is terminated, it is terminated in the same way that its statement is: in particular, if the statement terminates abruptly, the activity terminates abruptly for the same reason. (§14.1).

Activities can be long-running entities with a good deal of local state. In particular they can involve recursive method calls (and therefore have runtime stacks). However, activities can also be short-running light-weight entities, e.g., it is reasonable to have an activity that simply increments a variable.

An activity may asynchronously and in parallel launch activities at other places. Every activity except the initial main activity is spawned by another. Thus, at any instant, the activities in a program form a tree.

X10 uses this tree in crucial ways. First is the distinction between local termination and global termination of a statement. The execution of a statement by an activity is said to terminate locally when the activity has finished all its computation. (For instance the creation of an asynchronous activity terminates locally when the activity has been created.) It is said to terminate globally when it has
terminated locally and all activities that it may have spawned at any place have, recursively, terminated globally. For example, consider:
```

async {s1();}
async {s2();}

```

The primary activity spawns two child activities and then terminates locally, very quickly. The child activities may take arbitrary amounts of time to terminate (and may spawn grandchildren). When s1(), s2(), and all their descendants terminate locally, then the primary activity terminates globally.

The program as a whole terminates when the root activity terminates globally. In particular, X10 does not permit the creation of daemon threads-threads that outlive the lifetime of the root activity. We say that an X10 computation is rooted (§14.4).

Future Extensions. We may permit the initial activity to be a daemon activity to permit reactive computations, such as webservers, that may not terminate.

\subsection*{14.1 The X10 rooted exception model}

The rooted nature of X10 computations permits the definition of a rooted exception model. In multi-threaded programming languages there is a natural parentchild relationship between a thread and a thread that it spawns. Typically the parent thread continues execution in parallel with the child thread. Therefore the parent thread cannot serve to catch any exceptions thrown by the child thread.

The presence of a root activity and the concept of global termination permits X10 to adopt a more powerful exception model. In any state of the computation, say that an activity \(A\) is a root of an activity \(B\) if \(A\) is an ancestor of \(B\) and \(A\) is blocked at a statement (such as the finish statement \(\S 14.3\) ) awaiting the termination of \(B\) (and possibly other activities). For every X10 computation, the root-of relation is guaranteed to be a tree. The root of the tree is the root activity of the entire computation. If \(A\) is the nearest root of \(B\), the path from \(A\) to \(B\) is called the activation path for the activity \({ }^{1}\)

\footnotetext{
\({ }^{1}\) Note that depending on the state of the computation the activation path may traverse activities that are running, blocked or terminated.
}

We may now state the exception model for X10. An uncaught exception propagates up the activation path to its nearest root activity, where it may be handled locally or propagated up the root-of tree when the activity terminates (based on the semantics of the statement being executed by the activity). \({ }^{2}\) There is always a good place to put a try-catch block to catch exceptions thrown by an asynchronous activity.

\section*{14.2 async: Spawning an activity}

Asynchronous activities serve as a single abstraction for supporting a wide range of concurrency constructs such as message passing, threads, DMA, streaming, and data prefetching. (In general, asynchronous operations are better suited for supporting scalability than synchronous operations.)
An activity is created by executing the async statement:
\begin{tabular}{lll} 
AsyncStmt & \(::=\) & async ClockedClause? Stmt \\
& \(\mid\) & clocked async Stmt
\end{tabular}

The basic form of async is async \(S\), which starts a new activity located here executing S. (For the clocked form, see 15.4 )
Multiple activities launched by a single activity at another place are not ordered in any way. They are added to the set of activities at the target place and will be executed based on the local scheduler's decisions. If some particular sequencing of events is needed, when, atomic, finish, clocks, and other X10 constructs can be used. X10 implementations are not required to have fair schedulers, though every implementation should make a best faith effort to ensure that every activity eventually gets a chance to make forward progress.

The statement in the body of an async is subject to the restriction that it must be acceptable as the body of a void method for an anonymous inner class declared at that point in the code. For example, it may reference val variables in lexically enclosing scopes, but not var variables. Similarly, it cannot break or continue surrounding loops.

\footnotetext{
\({ }^{2}\) In X10 v2.2 the finish statement is the only statement that marks its activity as a root activity. Future versions of the language may introduce more such statements.
}

\subsection*{14.3 Finish}

The statement finish S converts global termination to local termination.
\[
\begin{array}{rll}
\text { FinishStmt } & ::= & \text { finish Stmt } \\
& \mid & \text { clocked finish Stmt }
\end{array}
\]

An activity \(A\) executes finish \(S\) by executing S and then waiting for all activities spawned by \(S\) (directly or indirectly, here or at other places) to terminate. An activity may terminate normally, or abruptly, i.e. by throwing an exception. All exceptions thrown by spawned activities are caught and accumulated.
finish S terminates locally when all activities spawned by S terminate globally (either abruptly or normally). If \(S\) terminates normally, then finish \(S\) terminates normally and \(A\) continues execution with the next statement after finish S. If S or one of the activities spawned by it terminate abruptly, then finish \(S\) terminates abruptly and throws a single exception, of type \(x 10\).lang.MultipleExceptions, formed from the collection of exceptions accumulated at finish S.
Thus finish S statement serves as a collection point for uncaught exceptions generated during the execution of \(S\).
Note that repeatedly finishing a statement has little effect after the first finish: finish finish S is indistinguishable from finish S if S terminates normally. If \(S\) throws exceptions, finish \(S\) collects the exceptions and wraps them in a MultipleExceptions, whereas finish finish S does the same, and then puts that MultipleExceptions inside of a second MultipleExceptions.

\subsection*{14.4 Initial activity}

An X10 computation is initiated from the command line on the presentation of a class or struct name \(C\). The container must have a main method:
public static def main(a: Array[String](1)):void
method, or a
public static def main(a: Array[String]):void
method, otherwise an exception is thrown and the computation terminates. The single statement
```

finish async at (Place.FIRST_PLACE) {
C.main(s);
}

```
is executed where \(s\) is a one-dimensional Array of strings created from the command line arguments. This single activity is the root activity for the entire computation. (See 13 for a discussion of places.)

\subsection*{14.5 Ateach statements}

Deprecated: The ateach construct is deprecated.
\begin{tabular}{lll} 
AtEachStmt & \(::=\) & ateach (LoopIndex in Exp) ClockedClause? Stmt \\
& \(\mid\) & ateach (Exp) Stmt
\end{tabular}

In ateach (p in D) S, D must be either of type Dist (see 16.5) or of type DistArray [T] (see \(\$ 16\) ), and \(p\) will be of type Point (see \(\$ 16.1\) ). If \(D\) is an DistArray [T], then ateach (p in D) S is identical to ateach (p in D.dist)S; the iteration is over the array's underlying distribution.
Instead of writing ateach ( \(p\) in \(D\) ) \(S\) the programmer should write for ( \(p\) in D) \(\operatorname{at}(\mathrm{D}(\mathrm{p}))\) async \(S\) to get the same effect. For each point \(p\) in \(D\), at place \(D(p)\), transmitting information as specified by \(F, S\) is executed simultaneously.
However, this often results in excessive communication and parallelism. Instead the programmer may want to write:
```

for (place in D.places()) async at (place) {
for (p in D|here) {
S(p);
}
}

```

If the programmer wishes to execute \(S\) in parallel at each place, \(S(p)\) may be replaced by async \(S(p)\).
break and continue statements may not be applied to ateach.

\section*{14.6 vars and Activities}

X10 restricts the use of local var variables in activities, to make programs more deterministic. Specifically, a local var variable \(x\) defined outside of async \(S\) cannot appear inside async \(S\) unless there is a finish surrounding async \(S\) with the definition of \(x\) outside of \(i t\).
Example: The following code is fine; the definition of result appears outside of the finish block:
```

var result : Int = 0;
finish {
async result = 1;
}
assert result == 1;

```

This code is deterministic: the async will finish before the assert starts, and the assert's test will be true.
However, without the finish, it would be wrong, and would not compile in X10. If it were allowed to compile, the activity might finish or might not finish before the println, and the program would not be deterministic.

\subsection*{14.7 Atomic blocks}

X10's atomic blocks provide a high-level construct for coordinating the mutation of shared data. A programmer may use atomic blocks to guarantee that invariants of shared data-structures are maintained even as they are being accessed simultaneously by multiple activities running in the same place.
An X10 program in which all accesses (both reads and writes) of shared variables appear in atomic or when blocks is guaranteed to use all shared variables atomically. Equivalently, if two accesses to some shared variable v could collide at runtime, and one is in an atomic block, then the other must be in an atomic block as well to guarantee atomicity of the accesses to v . If some accesses to shared variables are not protected by atomic or when, then race conditions or deadlocks may occur.
In particular, atomic sections at the same place are atomic with respect to each other. They may not be atomic with respect to non-atomic code, or with respect to atomic sections at different places.

X10 guarantees that atomic sections at the same place are mutually exclusive. That is, if one activity \(A\) at a given place \(p\) is executing an atomic section, then no other activity \(B\) at \(p\) will also be executing an atomic section. If such a \(B\) attempts to execute an atomic or when command, it will be blocked until \(A\) finishes executing its atomic section.
\begin{tabular}{lll} 
AtomicStmt & \(::=\) atomic Stmt \\
WhenStmt & \(::=\) when (Exp ) Stmt
\end{tabular}

Example: Consider a class Redund [T], which encapsulates a list list and, (redundantly) keeps the size of the list in a second field size. Then r:Redund [T] has the invariant r.list.size() == r.size, which must be true at any point at which no method calls on r are active.
If the add method on Redund (which adds an element to the list) were defined as:
```

def add(x:T) { // Incorrect
this.list.add(x);
this.size = this.size + 1;
}

```

Then two activities simultaneously adding elements to the same r could break the invariant. Suppose that r starts out empty. Let the first activity perform the list.add, and compute this.size+1, which is 1, but not store it back into this.size yet. (At this point, r.list.size()==1 and r.size==0; the invariant expression is false, but, as the first call to r . add() is active, the invariant does not need to be true - it only needs to be true when the call finishes.) Now, let the second activity do its call to add to completion, which finishes with r.size==1. (As before, the invariant expression is false, but a call to r.add() is still active, so the invariant need not be true.) Finally, let the first activity finish, which assigns the 1 computed before back into this.size. At the end, there are two elements in
 is required to be true, but it is not.

In this case, the invariant can be maintained by making the increment atomic. Doing so forbids that sequence of events; the atomic block cannot be stopped partway.
```

def add(x:T) {
atomic {
this.list.add(x);

```
```

        this.size = this.size + 1;
    }
    }

```

\subsection*{14.7.1 Unconditional atomic blocks}

The simplest form of an atomic block is the unconditional atomic block: atomic \(S\). When atomic \(S\) is executing at some place \(p\), no other activity at \(p\) may enter an atomic block. So, other activities may continue, even at the same place, but code protected by atomic blocks is not subject to interference from other code in atomic blocks.
If execution of the statement may throw an exception, it is the programmer's responsibility to wrap the atomic block within a try/finally clause and include undo code in the finally clause. Thus the atomic statement only guarantees atomicity on successful execution, not on a faulty execution.
Atomic blocks are closely related to non-blocking synchronization constructs [6], and can be used to implement non-blocking concurrent algorithms.
Code executed inside of atomic \(S\) and when( \(E\) ) \(S\) is subject to certain restrictions. A violation of these restrictions causes an IllegalOperationException to be thrown at the point of the violation.
- S may not spawn another activity.
- S may not use any blocking statements; when, next, finish. (The use of a nested atomic is permitted.)
- S may not force() a Future.
- S may not use at expressions.

Note an important property of an (unconditional) atomic block:
atomic \{s1; atomic s2\} \(=\) atomic \{s1; s2\}
Atomic blocks do not introduce deadlocks. They may exhibit all the bad behavior of sequential programs, including throwing exceptions and running forever, but they are guaranteed not to deadlock.
Example: The following class method implements a (generic) compare and swap (CAS) operation:
```

var target:Object = null;
public atomic def CAS(old1: Object, y: Object):Boolean {
if (target.equals(old1)) {
target = y;
return true;
}
return false;
}

```

\subsection*{14.7.2 Conditional atomic blocks}

Conditional atomic blocks allow the activity to wait for some condition to be satisfied before executing an atomic block. For example, consider a Redund class holding a list r.list and, redundantly, its length r.size. A pop operation will delay until the Redund is nonempty, and then remove an element and update the length.
```

def pop():T {
var ret : T;
when(size>0) {
ret = list.removeAt(0);
size --;
}
return ret;
}

```

The execution of the test is atomic with the execution of the block. This is important; it means that no other activity can sneak in and make the condition be false after the test was seen to be true, but before the block is executed. In this example, two pops executing on a list with one element would work properly. Without the conditional atomic block - even doing the decrement atomically - one call to pop could pass the size \(>0\) guard; then the other call could run to completion (removing the only element of the list); then, when the first call proceeds, its removeAt will fail.

Note that if would not work here.
```

if(size>0) atomic{size--; return list.removeAt(0);}

```
allows another activity to act between the test and the atomic block. And
```

atomic{ if(size>0) {size--; ret = list.removeAt(0);}}

```
does not wait for size>0 to become true.
Conditional atomic blocks are of the form when(b)S; b is called the guard, and S the body.
An activity executing such a statement suspends until such time as the guard is true in the current state. In that state, the body is executed. The checking of the guards and the execution of the corresponding guarded statement is done atomically.
X10 does not guarantee that a conditional atomic block will execute if its condition holds only intermittently. For, based on the vagaries of the scheduler, the precise instant at which a condition holds may be missed. Therefore the programmer is advised to ensure that conditions being tested by conditional atomic blocks are eventually stable, i.e., they will continue to hold until the block executes (the action in the body of the block may cause the condition to not hold any more).

The statement when (true) S is behaviorally identical to atomic S : it never suspends.

The body \(S\) of when(b) \(S\) is subject to the same restrictions that the body of atomic \(S\) is. The guard is subject to the same restrictions as well. Furthermore, guards should not have side effects.
Note that this implies that guarded statements are required to be flat, that is, they may not contain conditional atomic blocks. (The implementation of nested conditional atomic blocks may require sophisticated operational techniques such as rollbacks.)
Example: The following class shows how to implement a bounded buffer of size 1 in X10 for repeated communication between a sender and a receiver. The call buf. send (ob) waits until the buffer has space, and then puts ob into it. Dually, buf.receive() waits until the buffer has something in it, and then returns that thing.
```

class OneBuffer[T] {
var datum: T;
def this(t:T) { this.datum = t; this.filled = true; }
var filled: Boolean;
public def send(v: T) {
when (!filled) {
this.datum = v;

```
```

            this.filled = true;
        }
    }
    public def receive(): T {
        when (filled) {
            v: T = datum;
            filled = false;
            return v;
        }
    }
    }

```

\section*{When when is Tested}

Suppose that activity \(A\) is blocked waiting on when(e) S , because e is false. If some other activity \(B\) changes the state in an atomic section in a way that makes e become true, then either:
- \(A\) will eventually execute S , or
- Some activity \(C \neq A\) will cause e to become false again.

In particular, if no other activity ever falsifies e, then \(A\) will, eventually, discover that e evaluates to true and run \(S\).
Two caveats are worth noting:
- X10 has no guarantees of fairness or liveness.
- X10 only makes guarantees about state changes in atomic sections alerting whens. State changes outside of atomic sections might not cause \(A\) to reevaluate e.

Example: The method good below will always terminate. In particular, if the when statement is allowed to run first and block on C() , the atomic will alert it that C() has changed.
The method bad has no such guarantee: it might terminate if the compiler and scheduler are in a generous mood, or the when might wait forever to be told that c() is now true. Without an atomic, the when statement might not be notified about the change in c() .
```

static def good() {
val c = new Cell[Boolean](false);
async {
atomic {c() = true;}
}
when( c() );
}
static def bad() {
val c = new Cell[Boolean](false);
async {
c() = true;
}
when( c() );
}

```

\subsection*{14.8 Use of Atomic Blocks}

The semantics of atomicity is chosen as a compromise between programming simplicity and efficient implementation. Unlike some possible definitions of "atomic", atomic blocks do not provide absolute atomicity.
Atomic blocks are atomic with respect to each other.
```

var n : Int = 0;
finish {
async atomic n = n + 1; //(a)
async atomic n = n + 2; //(b)
}

```

This program has only two possible interleavings: either (a) entirely precedes (b) or (b) entirely precedes (a). Both end up with \(n==3\).

However, atomic blocks are not atomic with respect to non-atomic code. It we remove the atomics on (a), we get far messier semantics.
```

var n : Int $=0$;
finish \{
// LEGAL BUT UNWISE
async $\mathrm{n}=\mathrm{n}+1$;

```
```

    async atomic n = n + 2; //(b)
    }

```

If X10 had absolute atomic semantics, this program would be guaranteed to treat the atomic increment as a single statement. This would permit three interleavings: the two possible from the fully atomic program, or a third one with the events: (a)'s read of 0 from \(n\), the entirety of (b), and then (a)'s write of \(0+1\) back to n . This interleaving results in \(\mathrm{n}==1\). So, with absolute atomic semantics, \(\mathrm{n}==1\) or \(\mathrm{n}==3\) are the possible results.
However, X10's semantics are weaker than that. Atomic statements are atomic with respect to each other - but there is no guarantee about how they interact with non-atomic statements at all. They might even break up the atomicity of an atomic block. In particular, the following fourth interleaving is possible: (a)'s read of 0 from \(n\), (b)'s read of 0 from \(n\), (a)'s write of 1 to \(n\), and (b)'s write of 2 to n . Thus, \(\mathrm{n}==2\) is permissible as a result in X10.

X10's semantics permit more efficient implementation than absolute atomicity. Absolute atomicity would, in principle, require all activities at place \(p\) to stop whenever one of them enters an atomic section, which would seriously curtail concurrency. X10 simply requires that, when one activity is in an atomic section, that other activities stop when they are trying to enter an atomic section - which is to say, they can continue computing on their own all they like. The difference can be substantial, both in execution time and possible behaviors.

However, X10's semantics do impose a certain burden on the programmer. A sufficient rule of thumb is that, if any access to a variable is done in an atomic section, then all accesses to it must be in atomic sections.

Atomic sections are a powerful and convenient general solution. Classes in the package x10.util. concurrent may be more efficient and more convenient in particular cases. For example, an AtomicInteger provides an atomic integer cell, with atomic get, set, compare-and-set, and add operations. Each AtomicInteger takes care of its own locking. Accesses to one AtomicInteger \(a\) only block activities which try to access \(a\) - not others, not even if they are using different AtomicIntegers or even atomic blocks.

\section*{15 Clocks}

Many concurrent algorithms proceed in phases: in phase \(k\), several activities work independently, but synchronize together before proceeding on to phase \(k+1\). X10 supports this communication structure (and many variations on it) with a generalization of barriers called clocks. Clocks are designed so that programs which follow a simple syntactic discipline will not have either deadlocks or race conditions.

The following minimalist example of clocked code has two worker activities A and \(B\), and three phases. In the first phase, each worker activity says its name followed by 1 ; in the second phase, by a 2 , and in the third, by a 3 . So, if say prints its argument, A-1 B-1 A-2 B-2 B-3 A-3 would be a legitimate run of the program, but A-1 A-2 B-1 B-2 A-3 B-3 (with A-2 before B-1) would not.
The program creates a clock cl to manage the phases. Each participating activity does the work of its first phase, and then executes Clock.advanceAll(); to signal that it is finished with that work. Clock.advanceAll() ; is blocking, and causes the participant to wait until all participant have finished with the phase as measured by the clock cl to which they are both registered. Then they do the second phase, and another Clock. advanceAll () ; to make sure that neither proceeds to the third phase until both are ready. This example uses finish to wait for both particiants to finish.
```

class ClockEx {
static def say(s:String) =
{ atomic{x10.io.Console.OUT.println(s);} }
public static def main(argv:Rail[String]) {
finish async{
val cl = Clock.make();
async clocked(cl) {// Activity A
say("A-1");

```
```

                Clock.advanceAll();
                say("A-2");
                Clock.advanceAll();
                say("A-3");
                }// Activity A
            async clocked(cl) {// Activity B
            say("B-1");
            Clock.advanceAll();
            say("B-2");
            Clock.advanceAll();
            say("B-3");
        }// Activity B
        }
    }
}

```

This chapter describes the syntax and semantics of clocks and statements in the language that have parameters of type Clock.

The key invariants associated with clocks are as follows. At any stage of the computation, a clock has zero or more registered activities. An activity may perform operations only on those clocks it is registered with (these clocks constitute its clock set). An attempt by an activity to operate on a clock it is not registered with will cause a ClockUseException to be thrown. An activity is registered with zero or more clocks when it is created. During its lifetime the only additional clocks it can possibly be registered with are exactly those that it creates. In particular it is not possible for an activity to register itself with a clock it discovers by reading a data structure.
The primary operations that an activity a may perform on a clock c that it is registered upon are:
- It may spawn and simultaneously register a new activity on c , with the statement async clocked(c)S.
- It may unregister itself from c, with c.drop(). After doing so, it can no longer use most primary operations on c .
- It may resume the clock, with c.resume(), indicating that it has finished
with the current phase associated with c and is ready to move on to the next one.
- It may wait on the clock, with c.advance(). This first does c.resume(), and then blocks the current activity until the start of the next phase, viz., until all other activities registered on that clock have called c.resume().
- It may block on all the clocks it is registered with simultaneously, by the command Clock. advanceAll() ;. This, in effect, calls c.advance() simultaneously on all clocks \(c\) that the current activity is registered with.
- Other miscellaneous operations are available as well; see the Clock API.

\subsection*{15.1 Clock operations}

There are two language constructs for working with clocks. async clocked (cl) S starts a new activity registered on one or more clocks. Clock. advanceAll(); blocks the current activity until all the activities sharing clocks with it are ready to proceed to the next clock phase. Clocks are objects, and have a number of useful methods on them as well.

\subsection*{15.1.1 Creating new clocks}

Clocks are created using a factory method on \(\times 10\). lang. Clock:
```

val c: Clock = Clock.make();

```

The current activity is automatically registered with the newly created clock. It may deregister using the drop method on clocks (see the documentation of x10.lang. Clock). All activities are automatically deregistered from all clocks they are registered with on termination (normal or abrupt).

\subsection*{15.1.2 Registering new activities on clocks}
\begin{tabular}{lll} 
AsyncStmt & \(::=\) & async ClockedClause? Stmt \\
ClockedClause & \(::=\) & clocked async Stmt \\
clocked Arguments
\end{tabular}

The async statement with a clocked clause of either form, say
async clocked (c1, c2, c3) S
starts a new activity, initially registered with clocks c1, c2, and c3, and running S . The activity running this code must be registered on those clocks. Violations of these conditions are punished by the throwing of a ClockUseException.

If an activity \(a\) that has executed c.resume() then starts a new activity \(b\) also registered on c (e.g., via async clocked(c) S), the new activity \(b\) starts out having also resumed c , as if it too had executed c.resume(). That is, \(a\) and \(b\) are in the same phase of the clock.
```

// ACTIVITY a
val c = Clock.make();
c.resume();
async clocked(c) {
// ACTIVITY b
c.advance();
b_phase_two();
// END OF ACTIVITY b
}
c.advance();
a_phase_two();
// END OF ACTIVITY a

```

In the proper execution, \(a\) and \(b\) both perform c.advance() and then their phase2 actions. However, if \(b\) were not initially in the resume state for c , there would be a race condition; \(b\) could perform c.advance() and proceed to b_phase_two before \(a\) performed c.advance().

An activity may check whether or not it is registered on a clock c by the method call c.registered()

Note: X10 does not contain a "register" operation that would allow an activity to discover a clock in a datastructure and register itself (or another process) on it. Therefore, while a clock c may be stored in a data structure by one activity a and read from it by another activity \(b\), \(b\) cannot do much with \(c\) unless it is already registered with it. In particular, it cannot register itself on c, and, lacking that registration, cannot register a sub-activity on it with async clocked(c) S.

\subsection*{15.1.3 Resuming clocks}

X10 permits split phase clocks. An activity may wish to indicate that it has completed whatever work it wishes to perform in the current phase of a clock cit is registered with, without suspending itself altogether. It may do so by executing c.resume();

An activity may invoke resume() only on a clock it is registered with, and has not yet dropped ( \(\$ 15.1 .5\) ). A ClockUseException is thrown if this condition is violated. Nothing happens if the activity has already invoked a resume on this clock in the current phase.

An activity may invoke Clock.resumeAll() to resume all the clocks that it is registered with and has not yet dropped. This resume()s all these clocks in parallel, or, equivalently, sequentially in some arbitrary order.

\subsection*{15.1.4 Advancing clocks}

An activity may execute the following method call to signal that it is done with the current phase.

Clock.advanceAll();
Execution of this call blocks until all the clocks that the activity is registered with (if any) have advanced. (The activity implicitly issues a resume on all clocks it is registered with before suspending.)

Clock.advanceAll(); may be thought of as calling c.advance() in parallel for all clocks that the current activity is registered with. (The parallelism is conceptually important: if activities \(a\) and \(b\) are both registered on clocks c and d , and \(a\) executes c.advance(); d.advance() while \(b\) executes d.advance(); c.advance (), then the two will deadlock. However, if the two clocks are waited on in parallel, as Clock. advanceAll () ; does, \(a\) and \(b\) will not deadlock.)

Equivalently, Clock.advanceAll() ; sequentially calls c.resume() for each registered clock c, in arbitrary order, and then c.advance() for each clock, again in arbitrary order.

An activity blocked on advance() resumes execution once it is marked for progress by all the clocks it is registered with.

\subsection*{15.1.5 Dropping clocks}

An activity may drop a clock by executing c.drop();.
The activity is no longer considered registered with this clock. A ClockUseException is thrown if the activity has already dropped c.

\subsection*{15.2 Deadlock Freedom}

In general, programs using clocks can deadlock, just as programs using loops can fail to terminate. However, programs written with a particular syntactic discipline are guaranteed to be deadlock-free, just as programs which use only bounded loops are guaranteed to terminate. The syntactic discipline is:
- The advance() instance method shall not be called on any clock. (The Clock.advanceAll(); method is allowed for this discipline.)
- Inside of finish\{S\}, all clocked asyncs shall be in the scope an unclocked async.

X10 does not enforce this discipline. Doing so would exclude useful programs, many of which are deadlock-free for reasons more subtle than the straightforward syntactic discipline. Still, this discipline is useful for simple cases.
The first clause of the discipline prevents a deadlock in which an activity is registered on two clocks, advances one of them, and ignores the other. The second clause prevents the following deadlock.
```

val c:Clock = Clock.make();
async clocked(c) { // (A)
finish async clocked(c) { // (B) Violates clause 2
Clock.advanceAll(); // (Bnext)
}
Clock.advanceAll(); // (Anext)
}

```
(A), first of all, waits for the finish containing (B) to finish. (B) will execute its advance at (Bnext), and then wait for all other activities registered on \(C\) to execute their advance () s. However, (A) is registered on c. So, (B) cannot finish until (A) has proceeded to (Anext), and (A) cannot proceed until (B) finishes. Thus, this causes deadlock.

\subsection*{15.3 Program equivalences}

From the discussion above it should be clear that the following equivalences hold:
```

c.resume(); Clock.advanceAll(); = Clock.advanceAll();
c.resume(); d.resume(); = d.resume(); c.resume();(15.2)
c.resume(); c.resume(); = c.resume();

Note that Clock.advanceAll(); Clock.advanceAll(); is not the same as Clock. advanceAll(); The first will wait for clocks to advance twice, and the second once.

### 15.4 Clocked Finish

In the most common case of a single clock coordinating a few behaviors, X10 allows coding with an implicit clock. finish and async statements may be qualified with clocked.

A clocked finish introduces a new clock. It executes its body in the usual way that a finish does- except that, when its body completes, the activity executing the clocked finish drops the clock, while it waits for asynchronous spawned asyncs to terminate.

A clocked async registers its async with the implicit clock of the surrounding clocked finish.

The bodies of the clocked finish and clocked async statements may use the Clock.advanceAll () method call to advance the implicit clock. Since the implicit clock is not available in a variable, it cannot be manipulated directly. (If you want to manipulate the clock directly, use an explicit clock, not a clocked finish.)

Example: The following code starts two activities, each of which perform their first phase, wait for the other to finish phase 1, and then perform their second phase.

```
clocked finish {
    clocked async {
            phase("A", 1);
            Clock.advanceAll();
            phase("A", 2);
        }
        clocked async {
            phase("B", 1);
            Clock.advanceAll();
            phase("B", 2);
    }
}
```

Clocked finishes may be nested. The inner clocked finish operates in a single phase of the outer one.

## 16 Local and Distributed Arrays

Arrays provide indexed access to data at a single Place, via Points-indices of any dimensionality. DistArrays is similar, but spreads the data across multiple Places, via Dists. We refer to arrays either sort as "general arrays".

This chapter provides an overview of local and distributed arrays, (the x10. array classes Array and DistArray), and their supporting classes Point, IntRange, Region, and Dist.

### 16.1 Points

Both kinds of arrays are indexed by Points, which are $n$-dimensional tuples of integers. The rank property of a point gives its dimensionality. Points can be constructed from integers or Array [Int] (1)s by the Point.make factory methods:

```
val origin_1 : Point{rank==1} = Point.make(0);
val origin_2 : Point{rank==2} = Point.make(0,0);
val origin_5 : Point{rank==5} = Point.make([0,0,0,0,0]);
```

There is an implicit conversion from Array [Int] (1) to Point, giving a convenient syntax for constructing points:

```
val p : Point = [1,2,3];
val q : Point{rank==5} = [1,2,3,4,5];
val r : Point(3) = [11,22,33];
```

The coordinates of a point are available by function application, or, if you prefer, by subscripting; $\mathrm{p}(\mathrm{i})$ is the $i$ th coordinate of the point p . Point $(n)$ is a typedefined shorthand for Point $\{\operatorname{rank}==n\}$.

### 16.2 IntRange

An IntRange is a representation of a set of consecutive integers: 1.10 is the numbers 1 through 10. There is nothing special about $x 10 . l a n g$. IntRange, beyond its package. However, it appears frequently in idioms involving arrays and related constructs, especially rectangular arrays.
One notable idiom involving IntRange is the integer iteration idiom. for ( $i$ in 1..10) use(i); calls use on each number $1,2, \ldots, 10$, in turn.

If $m>n$, the IntRange $m . . n$ is empty. It has no elements, and iterating over it will not execute the body of the loop.

### 16.3 Regions

A region is a set of points of the same rank. X10 provides a built-in class, x10.array.Region, to allow the creation of new regions and to perform operations on regions. Each region R has a property R.rank, giving the dimensionality of all the points in it.

## Example:

```
val MAX_HEIGHT=20;
val Null = Region.makeUnit(); //Empty 0-dimensional region
val R1 = 1..100; // IntRange
val R2 = R1 as Region(1);
val R3 = (0..99) * (-1..MAX_HEIGHT);
val R4 = Region.makeUpperTriangular(10);
val R5 = R4 && R3; // intersection of two regions
```

The IntRange value $1 . .100$ can be implicitly or explicitly coerced to a onedimensional Region consisting of the points $\{[\mathrm{m}], \ldots,[\mathrm{n}]\}$. IntRanges are useful in building up regions, especially rectangular regions. In general, we ignore the distinction between an IntRange and a rank-one Region, except for those occasional situations where the compiler requires attending to the distinction.

By a special dispensation, the compiler knows that, if $r$ : Region(m) and $s$ : Region(n), then r*s : Region(m+n). (The X10 type system ordinarily could not specify the sum; the best it could do would be r*s : Region, with the rank
of the region unknown.) This feature allows more convenient use of arrays; in particular, one does not need to keep track of ranks nearly so much.
Various built-in regions are provided through factory methods on Region.

- Region.makeEmpty(n) returns an empty region of rank $n$.
- Region.makeFull(n) returns the region containing all points of rank $n$.
- Region.makeUnit() returns the region of rank 0 containing the unique point of rank 0 . It is useful as the identity for Cartesian product of regions.
- Region.makeHalfspace(normal, k), where normal is a Point and k an Int, returns the unbounded half-space of rank normal.rank, consisting of all points p satisfying the vector inequality $\mathrm{p} \cdot$ normal $\leq \mathrm{k}$.
- Region.makeRectangular(min, max), where min and max are rank-1 length-n integeger arrays, returns a Region(n) equal to: $[\min (\theta)$.. $\max (0), \ldots, \min (n-1) . . \max (n-1)]$.
- Region.make(regions) constructs the Cartesian product of the rectangular Region(1)s in regions.
- Region.makeBanded(size, a, b) constructs the banded Region(2) of size size, with a bands above and b bands below the diagonal.
- Region.makeBanded(size) constructs the banded Region(2) with just the main diagonal.
- Region.makeUpperTriangular( N ) returns a region corresponding to the non-zero indices in an upper-triangular $\mathrm{N} \times \mathrm{N}$ matrix.
- Region.makeLowerTriangular( N ) returns a region corresponding to the non-zero indices in a lower-triangular $\mathrm{N} \times \mathrm{N}$ matrix.
- If $R$ is a region, and $p$ a Point of the same rank, then $R+p$ is $R$ translated forwards by $p$ - the region whose points are $r+p$ for each $r$ in $R$.
- If $R$ is a region, and $p$ a Point of the same rank, then $R-p$ is $R$ translated backwards by p - the region whose points are $\mathrm{r}-\mathrm{p}$ for each r in R .

All the points in a region are ordered canonically by the lexicographic total order. Thus the points of the region $(1 . .2) *(1 . .2)$ are ordered as

$$
(1,1),(1,2),(2,1),(2,2)
$$

Sequential iteration statements such as for ( $\S(12.12)$ iterate over the points in a region in the canonical order.
A region is said to be rectangular if it is of the form ( $\mathrm{T}_{1} * \ldots * \mathrm{~T}_{k}$ ) for some set of intervals $\mathrm{T}_{i}=\mathrm{l}_{i} \ldots \mathrm{~h}_{i}$. In particular an IntRange turned into a Region is rectangular: (1..10) as Region(1). Such a region satisfies the property that if two points $p_{1}$ and $p_{3}$ are in the region, then so is every point $p_{2}$ between them (that is, it is convex). (Banded and triangular regions are not rectangular.) The operation R.boundingBox () gives the smallest rectangular region containing R.

### 16.3.1 Operations on regions

Let $R$ be a region. A sub-region is a subset of $R$.
Let R1 and R2 be two regions whose types establish that they are of the same rank. Let $S$ be another region; its rank is irrelevant.
R1 \&\& R2 is the intersection of R1 and R2, viz., the region containing all points which are in both R1 and R2. For example, $1 . .10 \& \& 2 . .20$ is $2 . .10$.
R1 * S is the Cartesian product of R1 and S, formed by pairing each point in R1 with every point in S. Thus, $(1 . .2) *(3 . .4) *(5 . .6)$ is the region of rank 3 containing the eight points with coordinates $[1,3,5],[1,3,6],[1,4,5],[1,4,6]$, $[2,3,5],[2,3,6],[2,4,5],[2,4,6]$.
For a region R and point p of the same rank, $\mathrm{R}+\mathrm{p}$ and $\mathrm{R}-\mathrm{p}$ represent the translation of the region forward and backward by $p$. That is, $R+p$ is the set of points $p+q$ for all $q$ in $R$, and $R-p$ is the set of $q-p$.
More Region methods are described in the API documentation.

### 16.4 Arrays

Arrays are organized data, arranged so that it can be accessed by subscript. An Array [T] A has a Region A.region, telling which Points are in A. For each point $p$ in A.region, $A(p)$ is the datum of type $T$ associated with $p$. X10 implementations should attempt to store Arrays efficiently, and to make array element accesses quick-e.g., avoiding constructing Points when unnecessary.

This generalizes the concepts of arrays appearing in many other programming languages. A Point may have any number of coordinates, so an Array can have, in effect, any number of integer subscripts.
Example: Indeed, it is possible to write code that works on Arrays regardless of dimension. For example, to add one Array[Int] src into another dest,

```
static def addInto(src: Array[Int], dest:Array[Int])
    {src.region == dest.region}
    = {
        for (p in src.region)
            dest(p) += src(p);
    }
```

Since p is a Point, it can hold as many coordinates as are necessary for the arrays src and dest.
The basic operation on arrays is subscripting: if $A$ is an Array [T] and $p$ a point with the same rank as A.region, then $A(p)$ is the value of type $T$ associated with point p . This is the same operation as function application ( $\S 10.2$ ); arrays implement function types, and can be used as functions.
Array elements can be changed by assignment. If $t: T$,

$$
A(p)=t ;
$$

modifies the value associated with p to be t , and leaves all other values in A unchanged.
An Array [T] named a has:

- a.region: the Region upon which $a$ is defined.
- a.size: the number of elements in a.
- a.rank, the rank of the points usable to subscript a. a.rank is a cached copy of a.region.rank.


### 16.4.1 Array Constructors

To construct an array whose elements all have the same value init, call new Array[T] (R, init). For example, an array of a thousand "oh!"s can be made by: new Array[String](1..1000,).

To construct and initialize an array, call the two-argument constructor. new Array [T] (R, f) constructs an array of elements of type $T$ on region $R$, with $a(p)$ initialized to $f(p)$ for each point $p$ in R. $f$ must be a function taking a point of rank R.rank to a value of type T.
Example: One way to construct the array [11, 22, 33] is with an array constructor new Array[Int](1..3,)=>11*i(0)). To construct a multiplication table, call new Array[Int]((0..9)*(0..9),) $=>\mathrm{p}(0) * \mathrm{p}(1))$.
Other constructors are available; see the API documentation and $\$ 1.26$.

### 16.4.2 Array Operations

The basic operation on Arrays is subscripting. If a: Array [T] and p: Point \{rank $==a . r a n k\}$, then $a(p)$ is the value of type $T$ appearing at position $p$ in $a$. The syntax is identical to function application, and, indeed, arrays may be used as functions. $a(p)$ may be assigned to, as well, by the usual assignment syntax $a(p)=t$. (This uses the application and setting syntactic sugar, as given in 88.7.5.)
Sometimes it is more convenient to subscript by integers. Arrays of rank 1-4 can, in fact, be accessed by integers:

```
val A1 = new Array[Int] (1..10, 0);
A1(4) = A1(4) + 1;
val A4 = new Array[Int]((1..2)*(1..3)*(1..4)*(1..5), 0);
A4(2,3,4,5) = A4(1, 1, 1, 1)+1;
```

Iteration over an Array is defined, and produces the Points of the array's region. If you want to use the values in the array, you have to subscript it. For example, you could take the logarithm of every element of an Array [Double] by:

```
for (p in a) a(p) = Math.log(a(p));
```


### 16.5 Distributions

Distributed arrays are spread across multiple Places. A distribution, a mapping from a region to a set of places, describes where each element of a distributed array is kept. Distributions are embodied by the class $x 10$.array.Dist and its
subclasses. The rank of a distribution is the rank of the underlying region, and thus the rank of every point that the distribution applies to.

## Example:

```
val R <: Region = 1..100;
val D1 <: Dist = Dist.makeBlock(R);
val D2 <: Dist = Dist.makeConstant(R, here);
```

D 1 distributes the region R in blocks, with a set of consecutive points at each place, as evenly as possible. D 2 maps all the points in R to here.

Let $D$ be a distribution. D.region denotes the underlying region. Given a point $p$, the expression $D(p)$ represents the application of $D$ to $p$, that is, the place that $p$ is mapped to by $D$. The evaluation of the expression $D(p)$ throws an ArrayIndexOutofBoundsException if $p$ does not lie in the underlying region.

### 16.5.1 PlaceGroups

A PlaceGroup represents an ordered set of Places. PlaceGroups exist for performance and scaleability: they are more efficient, in certain critical places, than general collections of Place. PlaceGroup implements Sequence[Place], and thus provides familiar operations - pg.size() for the number of places, pg.iterator () to iterate over them, etc.

PlaceGroup is an abstract class. The concrete class SparsePlaceGroup is intended for a small group of places. new SparsePlaceGroup (somePlace) is a good PlaceGroup containing one place. new SparsePlaceGroup(seqPlaces) constructs a sparse place group from a sorted sequence of places.

### 16.5.2 Operations returning distributions

Let R be a region, Q a PlaceGroup, and P a place.

Unique distribution The distribution Dist.makeUnique( $Q$ ) is the unique distribution from the region (1..k) as Region(1) to $Q$ mapping each point i to pi.

Constant distributions. The distribution Dist.makeConstant ( $R, P$ ) maps every point in region $R$ to place $P$. The special case Dist.makeConstant $(R)$ maps every point in $R$ to here.

Block distributions. The distribution Dist.makeBlock(R) distributes the elements of R, in approximately-even blocks, over all the places available to the program. There are other Dist.makeBlock methods capable of controlling the distribution and the set of places used; see the API documentation.

Domain Restriction. If $D$ is a distribution and $R$ is a sub-region of $D . r e g i o n$, then $D \mid R$ represents the restriction of $D$ to $R$-that is, the distribution that takes each point $p$ in $R$ to $D(p)$, but doesn't apply to any points but those in $R$.

Range Restriction. If $D$ is a distribution and $P$ a place expression, the term $D$ | $P$ denotes the sub-distribution of $D$ defined over all the points in the region of $D$ mapped to $P$.
Note that $\mathrm{D} \mid$ here does not necessarily contain adjacent points in D.region. For instance, if D is a cyclic distribution, $\mathrm{D} \mid$ here will typically contain points that differ by the number of places. An implementation may find a way to still represent them in contiguous memory, e.g., using an arithmetic function to map from the region index to an index into the array.

### 16.6 Distributed Arrays

Distributed arrays, instances of DistArray [T], are very much like Arrays, except that they distribute information among multiple Places according to a Dist value passed in as a constructor argument.

Example: The following code creates a distributed array holding a thousand cells, each initialized to 0.0, distributed via a block distribution over all places.

```
val R <: Region = 1..1000;
val D <: Dist = Dist.makeBlock(R);
val da <: DistArray[Float]
    = DistArray.make[Float](D, (Point(1))=>0.0f);
```


### 16.7 Distributed Array Construction

DistArrays are instantiated by invoking one of the make factory methods of the DistArray class. A DistArray creation must take either an Int as an argument or a Dist. In the first case, a distributed array is created over the distribution Dist.makeConstant ( $0 . .(\mathrm{N}-1)$, here) ; in the second over the given distribution.
Example: A distributed array creation operation may also specify an initializer function. The function is applied in parallel at all points in the domain of the distribution. The construction operation terminates locally only when the DistArray has been fully created and initialized (at all places in the range of the distribution).
For instance:

```
val ident = ([i]:Point(1)) => i;
val data : DistArray[Int]
    = DistArray.make[Int](Dist.makeConstant(1..9), ident);
val blk = Dist.makeBlock((1..9)*(1..9));
val data2 : DistArray[Int]
    = DistArray.make[Int](blk, ([i,j]:Point(2)) => i*j);
```

The first declaration stores in data a reference to a mutable distributed array with 9 elements each of which is located in the same place as the array. The element at [i] is initialized to its index $\mathbf{i}$.
The second declaration stores in data 2 a reference to a mutable two-dimensional distributed array, whose coordinates both range from 1 to 9, distributed in blocks over all Places , initialized with i * j at point $[\mathrm{i}, \mathrm{j}]$.

### 16.8 Operations on Arrays and Distributed Arrays

Arrays and distributed arrays share many operations. In the following, let a be an array with base type T, and da be an array with distribution D and base type T .

### 16.8.1 Element operations

The value of a at a point $p$ in its region of definition is obtained by using the indexing operation $a(p)$. The value of da at $p$ is similarly da(p). This operation
may be used on the left hand side of an assignment operation to update the value: $a(p)=t$; and $d a(p)=t$; The operator assignments, $a(i)+=e$ and so on, are also available.
It is a runtime error to access arrays, with $d a(p)$ or $d a(p)=v$, at a place other than da. dist (p), viz. at the place that the element exists.

### 16.8.2 Arrays of Single Values

For a region $R$ and a value $v$ of type $T$, the expression new $\operatorname{Array}[T](R, v)$ produces an array on region $R$ initialized with value v. Similarly, for a distribution $D$ and a value $v$ of type $T$ the expression

```
DistArray.make[T](D, (Point(D.rank))=>v)
```

constructs a distributed array with distribution D and base type T initialized with v at every point.

Note that Arrays are constructed by constructor calls, but DistArrays are constructed by calls to the factory methods DistArray .make. This is because Arrays are fairly simple objects, but DistArrays may be implemented by different classes for different distributions. The use of the factory method gives the library writer the freedom to select appropriate implementations.

### 16.8.3 Restriction of an array

Let $R$ be a sub-region of da.region. Then da | R represents the sub-DistArray of da on the region $R$. That is, da | $R$ has the same values as da when subscripted by a point in region $R \& \&$ da.region, and is undefined elsewhere.
Recall that a rich set of operators are available on distributions ( $\$ 16.5$ ) to obtain sub-distributions (e.g. restricting to a sub-region, to a specific place etc).

### 16.8.4 Operations on Whole Arrays

Pointwise operations The unary map operation applies a function to each element of a distributed or non-distributed array, returning a new distributed array with the same distribution, or a non-distributed array with the same region.
The following produces an array of cubes:

```
val A = new Array[Int](1..10, (p:Point(1))=>p(0) );
assert A(3) == 3 && A(4) == 4 && A(10) == 10;
val cube = (i:Int) => i*i*i;
val B = A.map(cube);
assert B(3) == 27 && B(4) == 64 && B(10) == 1000;
```

A variant operation lets you specify the array B into which the result will be stored,

```
val A = new Array[Int](1..10, (p:Point(1))=>p(0) );
assert A(3) == 3 && A(4) == 4 && A(10) == 10;
val cube = (i:Int) => i*i*i;
val B = new Array[Int](A.region); // B = 0,0,0,0,0,0,0,0,0,0
A.map(B, cube);
assert }B(3) == 27 && B(4) == 64 && B(10) == 1000
```

This is convenient if you have an already-allocated array lying around unused. In particular, it can be used if you don't need A afterwards and want to reuse its space:

```
val A = new Array[Int](1..10, (p:Point(1))=>p(0) );
assert A(3) == 3 && A(4) == 4 && A(10) == 10;
val cube = (i:Int) => i*i*i;
A.map(A, cube);
assert A(3) == 27 && A(4) == 64 && A(10) == 1000;
```

The binary map operation takes a binary function and another array over the same region or distributed array over the same distribution, and applies the function pointwise to corresponding elements of the two arrays, returning a new array or distributed array of the same shape. The following code adds two distributed arrays:

```
static def add(da:DistArray[Int], db: DistArray[Int])
    \{da.dist==db.dist\}
    = da.map(db, (a:Int,b:Int)=>a+b);
```

Reductions Let $f$ be a function of type ( $T, T$ ) $=>T$. Let a be an array over base type $T$. Let unit be a value of type $T$. Then the operation a.reduce ( $f$, unit) returns a value of type T obtained by combining all the elements of a by use of $f$ in some unspecified order (perhaps in parallel). The following code gives
one method which meets the definition of reduce, having a running total $r$, and accumulating each value $a(p)$ into it using $f$ in turn. (This code is simply given as an example; Array has this operation defined already.)

```
def oneWayToReduce[T](a:Array[T], f:(T,T)=>T, unit:T):T {
    var r : T = unit;
    for(p in a.region) r = f(r, a(p));
    return r;
}
```

For example, the following sums an array of integers. $f$ is addition, and unit is zero.

```
val a = [1,2,3,4];
val sum = a.reduce((a:Int,b:Int)=>a+b, 0);
assert(sum == 10); // 10 == 1+2+3+4
```

Other orders of evaluation, degrees of parallelism, and applications of $f(x$, unit) and $f($ unit,$x)$ are also correct. In order to guarantee that the result is precisely determined, the function $f$ should be associative and commutative, and the value unit should satisfy $f$ (unit, $x$ ) $=x==f(x, u n i t)$ for all $x$ :T.
DistArrays have the same operation. This operation involves communication between the places over which the DistArray is distributed. The X10 implementation guarantees that only one value of type T is communicated from a place as part of this reduction process.

Scans Let $f:(T, T)=>T$, unit:T, and a be an Array[T] or DistArray[T]. Then a.scan(f,unit) is the array or distributed array of type $T$ whose $i$ th element in canonical order is the reduction by $f$ with unit unit of the first $i$ elements of a.

This operation involves communication between the places over which the distributed array is distributed. The X10 implementation will endeavour to minimize the communication between places to implement this operation.
Other operations on arrays, distributed arrays, and the related classes may be found in the $\times 10$. array package.

## 17 Annotations

X10 provides an an annotation system system for to allow the compiler to be extended with new static analyses and new transformations.
Annotations are constraint-free interface types that decorate the abstract syntax tree of an X10 program. The X10 type-checker ensures that an annotation is a legal interface type. In X10, interfaces may declare both methods and properties. Therefore, like any interface type, an annotation may instantiate one or more of its interface's properties.

### 17.1 Annotation syntax

The annotation syntax consists of an "@" followed by an interface type.

| Annotations | $::=$ | Annotation |
| :--- | :---: | :--- |
|  | $\mid$ | Annotations Annotation |
| Annotation | $::=$ | @ NamedTypeNoConstraints |

Annotations can be applied to most syntactic constructs in the language including class declarations, constructors, methods, field declarations, local variable declarations and formal parameters, statements, expressions, and types. Multiple occurrences of the same annotation (i.e., multiple annotations with the same interface type) on the same entity are permitted.
Recall that interface types may have dependent parameters.
The following examples illustrate the syntax:

- Declaration annotations:

```
// class annotation
@Value
class Cons { ... }
// method annotation
@PreCondition(0 <= i && i < this.size)
public def get(i: Int): Object { ... }
// constructor annotation
@Where(x != null)
def this(x: T) { ... }
// constructor return type annotation
def this(x: T): C@Initialized { ... }
// variable annotation
@Unique x: A;
```

- Type annotations:

List@Nonempty
Int@Range(1,4)

Array[Array[Double]]@Size(n * n)

- Expression annotations:
m() @RemoteCall
- Statement annotations:

```
@Atomic { ... }
@MinIterations(0)
@MaxIterations(n)
for (var i: Int = 0; i < n; i++) { ... }
// An annotated empty statement ;
@Assert(x < y);
```


### 17.2 Annotation declarations

Annotations are declared as interfaces. They must be subtypes of the interface x10.lang.annotation.Annotation. Annotations on particular static entities must extend the corresponding Annotation subclasses, as follows:

- Expressions-ExpressionAnnotation
- Statements-StatementAnnotation
- Classes-ClassAnnotation
- Fields-FieldAnnotation
- Methods-MethodAnnotation
- Imports—ImportAnnotation
- Packages-PackageAnnotation


## 18 Native Code Integration

At times it becomes necessary to call non-X10 code from X10, perhaps to make use of specialized libraries in other languages or to write more precisely controlled code than X10 generally makes available.

The @Native(lang, code) Phrase annotation from x10.compiler.Native in X10 can be used to tell the X10 compiler to generate code for certain kinds of Phrase, instead of what it would normally compile to, when compiling to the lang back end.

The compiler cannot analyze native code the same way it analyzes X10 code. In particular, @Native fields and methods must be explicitly typed; the compiler will not infer types.

### 18.1 Native static Methods

static methods can be given native implementations. Note that these implementations are syntactically expressions, not statements, in C++ or Java. Also, it is possible (and common) to provide native implementations into both Java and $\mathrm{C}++$ for the same method.

```
import x10.compiler.Native;
class Son {
    @Native("c++", "printf(\"Hi!\")")
    @Native("java", "System.out.println(\"Hi!\")")
    static def printNatively():void = {};
}
```

If only some back-end languages are given, the X10 code will be used for the remaining back ends:

```
import x10.compiler.Native;
class Land {
    @Native("c++", "printf(\"Hi from C++!\")")
    static def example():void = {
        x10.io.Console.OUT.println("Hi from X10!");
    };
}
```

The native modifier on methods indicates that the method must not have an X10 code body, and @Native implementations must be given for all back ends:

```
import x10.compiler.Native;
class Plants {
    @Native("c++", "printf(\"Hi!\")")
    @Native("java", "System.out.println(\"Hi!\")")
    static native def printNatively():void;
}
```

Values may be returned from external code to X10. Scalar types in Java and C++ correspond directly to the analogous types in X10.

```
import x10.compiler.Native;
class Return {
    @Native("c++", "1")
    @Native("java", "1")
    static native def one():Int;
}
```

Types are not inferred for methods marked as @Native.
Parameters may be passed to external code. (\#1) is the first parameter, (\#2) the second, and so forth. ((\#0) is the name of the enclosing class, or the this variable.) Be aware that this is macro substitution rather than normal parameter passing; e.g., if the first actual parameter is i++, and (\#1) appears twice in the external code, i will be incremented twice. For example, a (ridiculous) way to print the sum of two numbers is:

```
import x10.compiler.Native;
class Species {
    @Native("c++","printf(\"Sum=%d\", ((#1)+(#2)) )")
    @Native("java","System.out.println(\"\" + ((#1)+(#2)))")
```

```
    static native def printNatively(x:Int, y:Int):void;
```

\}

Static variables in the class are available in the external code. For Java, the static variables are used with their X10 names. For C++, the names must be mangled, by use of the FMGL macro.

```
import x10.compiler.Native;
class Ability {
    static val A : Int = 1;
    @Native("java", "A+2")
    @Native("c++", "Ability::FMGL(A)+2")
    static native def fromStatic():Int;
}
```


### 18.2 Native Blocks

Any block may be annotated with @Native(lang,stmt), indicating that, in the given back end, it should be implemented as stmt. All variables from the surrounding context are available inside stmt. For example, the method call born. example(10), if compiled to Java, changes the field y of a Born object to 10 . If compiled to $\mathrm{C}++$ (for which there is no @Native), it sets it to 3 .

```
import x10.compiler.Native;
class Born {
    var y : Int = 1;
    public def example(x:Int):Int{
        @Native("java", "y=x;")
        {y = 3;}
        return y;
    }
}
```

Note that the code being replaced is a statement - the block $\{y=3 ;\}$ in this case - so the replacement should also be a statement.

Other X10 constructs may or may not be available in Java and/or C++ code. For example, type variables do not correspond exactly to type variables in either language, and may not be available there. The exact compilation scheme is not fully
specified. You may inspect the generated Java or C++ code and see how to do specific things, but there is no guarantee that fancy external coding will continue to work in later versions of X10.

The full facilities of C++ or Java are available in native code blocks. However, there is no guarantee that advanced features behave sensibly. You must follow the exact conventions that the code generator does, or you will get unpredictable results. Furthermore, the code generator's conventions may change without notice or documentation from version to version. In most cases the code should either be a very simple expression, or a method or function call to external code.

### 18.3 External Java Code

When X10 is compiled to Java, mentioning a Java class name in native code will cause the Java compiler to find it in the sourcepath or classpath, in the usual way. This requires no particular extra work from the programmer.

### 18.4 External C++ Code

$\mathrm{C}++$ code can be linked to X 10 code, either by writing auxiliary $\mathrm{C}++$ files and adding them with suitable annotations, or by linking libraries.

### 18.4.1 Auxiliary C++ Files

Auxiliary $\mathrm{C}++$ code can be written in . h and .cc files, which should be put in the same directory as the the X10 file using them. Connecting with the library uses the @NativeCPPInclude(dot_h_file_name) annotation to include the header file, and the @NativeCPPCompilationUnit(dot_cc_file_name) annotation to include the $\mathrm{C}++$ code proper. For example:

## MyCppCode.h:

void foo();

## MyCppCode.cc:

```
#include <cstdlib>
#include <cstdio>
void foo() {
    printf("Hello World!\n");
}
```

Test.x10:
import x10.compiler.Native;
import x10.compiler.NativeCPPInclude;
import x10.compiler.NativeCPPCompilationUnit;
@NativeCPPInclude("MyCPPCode.h")
@NativeCPPCompilationUnit("MyCPPCode.cc")
public class Test \{
public static def main (args:Array[String] (1)) \{ \{ @Native("c++","foo();") \{\} \}
\}
\}

### 18.4.2 C++ System Libraries

If we want to additionally link to more libraries in /usr/lib for example, it is necessary to adjust the post-compilation directly. The post-compilation is the compilation of the $\mathrm{C}++$ which the $\mathrm{X} 10-$ to- $\mathrm{C}++$ compiler $\mathrm{x} 10 \mathrm{c}++$ produces.
The mechanism used for this is the -post command line parameter to $\mathrm{x} 10 \mathrm{c}++$. The following example shows how to compile blas into the executable via post compiler parameters. The command must be issued on one line.

```
x10c++ Test.x10 -post '# # -I /usr/local/blas #
    -L /usr/local/blas -lblas'
```

- The first \# means to use the default compiler for the architecture (from x10rt properties file).
- The second \# is substituted for the .cc files and CXXFLAGS that would ordinarily be used.
- The third \# is substituted for the libraries and LDFLAGS that would ordinarily used.
- For the second and third, if a \% is used instead of a \# then the the substitution does not occur in that position. The \% is erased. The desired parameter value should appear after the $\%$ on the line. This allows a complete override of the postcompiler behaviour.


## 19 Definite Assignment

X10 requires, reasonably enough, that every variable be set before it is read. Sometimes this is easy, as when a variable is declared and assigned together:

```
var x : Int = 0;
assert x == 0;
```

However, it is convenient to allow programs to make decisions before initializing variables.

```
def example(a:Int, b:Int) {
    val max:Int;
    //ERROR: assert max==max; // can't read 'max'
    if (a > b) max = a;
    else max = b;
    assert max >= a && max >= b;
}
```

This is particularly useful for val variables. vars could be initialized to a default value and then reassigned with the right value. vals must be initialized once and cannot be changed, so they must be initialized with the correct value.

However, one must be careful - and the X10 compiler enforces this care. Without the else clause, the preceding code might not give max a value by the assert.
This leads to the concept of definite assignment [5]. A variable is definitely assigned at a point in code if, no matter how that point in code is reached, the variable has been assigned to. In X10, variables must be definitely assigned before they can be read.

As X10 requires that val variables not be initialized twice, we need the dual concept as well. A variable is definitely unassigned at a point in code if it cannot have
been assigned there. For example, immediately after val x : Int, x is definitely unassigned.

Finally, we need the concept of singly and multiply assigned. A variable is singly assigned in a block if it is assigned precisely once; it is multiply assigned if it could possibly be assigned more than once. vars can multiply assigned as desired. vals must be singly assigned. For example, the code $\mathrm{x}=1$; $\mathrm{x}=2$; is perfectly fine if x is a var, but incorrect (even in a constructor) if x is a val.
At some points in code, a variable might be neither definitely assigned nor definitely unassigned. Such states are not always useful.

```
def example(flag : Boolean) {
    var x : Int;
    if (flag) x = 1;
    // x is neither def. assigned nor unassigned.
    x = 2;
    // x is def. assigned.
```

This shows that we cannot simply define "definitely unassigned" as "not definitely assigned". If $x$ had been a val rather than a var, the previous example would not be allowed.
Unfortunately, a completely accurate definition of "definitely assigned" or "definitely unassigned" is undecidable - impossible for the compiler to determine. So, X10 takes a conservative approximation of these concepts. If X10's definition says that x is definitely assigned (or definitely unassigned), then it will be assigned (or not assigned) in every execution of the program.
However, there are programs which X10's algorithm says are incorrect, but which actually would behave properly if they were executed. In the following example, flag is either true or false, and in either case $x$ will be initialized. However, X10's analysis does not understand this - thought it would understand if the example were coded with an if-else rather than a pair of ifs. So, after the two if statements, $x$ is not definitely assigned, and thus the assert statement, which reads it, is forbidden.

```
def example(flag:Boolean) {
    var x : Int;
    if (flag) x = 1;
    if (!flag) x = 2;
    // ERROR: assert x < 3;
```

\}

### 19.1 Asynchronous Definite Assignment

Local variables and instance fields allow asynchronous assignment. A local variable can be assigned in an async statement, and, when the async is finished, the variable is definitely assigned.

## Example:

```
val a : Int;
finish {
    async {
            a = 1;
    }
    // a is not definitely assigned here
}
// a is definitely assigned after 'finish'
assert a==1;
```

This concept supports a core X10 programming idiom. A val variable may be initialized asynchronously, thereby providing a means for returning a value from an async to be used after the enclosing finish.

### 19.2 Characteristics of Definite Assignment

The properties "definitely assigned", "singly assigned", and "definitely unassigned" are computed by a conservative approximation of X10's evaluation rules.

The precise details are up to the implementation. Many basic cases must be handled accurately; e.g., $\mathrm{x}=1$; definitely and singly assigns x .

However, in more complicated cases, a conforming X10 may mark as invalid some code which, when executed, would actually be correct. For example, the following program fragment will always result in x being definitely and singly assigned:

```
val x : Int;
var b : Boolean = mysterious();
if (b) {
    x = cryptic();
}
if (!b) {
    x = unknown();
}
```

However, most conservative approximations of program execution won't mark x as properly initialized, though it is. For x to be properly initialized, precisely one of the two assignments to x must be executed. If b were true initially, it would still be true after the call to cryptic () - since methods cannot modify their caller's local variables - and so the first but not the second assignment would happen. If $b$ were false initially, it would still be false when ! $b$ is tested, and so the second but not the first assignment would happen. Either way, x is definitely and singly assigned.
However, for a slightly different program, this analysis would be wrong. E.g., if b were a field of this rather than a local variable, cryptic() could change b; if b were true initially, both assignments might happen, which is incorrect for a val.
This sort of reasoning is beyond most conservative approximation algorithms. (Indeed, many do not bother checking that ! b late in the program is the opposite of b earlier.) Algorithms that pay attention to such details and subtleties tend to be fairly expensive, which would lead to very slow compilation for X10 - for the sake of obscure cases.
X10's analysis provides at least the following guarantees. We describe them in terms of a statement S performing some collection of possible numbers of assignments to variables - on a scale of " 0 ", " 1 ", and "many". For example, if (b) $x=1$; else $\{x=1 ; x=2 ; y=2 ;\}$ might assign to $x$ one or many times, and might assign to $y$ zero or one time. Hence, after it, $x$ is definitely assigned and may be multiply assigned, and $y$ is neither definitely assigned nor definitely unassigned.
These descriptions are combined in natural ways. For example, if R says that x will be assigned 0 or 1 times, and $S$ says it will be assigned precisely once, then $R ; S$ will assign it one or many times. If only one or $R$ or $S$ will occur, as from if (b) R; else S;, then $x$ may be assigned 0 or 1 times.
This information is sufficient for the tests X10 makes. If x can is assigned one or many times in $S$, it is definitely assigned. It is an error if $x$ is ever read at a point
where it have been assigned zero times. It is an error if a val may be assigned many times.

We do not guarantee that any particular X10 compiler uses this algorithm; indeed, as of the time of writing, the X10 compiler uses a somewhat more precise one. However, any conformant X10 compiler must provide results which are at least as accurate as this analysis.

Assignment: $\mathrm{x}=\mathrm{e}$
$\mathrm{x}=\mathrm{e}$ assigns to x , in addition to whatever assignments e makes. For example, if this. setX ( $y$ ) sets a field $x$ to $y$ and returns $y$, then $x=\operatorname{this} . \operatorname{set} X(y) \operatorname{def}-$ initely and multiply assigns $x$.
async and finish
By itself, async $S$ provides few guarantees. After async $\{x=1 ;\}$ finishes, we know that there is a separate activity which will, when the scheduler lets it, set x to 1 . We do not know that anything has happened yet.
However, if there is a finish around the async, the situation is clearer. After finish\{ async $\{x=1 ;\}\}, x$ has definitely been assigned.
In general, if an async $S$ appears in the body of a finish in a way that guarantees that it will be executed, then, after the finish, the assignments made by $S$ will have occurred. For example, if $S$ definitely assigns to $x$, and the body of the finish guarantees that async $S$ will be executed, then finish\{... async S...\} definitely assigns $x$.

## if and switch

When $\operatorname{if}(E)$ S else $T$ finishes, it will have performed the assignments of $E$, together with those of either $S$ or $T$ but not both. For example, if (b) $x=1$; else $x=2$; definitely assigns $x$, but if (b) $x=1$; does not.
switch is more complex, but follows the same principles as if. For example, switch(E) \{case 1: A; break; case 2: B; default: C;\} performs the assignments of E, and those of precisely one of A, or B; C, or C. Note that case 2 falls through to the default case, so it performs the same assignments as B ; C .

## Sequencing

When R; S finishes, it will have performed the assignments of $R$ and those of $S$. For example, $\mathrm{x}=1$; $\mathrm{y}=2$; definitely assigns x and y , and $\mathrm{x}=1$; $\mathrm{x}=2$; multiply assigns x .

## Loops

while(E)S performs the assignments of $E$ one or more times, and those of $S$ zero or more times. For example, if while(b()) $\{x=1 ;\}$ might assign to $x$ zero, one, or many times. do $S$ while(E) performs the assignments of $E$ one or more times, and those of $S$ one or more times.
for ( $A ; B ; C$ ) D performs the assignments of $A$ once, those of $B$ one or more times, and those of $C$ and $D$ one or more times. for ( $x$ in $E$ ) $S$ performs the assignments of $E$ once and those of $S$ zero or more times.

Loops are of very little value for providing definite assignments, since X10 does not in general know how many times they will be executed.
continue and break inside of a loop are hard to describe in simple terms. They may be conservatively assumed to cause the loop give no information about the variables assigned inside of it. For example, the analysis may conservatively conclude that do $\mathrm{x}=1$; if (true) break; \} while(true) may assign to x zero, one, or many times, overlooking the more precise fact that it is assigned once.

## Method Calls

A method call E.m(A,B) performs the assignments of E, A, and B once each, and also those of m . This implies that X10 must be aware of the possible assignments performed by each method.
If X10 has complete information about m (as when m is a private or final method), this is straightforward. When such information is fundamentally impossible to acquire, as when m is a non-final method invocation, X10 has no choice but to assume that m might do anything that a method can do. (For this reason, the only methods that can be called from within a constructor on a raw - incompletelyconstructed - object) are the private and final ones.)

- m cannot assign to local fields of the caller; methods have no such power.
- m can assign to var fields of this freely.
- m cannot initialize val fields of this. (But see 88.5 .2 , when one constructor calls another as the first statement of its body, the other constructor can initialize vval fields. This is a constructor call, not a method call.)

Recall that every container must be fully initialized upon exit from its constructor. X10 places certain restrictions on which methods can be called from a constructor; see 8.10 .1 . One of these restrictions is that methods called before object initialization is complete must be final or private - and hence, available for static analysis. So, when checking field initialization, X10 will ensure:

1. Each val field is initialized before it is read. A method that does not read a val field $f$ may be called before $f$ is initialized; a method that reads $f$ must not be called until $f$ is initialized. For example, a constructor may have the form:
```
class C {
    val f : Int;
    val g : String;
    def this() {
            f = fless();
            g = useF();
    }
    private def fless() = "f not used here".length();
    private def useF() = "f=" + this.f;
}
```

2. var fields require a deeper analysis. Consider a var field var $\mathrm{x}: \mathrm{T}$ without initializer. If $T$ has a default value, $x$ may be read inside of a constructor before it is otherwise written, and it will have its default value.

If $T$ has no default value, an analysis like that used for vals must be performed to determine that x is initialized before it is used. The situation is more complex than for vals, however, because a method can assign to x as well read from it. The X10 compiler computes a conservative approximation of which methods read and write which var fields. (Doing this carefully requires finding a solution of a set of equations over sets of variables, with each callable method having equations describing what it reads and writes.)
at
at (p)S cannot perform any assignments. this cannot be read or written by an at-statement.
atomic
atomic $S$ performs the assignments of $S$, and when(E)S performs those of $E$ and S.
try
try S catch(x:T1) E1 ... catch(x:Tn) En finally F performs some or all of the assignments of S, plus all the assignments of zero or one of the E's, plus those of F. For example,

```
try {
    x = boomy();
    x = 0;
}
catch(e:Boom) { y = 1; }
finally { z = 1; }
```

assigns x zero, one, or many times assigns y zero or one time, and assigns $z$ exactly once.

## Expression Statements

Expression statements E; and other statements that execute an expression and do something innocuous with it (local variable declaration and assert) have the same effects as E.
return, throw
Statements that do not finish normally, such as return and throw, don't initialize anything (though the computation of the return or thrown value may). They also

[^18]terminate a line of computation. For example, $i f(b)\{x=1$; return; $\} \quad x=2$; definitely and singly assigns x .

## 20 Grammar

In this grammar, $X^{?}$ denotes an optional $X$ element.
(0) AdditiveExp $::=$ MultiplicativeExp
| AdditiveExp + MultiplicativeExp
| AdditiveExp - MultiplicativeExp
(1) AndExp ::= EqualityExp
| AndExp \& EqualityExp
(2) AnnotatedType $::=$ Type Annotations
(3) Annotation $::=$ @ NamedTypeNoConstraints
(4) AnnotationStmt $::=$ Annotations? NonExpStmt
(5) Annotations $::=$ Annotation
| Annotations Annotation
(6) ApplyOpDecln $::=$ MethMods operator this TypeParams? Formals Guard? HasResultType? MethodBody
(7) ArgumentList $::=$ Exp | ArgumentList, Exp
(8) Arguments $::=$ (ArgumentList)
(9) AssertStmt $\begin{aligned}::= & \text { assert Exp ; } \\ & \mid \quad \text { assert Exp }: \operatorname{Exp} \text {; }\end{aligned}$
(10) AssignPropCall ::= property TypeArgs? (ArgumentList?);
(11) Assignment $::=$ LeftHandSide AsstOp AsstExp ExpName (ArgumentList? ) AsstOp AsstExp | Primary (ArgumentList? ) AsstOp AsstExp
(12) AsstExp $::=$ Assignment
| ConditionalExp
(13) AsstOp ::= =

$$
\left\lvert\, \begin{aligned}
& *= \\
& /= \\
& \%= \\
& += \\
& -= \\
& \ll= \\
& \gg= \\
& \ggg= \\
& \&= \\
& n= \\
& 1= \\
& 1= \\
& =
\end{aligned}\right.
$$

(14) AsyncStmt $::=$ async ClockedClause? Stmt | clocked async Stmt
(15) AtCaptureDeclr $::=$ Mods? VarKeyword? VariableDeclr

(16) AtCaptureDeclrs ::= AtCaptureDeclr
| AtCaptureDeclrs, AtCaptureDeclr
(17) AtEachStmt $::=$ ateach (LoopIndex in Exp ) ClockedClause? Stmt | ateach (Exp) Stmt
(18) AtExp ::= at (Exp) ClosureBody
(19) AtStmt ::= at (Exp) Stmt
(20) AtomicStmt $::=$ atomic Stmt
(21) BasicForStmt $::=$ for ( ForInit ? ${ }^{\text {; Exp? }}$; ForUpdate? ) Stmt

(23) BinOpDecln $::=$ MethMods operator TypeParams? (Formal) BinOp (Formal ) Guard? HasResultType? MethodBody
| MethMods operator TypeParams? this BinOp (Formal) Guard? HasResultType? MethodBody
| MethMods operator TypeParams? (Formal) BinOp this Guard? HasResultType? MethodBody
(24) Block $::=$ \{ BlockStmts? $\}$
(25) BlockInteriorStmt $::=$ LocVarDeclnStmt
| ClassDecln
| StructDecln
| TypeDefDecln
| Stmt
(26) BlockStmts ::= BlockInteriorStmt
| BlockStmts BlockInteriorStmt
(27) BooleanLiteral $::=$ true
| false
(28) BreakStmt $::=$ break $I d^{?}$;
(29) CastExp $::=$ Primary
| ExpName
| CastExp as Type
(30) CatchClause $::=$ catch (Formal) Block
(31) Catches ::= CatchClause
| Catches CatchClause
(32) ClassBody $::=$ \{ ClassMemberDeclns? $\}$
(33) ClassDecln $::=$ Mods? class Id TypeParamsI? Properties? Guard? Super? Interfaces? ClassBody
(34) ClassMemberDecln $::=$ InterfaceMemberDecln
| CtorDecln

```
(35) ClassMemberDeclns ::= ClassMemberDecln | ClassMemberDeclns ClassMemberDecln
(36) ClassName ::= TypeName
(37) ClassType \(::=\) NamedType
(38) ClockedClause ::= clocked Arguments
(39) ClosureBody ::= Exp | Annotations? \{ BlockStmts? LastExp \} | Annotations? Block
(40) ClosureExp \(::=\) Formals Guard? HasResultType? \(=>\) ClosureBody
(41) CompilationUnit \(::=\) PackageDecln? TypeDeclns?
| PackageDecln? ImportDeclns TypeDeclns?
| ImportDeclns PackageDecln ImportDeclns? TypeDeclns?
| PackageDecln ImportDeclns PackageDecln ImportDeclns? TypeDeclns?
(42) ConditionalAndExp \(::=\) InclusiveOrExp
| ConditionalAndExp \&\& InclusiveOrExp
(43) ConditionalExp \(::=\) ConditionalOrExp
| ClosureExp
AtExp
ConditionalOrExp ? Exp : ConditionalExp
(44) ConditionalOrExp \(::=\) ConditionalAndExp
| ConditionalOrExp || ConditionalAndExp
(45) ConstantExp ::= Exp
```

ConstrainedType | $:=$ NamedType |
| :---: |
|  |

(47) ConstraintConjunction $::=$ Exp | ConstraintConjunction, Exp
(48) ContinueStmt $::=$ continue $I d^{?}$;
(49) ConversionOpDecln $::=$ ExplConvOpDecln | ImplConvOpDecln
(50) CtorBlock $::=$ \{ ExplicitCtorInvo? BlockStmts? $\}$
(51) CtorBody $::==$ CtorBlock
| CtorBlock
| = ExplicitCtorInvo
| = AssignPropCall
| ;
(52) CtorDecln $::=$ Mods? def this TypeParams? Formals Guard? HasResultType? CtorBody
(53) DepNamedType $::=$ SimpleNamedType DepParams
| ParamizedNamedType DepParams
(54) DoStmt ::= do Stmt while (Exp) ;
(55) EmptyStmt $::=$;
(56) EnhancedForStmt $::=$ for (LoopIndex in Exp ) Stmt | for (Exp) Stmt
(57)

EqualityExp ::= RelationalExp
| EqualityExp == RelationalExp
| EqualityExp != RelationalExp
| Type == Type
| EqualityExp ~ RelationalExp
EqualityExp ! ~ RelationalExp

ExclusiveOrExp $::=$ AndExp
| ExclusiveOrExp ^ AndExp
(59) Exp ::= AsstExp
(60) ExpName ::= Id
| FullyQualifiedName.Id
(61) ExpStmt ::= StmtExp ;
(62) ExplConvOpDecln ::= MethMods operator TypeParams? (Formal) as Type Guard? MethodBody
| MethMods operator TypeParams? (Formal) as ? Guard? HasResultType? MethodBody
(63)

ExplicitCtorInvo $::=$ this TypeArgs? ${ }^{?}$ ArgumentList? ${ }^{?}$ );
| super TypeArgs? (ArgumentList? ) ; Primary . this TypeArgs? (ArgumentList? ) ; | Primary . super TypeArgs? (ArgumentList? ) ;
(64) ExtendsInterfaces ::= extends Type | ExtendsInterfaces, Type
(65)

FieldAccess $::=$ Primary . Id
| super.Id
| ClassName. super . Id
(66) FieldDecln $::=$ Mods? VarKeyword FieldDeclrs ; | Mods? FieldDeclrs ;
(67) FieldDeclr ::= Id HasResultType
| Id HasResultType? = VariableInitializer
(68) FieldDeclrs $::=$ FieldDeclr | FieldDeclrs, FieldDeclr
(69) Finally ::= finally Block
(70) FinishStmt $::=$ finish Stmt
| clocked finish Stmt
(71) ForInit ::= StmtExpList
| LocVarDecln
(72) ForStmt ::= BasicForStmt
| EnhancedForStmt
(73) ForUpdate $::=$ StmtExpList
(74) Formal ::= Mods? FormalDeclr $\left\lvert\, \begin{aligned} & \text { Mods? VarKeyword FormalDeclr } \\ & \text { Type }\end{aligned}\right.$
(75) FormalDeclr $::=$ Id ResultType
| [ IdList ] ResultType
| Id [IdList] ResultType
(76) FormalDeclrs $::=$ FormalDeclr
| FormalDeclrs, FormalDeclr

```
(77) FormalList \(::=\) Formal
    | FormalList , Formal
(78) Formals \(::=\) ( FormalList \(^{?}\) )
(79) FullyQualifiedName ::= Id
        | FullyQualifiedName . Id
(80) FunctionType \(::=\) TypeParams? \({ }^{\text {( FormalList }}\) ? ) Guard? \({ }^{\text {? }}\) => Type
(81) Guard ::= DepParams
(82) HasResultType \(::=\) ResultType
        | <: Type
(83) HasZeroConstraint ::= Type haszero
(84) HomeVariable \(::=\) Id
                        | this
(85) HomeVariableList ::= HomeVariable
                        | HomeVariableList, HomeVariable
(86) Id \(::=\) IDENTIFIER
(87) IdList ::= Id
        | IdList, Id
(88) IfThenElseStmt \(::=\) if (Exp) Stmt else Stmt
(89) IfThenStmt ::= if (Exp ) Stmt
```

(91) ImportDecln $::=$ SingleTypeImportDecln | TypeImportOnDemandDecln
$\begin{array}{rcl}\text { ImportDeclns } & :=\text { ImportDecln } \\ & \mid \quad \text { ImportDeclns ImportDecln }\end{array}$
(93) InclusiveOrExp $::=$ ExclusiveOrExp | InclusiveOrExp | ExclusiveOrExp
(94) InterfaceBody $::=$ \{ InterfaceMemberDeclns? $\}$
(95) InterfaceDecln $::=$ Mods? interface Id TypeParamsI? Properties? Guard? ExtendsInterfaces? InterfaceBody
(96) InterfaceMemberDecln ::= MethodDecln
| PropMethodDecln
| FieldDecln
TypeDecln
(97)

| InterfaceMemberDeclns $::=$ | InterfaceMemberDecln |  |
| ---: | :--- | :--- |
|  | $\|$InterfaceMemberDeclns <br>  <br>  <br> berDecln | InterfaceMem- |

(98) InterfaceTypeList ::= Type | InterfaceTypeList, Type
(99) Interfaces $::=$ implements InterfaceTypeList
(100) LabeledStmt $::=$ Id $:$ LoopStmt
(101) LastExp $::=$ Exp
(102) LeftHandSide $::=$ ExpName | FieldAccess

(104) LocVarDecln $::=$ Mods? VarKeyword VariableDeclrs
| Mods? VarDeclsWType
| Mods? VarKeyword FormalDeclrs
(105) LocVarDeclnStmt $::=$ LocVarDecln ;
(106) LoopIndex $::=$ Mods? LoopIndexDeclr
| Mods? VarKeyword LoopIndexDeclr
(107) LoopIndexDeclr $::=\quad$ Id HasResultType?
| [IdList] HasResultType?
| Id [IdList ] HasResultType?


(114) Mod $::=$| abstract |
| :--- |
|  |\(\left|\begin{array}{l}Annotation <br>

atomic <br>
final <br>
native <br>
private <br>
protected <br>
public <br>
<br>

\end{array}\right|\)| static |
| :--- |
| transient |
| clocked |

(115) MultiplicativeExp ::= RangeExp MultiplicativeExp * RangeExp MultiplicativeExp / RangeExp MultiplicativeExp \% RangeExp MultiplicativeExp ** RangeExp
(116) NamedType $::=$ NamedTypeNoConstraints
| DepNamedType
(117) NamedTypeNoConstraints ::= SimpleNamedType
| ParamizedNamedType

(119) ObCreationExp ::= new TypeName TypeArgs? (ArgumentList? ) ClassBody?
| Primary . new Id TypeArgs? (ArgumentList? ) ClassBody?
| FullyQualifiedName . new Id TypeArgs? ( ArgumentList ${ }^{\text {? }}$ ) ClassBody?
(120) PackageDecln ::= Annotations? package PackageName;
(121) PackageName ::= Id
| PackageName . Id
(122) PackageOrTypeName ::= Id | PackageOrTypeName . Id
(123) ParamizedNamedType $::=$ SimpleNamedType Arguments
| SimpleNamedType TypeArgs
| SimpleNamedType TypeArgs Arguments
(124) PostDecrementExp $::=$ PostfixExp --
(125) PostIncrementExp ::= PostfixExp ++
(126) PostfixExp $::=$ CastExp
| PostIncrementExp
| PostDecrementExp
(127) PreDecrementExp ::= -- UnaryExpNotPlusMinus
(128) PreIncrementExp ::= ++ UnaryExpNotPlusMinus
(129) PrefixOp ::= +

(130) PrefixOpDecln $::=$ MethMods operator TypeParams? PrefixOp (Formal ) Guard? HasResultType? MethodBody
| MethMods operator TypeParams? PrefixOp this Guard? HasResultType? MethodBody

| (131) | Primary $::=$ here $\quad$ [ ArgumentList $\left.{ }^{?}\right]$ |
| :---: | :---: |
| (132) | Prop ::= Annotations? Id ResultType |
| (133) | $\begin{aligned} & \text { PropList }::= \\ & \mid \\ & \text { Prop } \\ & \text { PropList, Prop } \end{aligned}$ |
| (134) | $\begin{aligned} \text { PropMethodDecln }::= & \text { MethMods Id TypeParams? Formals Guard? } \\ & \text { HasResultType? MethodBody } \end{aligned}$ |
| (135) | Properties $::=$ (PropList) |
| (136) | $\begin{aligned} \text { RangeExp } & ::=~ U n a r y E x p \\ & \mid \text { RangeExp . . UnaryExp } \end{aligned}$ |
| (137) | RelationalExp $:=$ ShiftExp <br>  $\|$HasZeroConstraint <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br> SubtypeConstraint <br> RelationalExp $<$ ShiftExp <br> RelationalExp $>$ ShiftExp <br> RelationalExp $<=$ ShiftExp <br> RelationalExp $>=$ ShiftExp <br> RelationalExp instanceof Type  |
| (138) | ResultType ::= : Type |



| (147) | $\begin{aligned} \text { StructDecln }::= & \text { Mods? struct Id TypeParamsI? Properties? } \\ & \text { Interfaces? ClassBody } \end{aligned}$ | Guard? |
| :---: | :---: | :---: |
| (148) | $\begin{array}{rc} \text { SubtypeConstraint } & ::=\text { Type <: Type } \\ & \mid \text { Type }:>\text { Type } \end{array}$ |  |
| (149) | Super $::=$ extends ClassType |  |
| (150) | SwitchBlock ::= \{ SwitchBlockGroups? SwitchLabels? ${ }^{\text {? }}$ |  |
| (151) | SwitchBlockGroup ::= SwitchLabels BlockStmts |  |
| (152) | $\begin{array}{ccl} \text { SwitchBlockGroups } & ::= & \text { SwitchBlockGroup } \\ & \mid \text { SwitchBlockGroups SwitchBlockGroup } \end{array}$ |  |
| (153) | $\begin{aligned} \text { SwitchLabel } & ::= \\ & \text { case ConstantExp : } \\ & \text { default : } \end{aligned}$ |  |
| (154) | $\begin{array}{rcl} \text { SwitchLabels } & ::= & \text { SwitchLabel } \\ & \mid & \text { SwitchLabels SwitchLabel } \end{array}$ |  |
| (155) | SwitchStmt ::= switch (Exp)SwitchBlock |  |
| (156) | ThrowStmt ::= throw Exp ; |  |
| (157) | $\begin{aligned} \text { TryStmt } & ::= \\ & \text { try Block Catches } \\ & \text { try Block Catches? Finally } \end{aligned}$ |  |
| (158) | $\begin{array}{rll} \text { Type } & ::= & \text { FunctionType } \\ & \mid & \text { ConstrainedType } \\ & & \text { Void } \end{array}$ |  |
| (159) | TypeArgs $::=$ [ TypeArgumentList ] |  |


| (160) | $\begin{aligned} \text { TypeArgumentList } & ::=\text { Type } \\ & \mid \text { TypeArgumentList, Type } \end{aligned}$ |
| :---: | :---: |
| (161) | TypeDecln$::=$ ClassDecln <br>  $\left\|\begin{array}{l}\text { StructDecln } \\ \text { InterfaceDecln } \\ \\ \end{array}\right\|$TypeDefDecln <br>  |
| (162) | $\begin{aligned} \text { TypeDeclns } & ::=\text { TypeDecln } \\ & \mid \quad \text { TypeDeclns TypeDecln } \end{aligned}$ |
| (163) | ```TypeDefDecln ::= Mods? type Id TypeParams? Guard? = Type ; \| Mods? type Id TypeParams? ( FormalList ) Guard? = Type ;``` |
| (164) | TypeImportOnDemandDecln ::= import PackageOrTypeName . * |
| (165) | $\begin{array}{rll} \text { TypeName } & ::= & \text { Id } \\ & \mid \text { TypeName . Id } \end{array}$ |
| (166) | TypeParam ::= Id |
| (167) | TypeParamIList $::=$ TypeParam <br>  $\|$TypeParamIList, TypeParam <br> TypeParamIList, |
| (168) | $\begin{array}{rc} \text { TypeParamList } & ::=\text { TypeParam } \\ & \mid \text { TypeParamList, TypeParam } \end{array}$ |
| (169) | TypeParams $::=$ [ TypeParamList ] |
| (170) | TypeParamsI $::=$ [ TypeParamIList ] |

(171)

$$
\begin{array}{lll}
\text { UnannotatedUnaryExp } & ::= & \text { PreIncrementExp } \\
& \left|\begin{array}{l}
\text { PreDecrementExp } \\
\\
\\
\\
\\
\\
\\
\\
\\
\\
\end{array}\right| \begin{array}{l}
\text { - UnaryExpNotPlusMinus } \\
\text { UnaryExpNotPlusMinus }
\end{array} \\
\end{array}
$$

(172) UnaryExp ::= UnannotatedUnaryExp | Annotations UnannotatedUnaryExp
(173) UnaryExpNotPlusMinus $::=$ PostfixExp
| ~ UnaryExp
| ! UnaryExp
^ UnaryExp
| UnaryExp
\& UnaryExp

* UnaryExp
/ UnaryExp
| \% UnaryExp
(174) VarDeclWType $::=$ Id HasResultType $=$ VariableInitializer
| [ IdList ] HasResultType = VariableInitializer
| Id [ IdList ] HasResultType $=$ VariableInitializer
(175) VarDeclsWType $::=$ VarDeclWType
| VarDeclsWType , VarDeclWType
(176) VarKeyword ::= val
| var
(177) VariableDeclr $::=$ Id HasResultType? $=$ VariableInitializer
| [ IdList ] HasResultType? = VariableInitializer
| Id [IdList $]$ HasResultType? $=$ VariableInitializer
(178) VariableDeclrs $::=$ VariableDeclr
| VariableDeclrs, VariableDeclr
(179) VariableInitializer $::=\quad$ Exp
(180) Void ::= void
(181) WhenStmt ::= when (Exp) Stmt
(182) WhileStmt $::=$ while (Exp) Stmt


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## A Deprecations

X10 version 2.2 has a few relics of previous versions, code that is being used by libraries but is not intended for general programming. They should be ignored. These are:

- acc variables.
- The offers clause, as seen in the Offers nonterminal in the grammar (??).
- The grammar allows covariant and contravariant type parameters, marked by + and -:
class Variant[X, +Y, -Z] \{\}
X10 does not support these in any other way.
- The syntax allows for a few Java-isms, such as c.class and super.class, which are not used.


## B Change Log

## B. 1 Changes from X10 v2.1

1. Covariance and contravariance are gone.
2. Operator definitions are regularized. A number of new operator symbols are available.
3. The operator in is gone. in is now only a keyword.
4. Method functions and operator functions are gone.
5. m. . $n$ is now a type of struct called IntRange.
6. for (i in m..n) now works. The old forms, for((i) in m..n) and for ([i] in m..n), are no longer needed.
7. (e as T) now has type T. (It used to have an identity constraint conjoined in.)
8. vars can no longer be assigned in their place of origin. Use a GlobalRef [Cell [T]] instead. We'll have a new idiom for this in 2.3.
9. The -STATIC_CALLS command-line flag is now -STATIC_CHECKS.
10. Any string may be written in backquotes to make an identifier: 'while'.
11. The next and resume keywords are gone; they have been replaced by static methods on Clock.
12. The typed array construction syntax new Array [T] [t1, t2] is gone. Use [t1 as T, t2] (if just plain [t1, t2] doesn't work).

## B. 2 Changes from X10 v2.0.6

This document summarizes the main changes between X10 2.0.6 and X10 2.1. The descriptions are intended to be suggestive rather than definitive; see the language specification for full details.

## B.2.1 Object Model

1. Objects are now local rather than global.
(a) The home property is gone.
(b) at $(P) S$ produces deep copies of all objects reachable from lexically exposed variables in S when it executes S . (Warning: They are copied even in at (here)S.)
2. The GlobalRef[T] struct is the only way to produce or manipulate crossplace references.
(a) GlobalRef's have a home property.
(b) Use GlobalRef[Foo] (foo) to make a new global reference.
(c) Use myGlobalRef() to access the object referenced; this requires here == myGlobalRef.home.
3. The ! type modifier is no longer needed or present.
4. global modifiers are now gone:
(a) global methods in interfaces are now the default.
(b) global fields are gone. In some cases object copying will produce the same effect as global fields. In other cases code must be rewritten. It may be desirable to mark nonglobal fields transient in many cases.
(c) global methods are now marked @Global instead. Methods intended to be non-global may be marked @Pinned.

## B.2.2 Constructors

1. proto types are gone.
2. Constructors and the methods they call must satisfy a number of static checks.
(a) Constructors can only invoke private or final methods, or methods annotated @NonEscaping.
(b) Methods invoked by constructors cannot read fields before they are written.
(c) The compiler ensures this with a detailed protocol.
3. It is still impossible for X10 constructors to leak references to this or observe uninitialized fields of an object. Now, however, the mechanisms enforcing this are less obtrusive than in 2.0.6; the burden is largely on the compiler, not the programmer.

## B.2.3 Implicit clocks for each finish

Most clock operations can be accomplished using the new implicit clocks.

1. A finish may be qualified with clocked, which gives it a clock.
2. An async in a clocked finish may be marked clocked. This registers it on the same clock as the enclosing finish.
3. clocked async S and clocked finish S may use next in the body of $S$ to advance the clock.
4. When the body of a clocked finish completes, the clocked finish is dropped form the clock. It will still wait for spawned asyncs to terminate, but such asyncs need to wait for it.

## B.2.4 Asynchronous initialization of val

vals can be initialized asynchronously. As always with vals, they can only be read after it is guaranteed that they have been initialized. For example, both of the prints below are good. However, the commented-out print in the async is bad, since it is possible that it will be executed before the initialization of a.

```
val a:Int;
finish {
    async {
        a = 1;
        print("a=" + a);
    }
    // WRONG: print("a=" + a);
}
print("a=" + a);
```


## B.2.5 Main Method

The signature for the main method is now:

$$
\text { def main(Array[String]) \{..\} }
$$

or, if the arguments are actually used,

$$
\text { def main(argv: Array[String](1)) \{..\} }
$$

## B.2.6 Assorted Changes

1. The syntax for destructuring a point now uses brackets rather than braces: for ( $[\mathrm{i}]$ in $1 . .10$ ), rather than the prior (i).

## B.2.7 Safety of atomic and when blocks

1. Static effect annotations (safe, sequential, nonblocking, pinned) are no longer used. They have been replaced by dynamic checks.
2. Using an inappropriate operation in the scope of an atomic or when construct will throw IllegalOperationException. The following are inappropriate:

- when
- resume() or next on clocks
- async
- Future.make(), or Future.force().
- at


## B.2.8 Removed Topics

The following are gone:

1. foreach is gone.
2. All vars are effectively shared, so shared is gone.
3. The place clause on async is gone. async ( $P$ ) $S$ should be written at $(P)$ async S.
4. Checked exceptions are gone.
5. future is gone.
6. await ... or ... is gone.
7. const is gone.

## B.2.9 Deprecated

The following constructs are still available, but are likely to be replaced in a future version:

1. ValRail.
2. Rail.
3. ateach
4. offers. The offers concept was experimental in 2.1, but was determined inadequate. It has not been removed from the compiler yet, but it will be soon. In the meantime, traces of it are still visible in the grammar. They should not be used and can safely be ignored.

## B. 3 Changes from X10 v2.0

Some of these changes have been made obsolete in X10 2.2.

- Any is now the top of the type hierarchy (every object, struct and function has a type that is a subtype of Any). Any defines home, at, toString, typeName, equals and hashCode. Any also defines the methods of Equals, so Equals is not needed any more.
- Revised discussion of incomplete types.
- The manual has been revised and brought into line with the current implementation.


## B. 4 Changes from X10 v1.7

The language has changed in the following ways. Some of these changes have been made obsolete in X10 2.2.

- Type system changes: There are now three kinds of entities in an X10 computation: objects, structs and functions. Their associated types are class types, struct types and function types.
Class and struct types are called container types in that they specify a collection of fields and methods. Container types have a name and a signature (the collection of members accessible on that type). Collection types support primitive equality == and may support user-defined equality if they implement the x10.lang.Equals interface.
Container types (and interface types) may be further qualified with constraints.

A function type specifies a set of arguments and their type, the result type, and (optionally) a guard. A function application type-checks if the arguments are of the given type and the guard is satisfied, and the return value is of the given type. A function type does not permit $==$ checks. Closure literals create instances of the corresponding function type.

Container types may implement interfaces and zero or more function types.
All types support a basic set of operations that return a string representation, a type name, and specify the home place of the entity.
The type system is not unitary. However, any type may be used to instantiate a generic type.
There is no longer any notion of value classes. value classes must be re-written into structs or (reference) classes.

- Global object model: Objects are instances of classes. Each object is associated with a globally unique identifier. Two objects are considered identical == if their ids are identical. Classes may specify global fields and methods. These can be accessed at any place. (global fields must be immutable.)
- Proto types. For the decidability of dependent type checking it is necessary that the property graph is acyclic. This is ensured by enforcing rules on the leakage of this in constructors. The rules are flexible enough to permit cycles to be created with normal fields, but not with properties.
- Place types. Place types are now implemented. This means that non-global methods can be invoked on a variable, only if the variable's type is either a struct type or a function type, or a class type whose constraint specifies that the object is located in the current place.

There is still no support for statically checking array access bounds, or performing place checks on array accesses.

## C Options

## C.0.1 Compiler Options

The X10 compilers have many useful options.

## C.0. 2 Optimization: -0 or -optimize

This flag causes the compiler to generate optimized code.

## C.0.3 Debugging: -DEBUG=boolean

This flag, if true, causes the compiler to generate debugging information. It is false by default.

## C.0.4 Call Style: -STATIC_CHECKS, -VERBOSE_CHECKS

By default, if a method call could be correct but is not necessarily correct, the X 10 compiler generates a dynamic check to ensure that it is correct before it is performed. For example, the following code:

```
def use(n:Int{self == 0}) {}
def test(x:Int) {
    use(x); // creates a dynamic cast
}
```

compiles with -STATIC_CHECKS, even though it is possible that $\mathrm{x}!=0$ when use ( x ) is called. In this case, the compiler inserts a cast, which has the effect of checking that the call is correct before it happens:

```
def use(n:Int{self == 0}) {}
def test(x:Int) {
    use(x as Int{self == 0});
}
```

The compiler produces a warning that it inserted some dynamic casts. If you then want to see what it did, use -VERBOSE_CHECKS.

You may also turn on static checking, with the -STATIC_CHECKS flag. With static checking, calls that cannot be proved correct statically will be marked as errors.

## C.0.5 Help: -help and -- -help

These options cause the compiler to print a list of all command-line options.

## C.0.6 Source Path: -sourcepath path

This option tells the compiler where to look for X10 source code.

## C.0. 7 (Deprecated) Class Path: -classpath path

This option is accepted for backward compatibility, but ignored.

## C. 0.8 Output Directory: -d directory

This option tells the compiler to produce its output files in the specified directory.

## C.0.9 Runtime-x10rt impl

This option tells which runtime implementation to use. The choices are lapi, pgp, sockets, mpi, and standalone.

## C.0.10 Executable File -o path

This option tells the compiler what path to use for the executable file.

## C. 1 Execution Options: Java

The Java execution command $\times 10$ has a number of options as well.

## C.1.1 Class Path: -classpath path

This option specifies the search path for class files.

## C.1.2 Library Path: -libpath path

This option specifies the search path for native libraries.

## C.1.3 Heap Size: -mx size

Sets the maximum size of the heap.

## C.1.4 Help: -h

Prints a listing of all execution options.

## C. 2 Running X10

An X10 application is launched either by a direct invocation of the generated executable or using a launcher command. The specification of the number of places and the mapping from places to hosts is transport specific and discussed in C. 3 for Managed X10 (Java back end) and C. 4 for Native X10 (C++ back end). For distributed runs, the x10 distribution (libraries) and the compiled application code (binary or bytecode) are expected to be available at the same paths on all the nodes.

Detailed, up-to-date documentation may be found at

## C. 3 Managed X10

Managed X10 applications are launched using the x10 script followed by the qualified name of the main class.

```
x10c HelloWholeWorld.x10
x10 HelloWholeWorld
```

The main purpose of the x 10 script is to set the jvm classpath and the java.library. path system property to ensure the x 10 libraries are on the path.

## C. 4 Native X10

On most platforms and for most transports, X10 applications can be launched by invoking the generated executable.
x10c++ -o HelloWholeWorld HelloWholeWorld.x10
./HelloWholeWorld
On cygwin, X10 applications must be launched using the runx10 script followed by the name of the generated executable.
x10c++ -o HelloWholeWorld HelloWholeWorld.x10
runx10 HelloWholeWorld
The purpose of the runx10 script is to ensure the x 10 libraries are on the path.
Detailed, up-to-date documentation may be found at
http://xj.watson.ibm.com/twiki/bin/view/Main/X10NativeImplementation
The X10 language has been developed as part of the IBM PERCS Project, which is supported in part by the Defense Advanced Research Projects Agency (DARPA) under contract No. NBCH30390004.
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[^0]:    ${ }^{1}$ The class is officially declared abstract to allow for multiple implementations, like sparse and band matrices, but in fact is abstract to avoid having to write the actual definitions of + and $*$.

[^1]:    ${ }^{2}$ In this X10 is similar to more modern languages such as ZPL [4].

[^2]:    ${ }^{1}$ Except that literals like 1 which match both $i$ and $f$ are counted as integers, not Double; Doubles require a decimal point, an exponent, or the d marker.

[^3]:    ${ }^{2}$ Grammar rules are given in $\$ 20$, and referred to by equation number in that section.

[^4]:    ${ }^{1} \mathrm{X} 10$ automatically uses the identifier self for the element of the type being constrained.

[^5]:    ${ }^{2}$ The actual grammar, as given in $\$ 20$ is slightly more intricate for technical reasons. The set of types is the same, however, and this grammar is better for exposition.
    ${ }^{3}$ In practice, most people would use an Array rather than making a new Pair class.

[^6]:    ${ }^{4}$ By contrast, in Java, the equivalent of Bottle alone would be a type, via type erasure of generics.

[^7]:    ${ }^{5}$ We call them Position to avoid confusion with the built-in class Point. Also, Position is a struct rather than a class so that the non-equality test start $!=$ end compares the coordinates. If Position were a class, start $!=$ end would check for different Position objects, which might have the same coordinates.

[^8]:    ${ }^{6}$ Currently inequalities of the form $e<f$ are not supported.

[^9]:    ${ }^{7}$ No experienced programmer should actually think that $==$ is mathematical equality in any case. It is quite common for two objects to appear identical but not be ==. X10's discrepancy between the two concepts is orthogonal to the familiar one.

[^10]:    ${ }^{8}$ Java, for one, suffers a number of inconveniences because some built-in types like int and char aren't subtypes of anything else.

[^11]:    ${ }^{9}$ The situation would be more complex if X10 had covariant and contravariant types.

[^12]:    ${ }^{10}$ In particular, X=Any doesn't work either. An Array[Int] is not an Array[Any] - and it must not be, for you can put a boolean value into an Array [Any], but you cannot put a boolean value into an Array [Int]. However, if the types of the arguments had simply been $X$ rather than Array [X], then type inference would correctly infer X=Any.

[^13]:    ${ }^{11}$ If y were an expression rather than a variable, there would be no good way to express its type in X10's type system. (The compiler has a more elaborate internal representation of types, not all of which are expressible in X10 version 2.2.)

[^14]:    ${ }^{1}$ This code is unnecessarily turgid for the sake of the example. One would generally write public def bump() = ++n;

[^15]:    ${ }^{1}$ In many cases, a val field can be upgraded to a property, which entails no compile-time or runtime cost. Some cannot be, e.g., in cases where cyclic structures of val fields are required.

[^16]:    ${ }^{2}$ This only applies to nullary property methods, not nullary instance methods. Nullary property methods perform limited computations, have no side effects, and always return the same value, since they have to be expressed in the constraint sublanguage. In this sense, a nullary property method does not behave hugely different from a property. Indeed, a compilation scheme which cached the value of the property method would all but erase the distinction. Other methods may have more behavior, e.g., side effects, so we keep the () to make it clear that a method call is potentially large.

[^17]:    ${ }^{3}$ Indeed, even for the standard types, these operators are defined in the library. Not even as basic an operation as integer addition is built into the language. Conversely, if you define a fullfeatured numeric type, it will have most of the privileges that the standard ones enjoy. The missing

[^18]:    ${ }^{1}$ A more precise analysis could discover that x cannot be initialized only once.

